



DesignNews

Introduction to Build Systems and CMake

DAY 4 : Designing your Build System

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01

Review: The Problem

The Problem

There are several problems that teams are facing:

- Managing multiple build configurations
- Slow builds
- Software quality issues
- Inability to use modern techniques like DevOps, Simulation, TDD, etc, effectively
- Productivity issues (time to market, product quality)

The Solution

A carefully designed CMake build system will:

- Simplify build configurations with better dependency management
- Allow for faster, cross-platform builds
- Enable consistency across different development environments
- Unlock modern development processes and tools like DevOps, Simulation, and TDD
- Increase productivity

THE SPEAKER



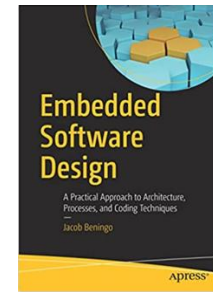
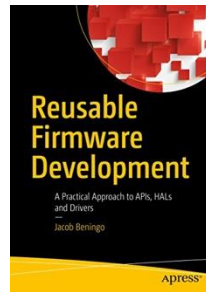
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Beningo Embedded Group – CEO / Founder

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The Plan

Transform Your Build Process: Streamline, Modernize, and Boost Productivity with CMake

Step 1
Learn the Technology

Step 2
Design the Solution

Step 3
Adopt Modern Practices



02

Your Ideal Build System

What your build system should get you . . .

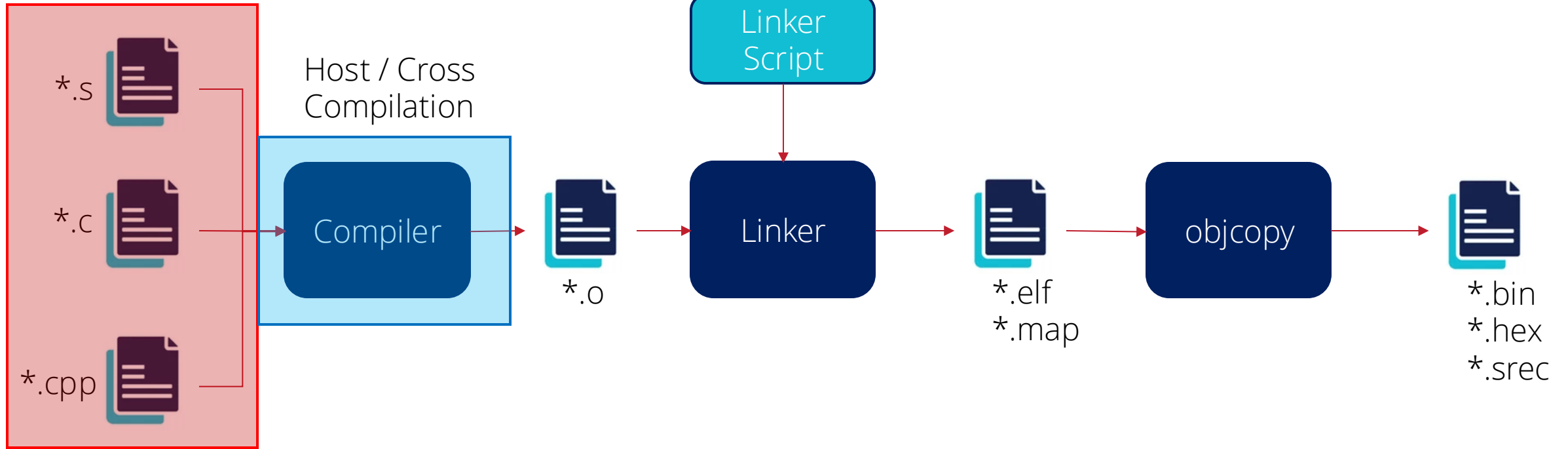
An **ideal build system** for embedded developers should

- streamline the development workflow
- improve productivity
- ensure reliability
- support the unique challenges of embedded systems

It should also be **adaptable** to **various** microcontroller architectures and vendor-specific SDKs.

What your build system does

Various Combinations



Characteristics

- Cross Compilation Support
- Toolchain Management
- Configuration Management
- Build System
- Build Management
- Dependency Management
- Debugging and Debugging Symbols
- Flashing and Deployment
- Build Artifact Management
- Testing and Test Automation
- CI/CD Integration
- Documentation Integration
- Version Control Management
- Reporting
- Extensibility and Customization
- Scalable and Portable
- Flexible

Audience POLL Question

What should your ideal build system do?

