# Embedded System Design Techniques™

# **Bootloader Design for MCUs**

Session 3: Setting up a Test Application

January 27<sup>th</sup>, 2016 Jacob Beningo, CSDP







#### **Session Overview**

- Components
- Project Organization
- Api's and HAL's
- Accessing Flash
- Linker Files
- Command Parsing
- Watchdog Timers







# **Bootloader Development**

What is needed for a test application?

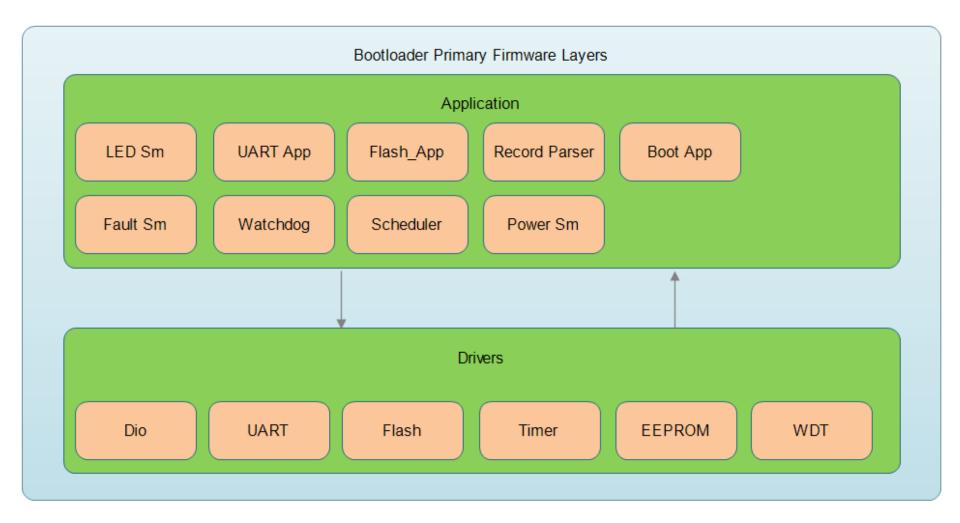








# **Bootloader Components**

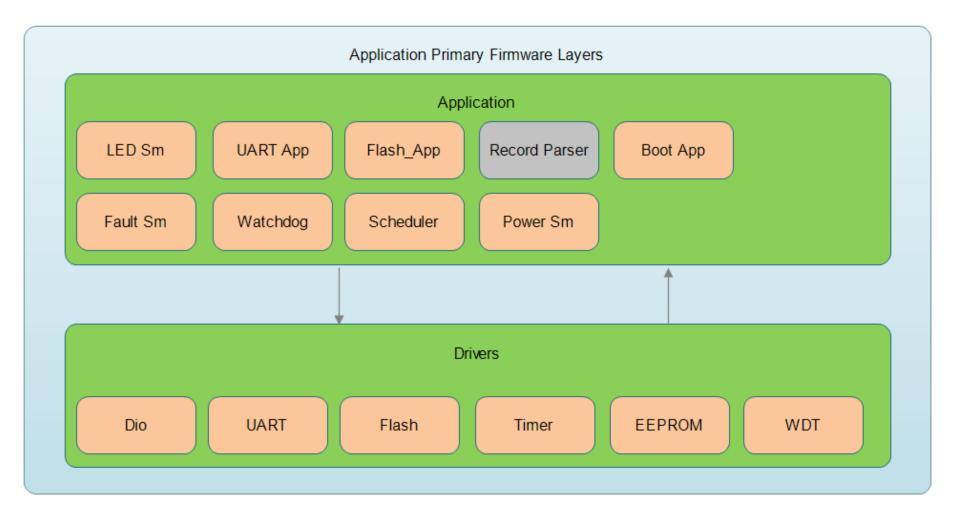








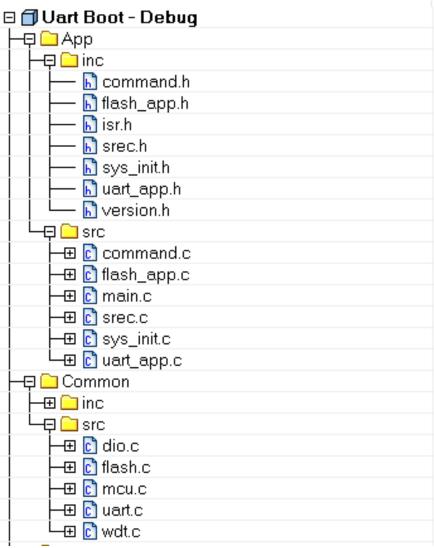
# **Application Components**



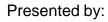




# **Project Organization**









#### API's

- Purpose simplify application programming by abstracting the application into black boxes.
- Critical to creating reusable software
- Defines a common interface that can be used from one project to the next





