



PIC Microcontroller Embedded Development Using the CCS PIC MCU C Compiler

Day 3: USB Development Using the CCS C Compiler

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Fred Eady

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AGENDA

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- Create a PIC18F47J53 USB Project
- Write the Application Code
- Code the USB Interface Application
- Run the USB Control Application





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PIC18F47J53 Hardware







PIC Microcontroller Embedded Development Using the CCS PIC MCU C Compiler USB Development Using the CCS C Compiler

Create a PIC18F47J53 USB Project

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PIC18F47J53 Hardware





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Choose the PIC and Specify the CPU Clock Speed

| | Optio | ns Code | | | | | |
|----------------|---------------------------|--|--|-------------|-------------------|-------------|---|
| eripherals | | 1 | | | | | |
| | Ge | Device | | | | | |
| alog | | Family: | PIC18 | ~ | Debug Code | | |
| mmunications | | Device: | PIC18F | 47J53 ~ | Fixed Compiler Ve | rsion: None | ~ |
| | | Clock | | | - | | |
| vers | | Oscillator Type: | Crystal | ~ | Use USB | Low Speed | |
| ader Files | | Crystal Clock Speed | d: 12 MHz | ~ 1 | 2 MIRS Clock Ou | Full Speed | |
| gh/Low Voltage | | | 40 MH2 | ~ | 2 mir 3 🛄 | | |
| errupts | | Enabled | WDT Reset | ○ 4096 ms | | | |
| Pins | | Check any of the following to restart | 0 8 ms | 0 8192 ms | | | |
| ners 0-2 | | getc() and fgetc() | ○ 32 ms | ○ 32768 ms | | | |
| iers 3-up | | i2c_read() | 0 128 ms | 0 131072 ms | | | |
| D (Internal) | | Delay Functions Reset: 4.0 ms | 256 ms 512 ms | | | | |
|) (External) | | | 0 1024 ms 2048 ms | | | | |
| | | | | | | | |
| oacitive Touch | | | | | | | |
| oacitive Touch | | | | | | | |



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Define the Analog Pins

| Project Wizard - C:\U | lsers | s\Public\c | ecCCS\day3_code\n | nain.ccspjt | | | | × |
|---------------------------|-------|---------------------|----------------------|-------------|------------|------------|---------------------|--------|
| <u>F</u> ile <u>H</u> elp | | | | | | | | |
| Peripherals | ^ | Options - Analog | Code g Input | | | | | |
| Analog | | An | alog Pins | | | Range V | ref-Vref 🗸 🗸 | |
| Communications | | | _ B0 _ C2 _ B1 | | | Units: 0-4 | .095 ~ | |
| SPI | | | B3 B2 | | | Internal R | C Clock 🗸 🗸 | |
| Header Files | | | _ E2 _ E1 _ E0 | | | Acquisitio | on time: 1.6 us 🛛 🗸 | |
| High/Low Voltage | | | _ A5 _ A3 _ A2 | | | | | |
| Interrupts | | | A1 A0 | | | | | |
| I/O Pins | | | | | | | | |
| Timers 0-2 | | | | | | | | |
| Timers 3-up | | | | | | | | |
| LCD (External) | | | | | | | | |
| CapacitiveTouch | | | | | | | | |
| RTCC | | | | | | | | |
| CCP/Vref | ¥ | | | | | | | |
| | | Chip: | PIC18F47J53 | Frequency: | 48,000,000 | | Create Project | Cancel |



