



DesignNews

Writing Microcontroller Drivers in Rust

DAY 5: Writing "Hello World"

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THE SPEAKER



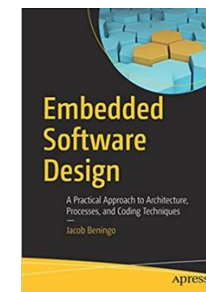
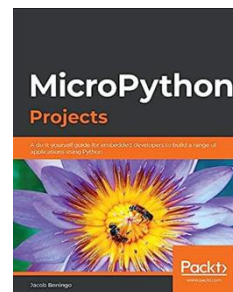
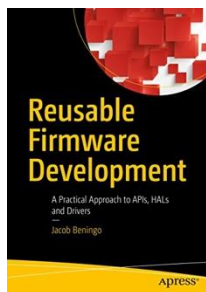
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Beningo Embedded Group – CEO / Founder

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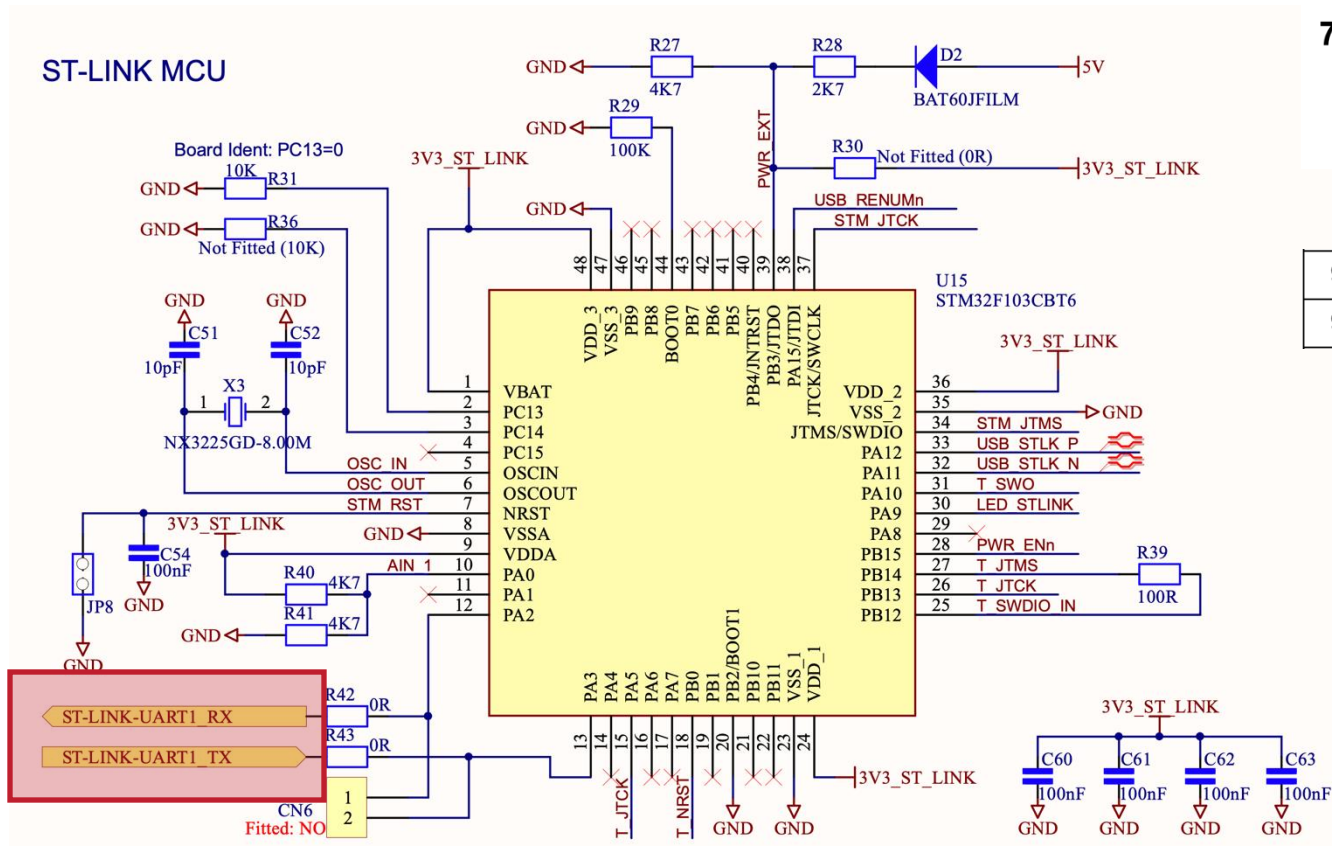
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•• Writing to the Terminal