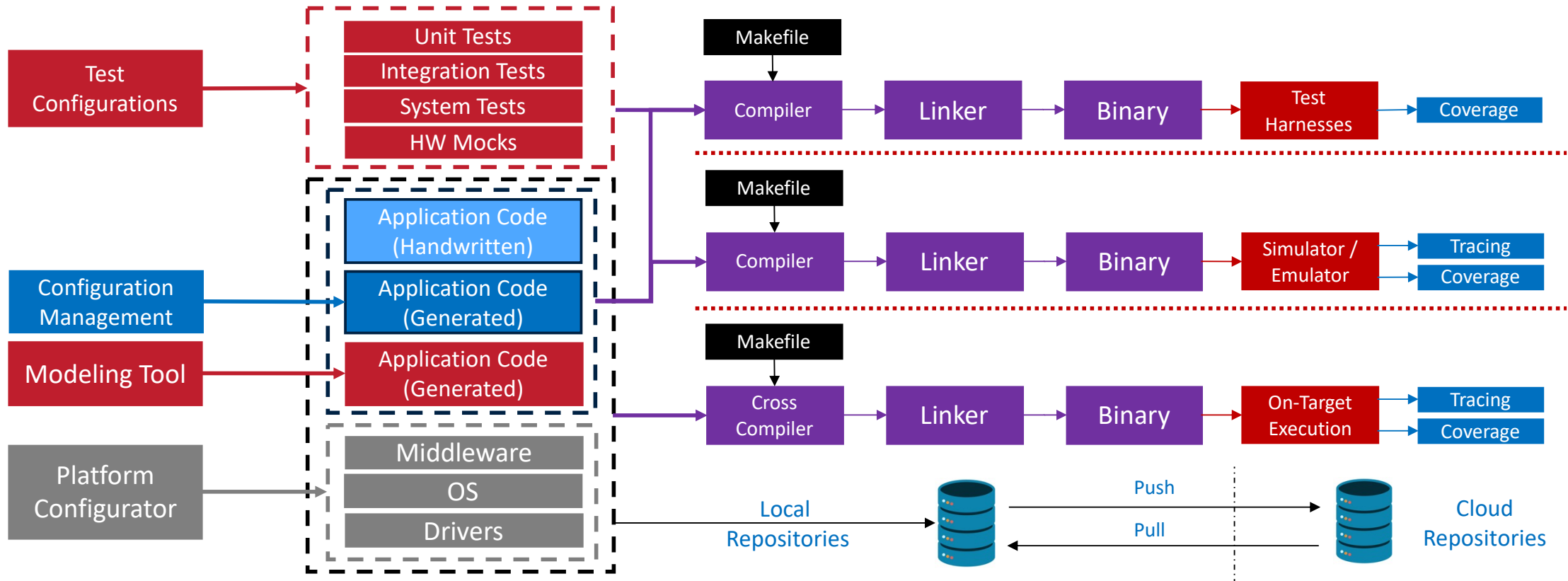
- a) streamline the development workflow
- b) improve productivity
- c) ensure reliability
- d) support the unique challenges of embedded systems
- e) All the above



03

Project Organization

The Build System Diagram



Project Organization

```
1  /YourEmbeddedProjectName
2  |-- /docs          # Project documentation, datasheets, and notes.
3  |   |-- /standards # Coding style and industry standards followed in this project.
4  |       |--cstyle.md # Example coding style document in markdown
5  |   |-- /datasheets # Microcontroller and peripheral datasheets.
6  |   |-- /design_notes # Design decisions, rationale, etc.
7  |       |-- /doxygen # Doxygen generated documentation.
8  |
9  |-- /firmware      # Firmware code directory.
10 |   |-- /app        # Application-specific source and header files.
11 |       |-- main.c
12 |       |-- /tasks  # Application tasks or threads.
13 |       |-- /config # Configuration files (e.g., system_config.h).
14 |       # Other potential application-specific folders could be added here.
15 |
16 |   |-- /boot       # bootloader project. Application-specific source and header files.
17 |       |-- main.c
18 |       |-- /config # Configuration files
19 |       # Other potential bootloader specific folders could be added here.
20 |
21 |   |-- /bsp        # Board Support Package - low-level drivers.
22 |       |-- /cfg    # Config files for the bsp devices
23 |       |-- /devices # Other potential bsp specific folders could be added here.
```

Project Organization

```
25 | |-- /hal          # Hardware Abstraction Layer.
26 | |   |-- /inc     # Header files for HAL.
27 | |   |-- /src    # Source files for HAL.
28 | |   `-- /cfg    # Config files for HAL.
29 |
30 | |-- /drivers     # Device drivers for peripherals (e.g., SPI, UART).
31 | |   |-- /devices # Header and source files for drivers.
32 | |   `-- /cfg     # Config files for drivers.
33 |
34 | |-- /lib         # Libraries and middleware (e.g., FreeRTOS, communication protocols)
35 | |   |-- /stm32   # Example mcu device folder
36 | |   |-- /cmsis   # Example Arm CMSIS support
37 | |   |-- /trace   # Example Percepio trace recorder library
38 | |   |-- /freertos # Example FreeRTOS folder for device target
39 | |   |-- /linux   # Example FreeRTOS folder for linux
40 | |   `-- /win32   # Example FreeRTOS folder for Win32
41 |
42 | |-- /utils      # Utilities, helpers, and service functions.
43 | |-- /test       # Unit tests, mocks, and testing scripts.
44 | `-- /ld         # Linker scripts.
45 |     `-- linker.ld
```