#### Creating a HAL

- Steps to develop a HAL for the peripheral
  - Review the microcontroller peripheral
  - Identify peripheral features
    - Identify common MCU elements
    - Identify non-standard MCU elements
  - Design and Create the API Interface
  - Create stubs and documentation templates
  - Implement for Target processor(s)
  - Test
  - Repeat for next peripheral







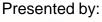
## Example HAL Interface

```
void Dio_Init(const Dio_Config_t *Config);
PinLevelEnum_t Dio_ChannelRead(DioChannel_t Channel);
void Dio_ChannelWrite(DioChannel_t Channel, PinLevelEnum_t State);
void Dio_ChannelToggle(DioChannel_t Channel);
void Dio_ChannelModeSet(DioChannel_t Channel, PinModeEnum_t Mode);
void Dio_FunctionModeSet(DioChannel_t Channel, Dio_FunctionSelect_t Func);
```

```
void Tmr_Init(const Tmr_Config_t *Config);
void Tmr_Enable(Tmr_Register_t Channel);
void Tmr_Disable(Tmr_Register_t Channel);
```

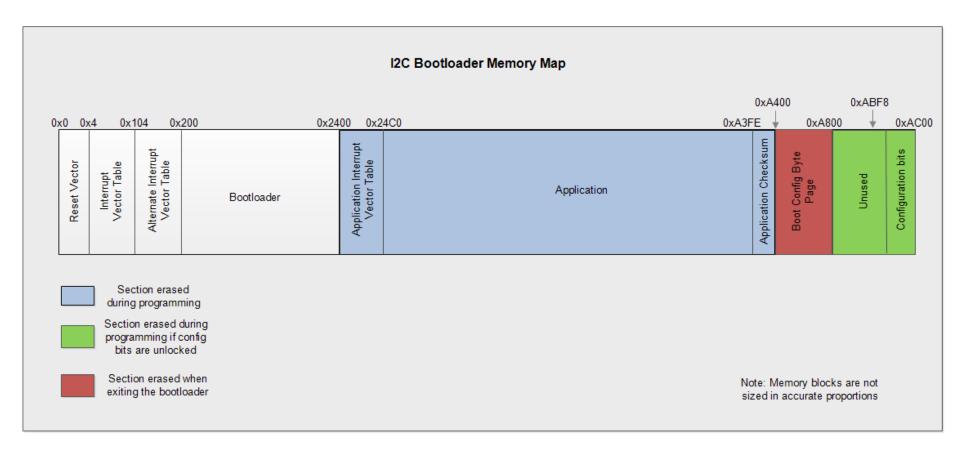
```
void Wdt_Enable(void);
void Wdt_Disable(void);
void Wdt_Reset(void);
void Wdt_Clear(void);
```



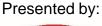




# Setting up the linker

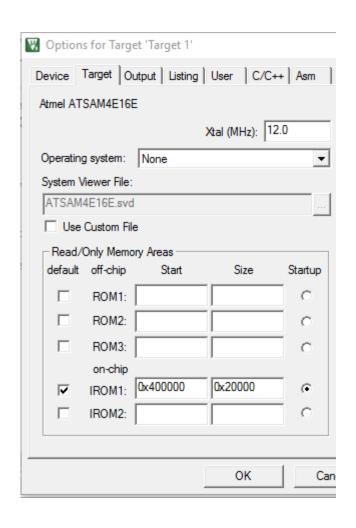








# Setting up the linker



```
MEMORY
      (a!xr) : ORIGIN = 0x800,
                                          LENGTH = 0x1FFF
  data
  reset
               : ORIGIN = 0x0,
                                          LENGTH = 0x4
               : ORIGIN = 0x4,
  ivt
                                          LENGTH = 0xFC
  aivt
               : ORIGIN = 0x104,
                                          LENGTH = 0xFC
 program (xr): ORIGIN = 0x200,
                                          LENGTH = 0x2200
               : ORIGIN = 0x2400,
 app ivt
                                          LENGTH = 0xC0
  checksum
               : ORIGIN = 0 \times A700,
                                     LENGTH = 0x4
  CONFIG4
               : ORIGIN = 0xABF8,
                                          LENGTH = 0x2
               : ORIGIN = 0xABFA,
  CONFIG3
                                         LENGTH = 0x2
               : ORIGIN = 0xABFC,
  CONFIG2
                                          LENGTH = 0x2
               : ORIGIN = 0xABFE,
  CONFIG1
                                          LENGTH = 0x2
 CONFIG4 = 0xABF8;
 CONFIG3 = 0xABFA;
 CONFIG2 = 0xABFC;
 CONFIG1 = 0 \times ABFE;
 NO HANDLES = 1;
                           /* Suppress handles on this device */
 IVT BASE = 0x4;
 AIVT BASE = 0x104;
 DATA BASE = 0x800;
 CODE BASE = 0x200;
 APP IVT BASE = 0x2400;
```