01

Writing to the terminal

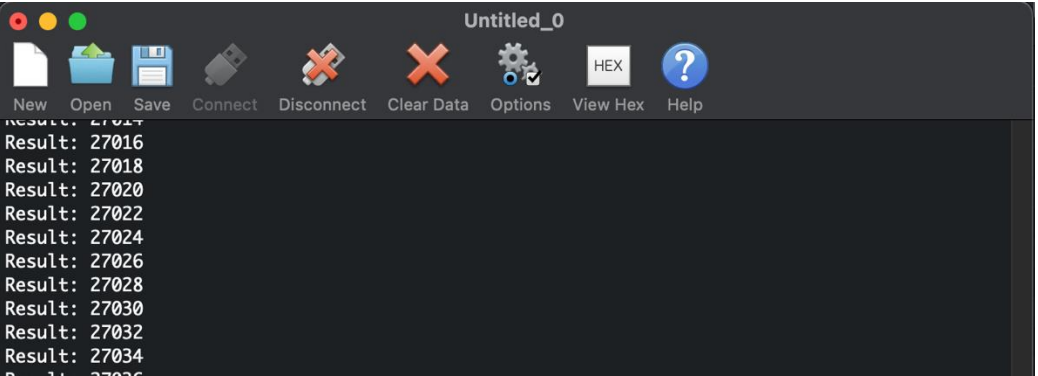
STM32L475 IoT Discovery Board USART1 Terminal



7.10 Virtual COM port

The serial interface USART1 is directly available as a Virtual COM port of the PC connected to the ST-LINK/V2-1 USB connector CN7. The Virtual COM port settings are configured as: 115200 b/s, 8 bits data, no parity, 1 stop bit, no flow control.

92	PB6	USART1_TX	ST-LINK-UART1_TX
93	PB7	USART1_RX	ST-LINK-UART1_RX



Writing to the terminal

Imports and tx definitions

```
use hal::prelude::*;
use hal::serial::{Config, Serial};
use core::fmt::Write;
use super::add;

#[shared]
struct Shared{
    led:
    hal::gpio::gpiob::PB14<hal::gpio::Output<hal
::gpio::PushPull>>,
    delay: hal::delay::Delay,
    tx: hal::serial::Tx<hal::pac::USART1>,
}
```

- Import Serial Config and Serial types
 - Configuration structure
 - Serial structure for USART interface
- Import Format
 - Trait for formatting strings
 - Allows formatting strings to USART1
- A field in Shared structure
 - Shared amongst tasks to access the USART
 - USART1 is a specific instance of serial

Writing to the terminal

Pin and Serial Initializations

```
let tx_pin = gpiob.pb6.into_alternate(&mut gpiob.moder, &mut gpiob.otyper, &mut gpiob.afrl);  
let rx_pin = gpiob.pb7.into_alternate(&mut gpiob.moder, &mut gpiob.otyper, &mut gpiob.afrl);
```

```
let serial = Serial::usart1(  
    dp.USART1,  
    (tx_pin, rx_pin),  
    Config::default().baudrate(115_200.bps()),  
    clocks,  
    &mut rcc.apb2,  
);
```

```
let (tx, _rx) = serial.split();
```

```
(Shared { led, delay, tx }, Local { button }, init::Monotonics())
```

Configure Pins

Configure the USART settings

Split serial structure into tx
and _rx structures

Writing to the terminal

Pin and Serial Initializations

```
loop {  
    a+1;  
    b+1;  
    result = unsafe { add(a, b) };  
  
    // Send result to USART1  
    tx.lock(|tx| {  
        writeln!(tx, "Result: {}", result).ok();  
    });  
  
    led.lock(|led| led.toggle());  
    delay.lock(|delay| delay.delay_ms(ms));  
}
```

Lock and transmit the result!

Audience POLL Question

What is the primary purpose of the `core::fmt::Write` trait in Rust?

- A) To implement custom serialization and deserialization logic.
- B) To provide methods for formatting and writing text to a string-like buffer.
- C) To handle reading and writing files efficiently.
- D) To allow writing binary data to standard output.