Project Organization

```
47 | -- /hw           # Hardware-related files (like PCB design).
48 |   |-- /schematics # Schematic design files.
49 |   `-- /layouts   # PCB layout files.
50 |
51 | -- /tools       # Build tools, scripts, and utilities.
52 |
53 | -- /build      # Compiled binaries, hex files, etc.
54 |
55 | -- Makefile     # Or CMakeLists.txt, depending on the build system.
56 |
57 | `-- README.md  # Project overview, setup instructions, etc.
58 |
59 |
60 | Notes:
61 |
62 | BSP (Board Support Package): Contains initialization code, hardware abstraction layers, and low-level
63 | drivers specific to the board.
64 | Drivers: Abstract and manage specific peripherals on the microcontroller, such as SPI, I2C, GPIO, etc.
65 | Libraries: Can be third-party or proprietary libraries. For example, you might have a communication
66 | protocol library or a motor control library.
67 | Unit Tests: If you practice Test-Driven Development (TDD) or have unit tests, they should reside in
68 | their directory.
69 | Output: This is where your compiled binaries, hex files, ELF files, and other output from the build
70 | process reside.
71 | Tools: Contains build tools, scripts, and other utilities. For instance, this might include scripts to
72 | program the microcontroller or debug scripts.
```

Audience POLL Question

How important is configuration management to your development?

- a) Not important
- b) Somewhat important
- c) Important
- d) Critically important



04

Custom Build Commands

Custom Docker Commands

```
62 # Custom targets
63 add_custom_target(docker_image
64 |   COMMAND docker build -t beningo/embedded-dev .
65 |   WORKING_DIRECTORY ${CMAKE_SOURCE_DIR}
66 | )
67
68 add_custom_target(docker_run
69 |   COMMAND docker run --rm -it --privileged -v "${CMAKE_SOURCE_DIR}:/home/app" beningo/embedded-dev:latest bash
70 |   WORKING_DIRECTORY ${CMAKE_SOURCE_DIR}
71 | )
```

cmake --build build --target docker_image

cmake --build build --target docker_run

Running clang-format

```
73   add_custom_target(format
74   |     COMMAND clang-format --style=Google -i ${CPP_SOURCES}
75   |     WORKING_DIRECTORY ${CMAKE_SOURCE_DIR}
76   | )
```

```
cmake --build build --target format
```

Running Unit Tests

```
78 add_custom_target(cppcheck
79 |   COMMAND cppcheck --enable=all --inconclusive --std=c++17 ${CPP_SOURCES}
80 |   WORKING_DIRECTORY ${CMAKE_SOURCE_DIR}
81 | )
```

cmake --build build --target cppcheck

Audience POLL Question

What might you use custom commands for?

- a) Unit Testing
- b) Linting
- c) All the above and more
- d) Nothing

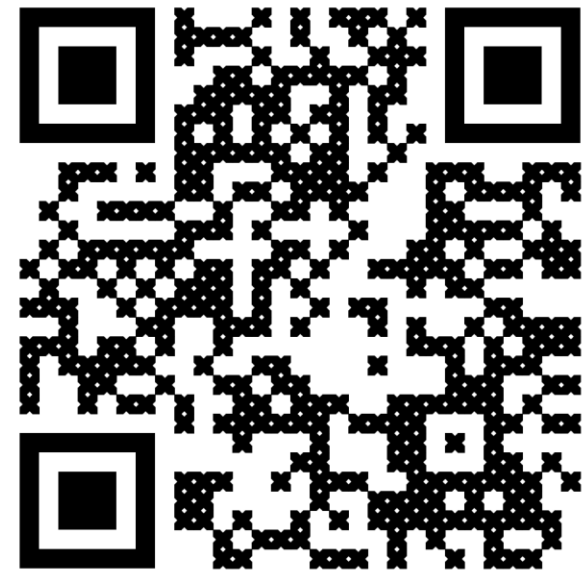
●● Next Steps

05

Embedded Build System

Transform your build system with the free Beningo Embedded Build System example:

- Docker container build system
- Makefile-based
- CMake with Ninja Example
- Compilation scripts
- Integrated tools like cpputest



<https://mailchi.mp/beningo/beningo-devops>

Additional Resources

Please consider the resources below:

- [Jacob's Blogs](#)
- [Jacob's CEC courses](#)
- [Embedded Software Academy](#)
- Embedded Bytes Newsletter
 - <http://bit.ly/1BAHYXm>



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Next Steps

- ✓ Introduction to Embedded Build Systems
- ✓ CMake Fundamentals
- ✓ CMake for Embedded Systems
- ✓ Designing your Build System
- Adopting Modern Practices



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