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Configure the UART

| Project Wizard - C:\l | Jsers | \Public\c | ecCCS\day | 3_code\ma | ain.ccspjt | | | | | | × |
|---------------------------|-------|-----------------|------------------|------------|------------|--------------------------|--------------|----------|--------------------|--------|--------|
| <u>F</u> ile <u>H</u> elp | | | | | | | | | | | |
| Device Selection | ^ | Options Comm | Code | | | | | | | | |
| Device | | RS | -232 Use RS-2 | 32 | | | | | | | |
| Example Code | | (| Port Count 1 | RS232# | 1 🗸 | Baud: | 9600 | Inver | t _high | | |
| Peripherals | | | O2 O3 | UART1 | ~ | Parity: Transmit Pin: | None V | Error | s mal interrupt | | |
| Analog | | (| O 4 | Standa | rd | Receive Pin: | C7 ~ | | | | |
| Communications | | | | ⊖ RS48 | 35 | Enable Pin: | None 🗸 | Receive | Enable Pin: | None 🗸 | |
| SPI | | | Restart W | DT on RS23 | 32 | Bits: Stream: | 8 v PORT1 | Buffer S | ize: | 0 | |
| Drivers | | | | | | | | | | | |
| Header Files | 1 | -120 | / Use I2C | | | | Restart WDT | on I2C | | | |
| High/Low Voltage | | s | SDA: B5 | ~ | Ös | lave | Force Hardw | /are | | | |
| Interrupts | | 5 | SCL: B4 | . J ~ | ⊚ F ⊖ S | ast low Slav | ve Address | |] | | |
| I/O Pins | | | | | | | | | 1 | | |
| Timers 0-2 | | | | | | | | | | | |
| Timers 3-up | | | | | | | | | | | |
| LCD (Internal) | | | | | | | | | | | |
| LOD (Entered) | | Chip: | PIC18 | 3F47J53 | Frequenc | y: 48 | ,000,000 | | Create P | roject | Cancel |



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Configure the USB Engine

| Project Wizard - C:\U | lsers | s\Public\cecCCS\day3_code\main.ccspjt | × |
|---------------------------|-------|--|-------------------|
| <u>F</u> ile <u>H</u> elp | | | |
| High/Low Voltage | ^ | Options Code | |
| Interrupts | | USB | |
| I/O Pins | | 1- 2/ | |
| Timers 0-2 | | Software Algorithm Interrupts Image: Connection Sense Pin None Image: Connection Sense Pin | |
| Timers 3-up | | Vendor ID (VID) 0x | |
| LCD (Internal) | | Product ID (PID) 0x | |
| LCD (External) | | Product String | |
| Capacitive Touch | | Maximum Bus Power (mA) 500 @ | |
| RTCC | | Device Class | |
| CCP/Vref | | Communication Device Class (CDC, Virtual COM port) Human Interface Device Class (HID) HID and CDC | |
| Comparator | | O Bulk USB | |
| USB | | PIC Transmit Size (bytes) | |
| TCP/IP | | PIC Receive Size (bytes) 0 | 2 |
| MODBus | | Enter Tx and Rx size fom 0 to 63 | A PROVIDE |
| CANBus | | THE THE PARTY OF T | $\langle \rangle$ |
| Bootloader | ~ | | |
| | | Chip: PIC18F47J53 Frequency: 48,000,000 Create Project Ca | ncel |



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Set and Expose the Fuses and Create the Project