•• Review

02

Embedded Programming Languages

Embedded Software Languages

Most Popular Embedded

- C (60 - 70%)
- C++ (20% - 25%)
- Python (<5%)
- Assembly
- Other

Note: 13-14% of Rust Developers are developing bare-metal embedded systems! [Source](#)

Oct 2024	Oct 2023	Change	Programming Language	Ratings	Change
1	1		Python	21.90%	+7.08%
2	3	^	C++	11.60%	+0.93%
3	4	^	Java	10.51%	+1.59%
4	2	v	C	8.38%	-3.70%
5	5		C#	5.62%	-2.09%
6	6		JavaScript	3.54%	+0.64%
7	7		Visual Basic	2.35%	+0.22%
8	11	^	Go	2.02%	+0.65%
9	16	^^	Fortran	1.80%	+0.78%
10	13	^	Delphi/Object Pascal	1.68%	+0.38%
13	20	^^	Rust	1.45%	+0.53%
16	10	v	Assembly language	1.13%	-0.51%

Rust in Embedded Systems

Why choose Rust for Embedded?

Advantages:

- Memory Safety
- Concurrency Safety
- Zero Overhead Abstractions
- Cross-Platform Development
- Modern Tooling
- Growing ecosystem
- Deterministic resource cleanup
- Compile-time error checking
- Interoperability

Disadvantages:

- Steep learning curve
- Smaller talent pool
- Limited library support for some targets
- Longer compile times
- Evolving language and ecosystem
- Verbose error handling
- Limited support for very low-level dev
- Lack of IDE support similar to C/C++
- Cross compilation complexity

The Peripheral Access Crate (PAC)

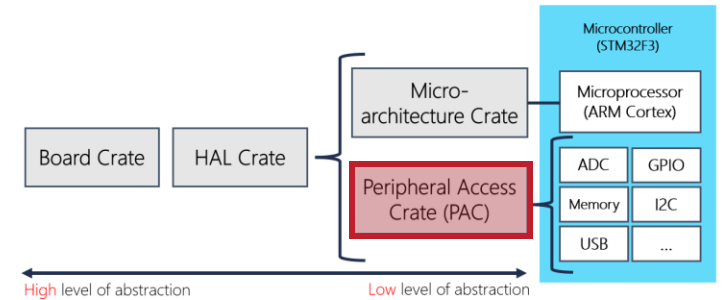
Defined

What is the PAC?

- PAC stands for Peripheral Access Crate.
- Provides direct, low-level access to a microcontroller's peripherals.
- Auto-generated from the microcontroller's SVD (System View Description) files, ensuring accuracy and completeness.

Key Features

- **Type Safety:** Utilizes Rust's type system to prevent common bugs (e.g., invalid register access).
- **Memory Safety:** Ensures safe access to peripheral registers, mitigating risks of memory corruption.
- **Concurrency Safety:** Facilitates safe sharing of peripherals between tasks in concurrent environments.



```

#![no_std]
#![no_main]

use panic_halt as _; // panic handler

use cortex_m_rt::entry;
use tm4c123x;

#[entry]
pub fn init() -> (Delay, Leds) {
    let cp = cortex_m::Peripherals::take().unwrap();
    let p = tm4c123x::Peripherals::take().unwrap();

    let pwm = p.PWM0;
    pwm.ctl.write(|w| w.globalsync0().clear_bit());
    // Mode = 1 => Count up/down mode
    pwm._2_ctl.write(|w| w.enable().set_bit().mode().set_bit());
    pwm._2_gena.write(|w| w.actcmpau().zero().actcmpad().one());
    // 528 cycles (264 up and down) = 4 loops per video line (2112 cycles)
    pwm._2_load.write(|w| unsafe { w.load().bits(263) });
    pwm._2_cmpa.write(|w| unsafe { w.compa().bits(64) });
    pwm.enable.write(|w| w.pwm4en().set_bit());
}

```


Audience POLL Question

Are you going to start using Rust for embedded development?

- A) Yes, for fun on my own projects
- B) Yes, for prototypes at work
- C) Yes, for customer deliverables at work.
- D) No, not convinced it's the right direction yet.

•• Next Steps

04

Embedded Rust Docker Container

- https://mailchi.mp/beningo/embedded_rust_docker_container
- Rust Toolchain
- Embedded Tools

Beningo Rust Docker Container



Additional Resources

Please consider the resources below:

- [Jacob's Blogs](#)
- [Jacob's CEC courses](#)
- [Embedded Software Academy](#)
- Embedded Bytes Newsletter
 - <http://bit.ly/1BAHYXm>

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