### **Accessing Flash**

- What mode?
  - Bit
  - Page
  - sector

 What should the API look like?

```
void Flash_Init(const Flash_Config_t * Config);
void Flash_Write(uint32_t Address, const uint16_t * Data, uint8_t Size);
void Flash_Read(uint32_t Address, const uint16_t * Data, uint8_t Size);
void Flash_Erase(uint32_t Address);
void Flash_RegisterWrite(uint32_t Address, uint32_t Value);
uint32_t Flash_RegisterRead(uint32_t Address);
void Flash_CallbackRegister(FlashCallback_t Function, TYPE (*CallbackFunction)(type));
```

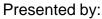




### **Accessing Flash**

```
void Flash Write(void)
   unsigned int i = 0;
   DWORD VAL Address;
   NVMCON = 0x4003;
   while(BufferedDataIndex > 0)
        Address.Val = ProgrammedPointer - BufferedDataIndex;
        TBLPAG = Address.word.HW;
          _builtin_tblwtl(Address.word.LW, ProgrammingBuffer[i]);
          builtin tblwth(Address.word.LW, ProgrammingBuffer[i + 1]);
        i = i + 2;
        asm("DISI #16");
          builtin write NVM();
        while(NVMCONbits.WR == 1){}
        BufferedDataIndex = BufferedDataIndex - 2;
   NVMCONbits.WREN = 0;
```



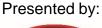




#### **Accessing Flash**

```
Bool SuccessFlag = 0;
/* Verify that the request address space is valid */
if((Address >= BOOTLOADER CONFIG START) &&
   (Address <= BOOTLOADER CONFIG END))
£
    SuccessFlag = Flash Write64KbSectorPage(Address, Data);
    //SuccessFlag = Flash Write8KbSectorPage(Address, Data);
ł
else if((Address >= BOOTLOADER APP START) &&
       (Address <= BOOTLOADER APP END))
4
   SuccessFlag = Flash Write64KbSectorPage(Address, Data);
return SuccessFlag;
```

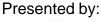




## **Command Parsing**

```
/**
 * Defines the command structure used to parse a command packet
typedef struct
  uint8 t Command;
                                       /**< Stores the command */
  void (*function)(uint8 t * Data); /**< Function pointer to execute on command */</pre>
}Command RxCmdListType;
1 * *
 * Defines an array of all of the supported commands and the function that should
 * be executed when the command is received.
 #/
const Command RxCmdListType CommandsList[] =
  {BOOT EXIT,
                          Command Exit
  {ERASE DEVICE,
                      Command Erase
  {PROGRAM DEVICE,
                       Command Program
  {QUERY DEVICE,
                        Command Query
  {END OF COMMANDS,
                          0 \times 00
3;
```







# **Command Parsing**

```
void Command Process(UartMessageType Message)
    const Command RxCmdListType * CmdListPtr;
    // Loop through the command list and see if there is a match.
    // It will loop until a null pointer is found in the table.
    for(CmdListPtr = CommandsList; CmdListPtr->function != 0; CmdListPtr++)
       // If we find the command we received then exit the loop and execute the command.
      if(CmdListPtr->Command == Message.OpCode)
         break:
    // Do one final check to make sure that a null pointer isn't being executed
    if (CmdListPtr->function != 0)
       // Execute the command and parse out the command byte
       (*CmdListPtr->function) (Message.Data);
```



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16

# Handling the Watchdog

- Must be enabled
  - Why?
- Integrate into the application
- May be windowed
- Set period for the application appropriately









### Resetting the System

- How to reset the system
  - Watchdog timer
    - Infinite loop
    - Illegal write to register
    - Soft reset command
  - Manual software reset
  - Notify user to power cycle



```
void Wdt_Reset(void)
{
   /* Enter an invalid key to force reset */
   SWT.SR.R = 0x0000FFFF;
}
```





#### Additional Resources

- Download Course Material for
  - Updated C Doxygen Templates (Sept 2015)
  - Example source code
  - Bootloader White Paper
  - Templates
- Microcontroller API Standard
- EDN Embedded Basics Articles
- Embedded Bytes Newsletter



#### From <u>www.beningo.com</u> under

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 Design for MCUs











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