| Project Wizard - C:\U | t Wizard - C:\Users\Public\cecCCS\day3_code\main.ccspjt | | | | | | | | × |
|---------------------------|---|-------------|-------------------------|-----------------------------------|---|---------------------------------|----------------------|----------------|--------|
| <u>F</u> ile <u>H</u> elp | | | | | | | | | |
| Timers 0-2 | ^ | Options | Code | | | | | | |
| Timers 3-up | | Fuses | ide Fuse | es | | | | | |
| LCD (Internal) | | | | | | | | | |
| LCD (External) | | St | ack full/ ttended | underflow wil set extension | i cause reset and Indexed Addr | essing mode en | abled | | |
| Capacitive Touch | | Co High | ode prot | ected from rea | ads s selected | | ~ | | |
| RTCC | | | utput clo | ck on OSC2 | | | | | |
| CCP/Vref | | Fa | iil-safe o ternal Ex | clock monitor e tternal Switch | nabled Over mode enable | ed | | | |
| Comparator | | DSW | DT use | s INTRC as ref | erence clock | | ~ | | |
| USB | | RTC | C uses S | Secondary Os | cillator as referen | ce source | ~ | | |
| TCP/IP | | BC | OR enab eep Slee | led in Deep Sl p Watchdog T | eep ïmer enabled | | | | |
| MODBus | | | SWDT_* lows on | ly one reconfi | guration of periph | eral pins | | | |
| CANBus | | ADC | is 12-bi | ts | | | ~ | | |
| Bootloader | | MSS | P uses 7 | 7 bit Masking r | node | | ~ | | |
| Advanced | | ⊠ W □ Co | rite/Eras onfigurat | e Protect Pag tion Words pa | e Start/End Locatio ge is erase/write- | on, set to last pa protected | ige or use WPFP=x to | set page | |
| Options | | | l Flash n | nemory may b | e erased or writte | n | and protocol of | | |
| Fuses | Ļ | Fiasi | n pages | WPPP to Cont | iguration words p | age are write/er | ase protected V | | |
| | | Chip: | F | PIC18F47J53 | Frequency: | 48,000, | 000 | Create Project | Cancel |



main.h

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#include <18F47J53.h> #device ADC=12

| #FUSES | NOWDT | //No Watch Dog Timer |
|---------------|--------------|---|
| #FUSES | SOSC_HIGH | //High-power SOSC circuit is selected |
| #FUSES | DSWDTOSC_INT | //DSWDT uses INTRC as reference clock |
| #FUSES | RTCOSC_T1 | //RTCC uses Secondary Oscillator as reference source |
| #FUSES | IOL1WAY | //Allows only one reconfiguration of peripheral pins |
| #FUSES | ADC12 | //ADC is 12-bits |
| #FUSES | MSSPMSK7 | //MSSP uses 7 bit Masking mode |
| #FUSES | WPFP | //Write/Erase Protect Page Start/End Location, set to last page or use WPFP=x to set page |
| #FUSES | WPDIS | //All Flash memory may be erased or written |
| #FUSES | WPEND | //Flash pages WPFP to Configuration Words page are write/erase protected |

#use delay(clock=48MHz,crystal=12MHz,USB_FULL)
#use FIXED_IO(D_outputs=PIN_D7,PIN_D6,PIN_D5,PIN_D4)
#define btnB1 PIN_B1
#define led0_ORG PIN_D4
#define led1_BLU PIN_D5
#define led2_RED PIN_D6
#define led3_GRN PIN_D7

#use rs232(baud=9600,parity=N,xmit=PIN_C6,rcv=PIN_C7,bits=8,stream=PORT1)
#use i2c(Master,Fast,sda=PIN_B5,scl=PIN_B4)

#define USB_CONFIG_BUS_POWER 500
#include <usb_cdc.h>



PIC Microcontroller Embedded Development Using the CCS PIC MCU C Compiler **USB Development Using the CCS C Compiler** Write the Application Code

Initialization Code

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#include <main.h>

```
unsigned int8 cmdBuf[8];
int16 adcVal;
int1 adcDone;
unsigned int8 cmdBufIndx;
```

```
/* TODO: Use usb_cdc_putc() to transmit data to the USB
virtual COM port. Use usb_cdc_kbhit() and usb_cdc_getc() to
receive data from the USB virtual COM port. usb_enumerated()
can be used to see if connected to a host and ready to
communicate. */
```

```
void main()
   setup_adc_ports(sAN1 | sAN0, VREF_VREF);
   setup_adc(ADC_CLOCK_INTERNAL | ADC_TAD_MUL_8);
   set_adc_channel(0);
   usb_init();
   output_low(led0_ORG);
   output_low(led1_BLU);
   output_low(led2_RED);
   output_low(led3_GRN);
   cmdBufIndx = 0;
```





PIC Microcontroller Embedded Development Using the CCS PIC MCU C Compiler USB Development Using the CCS C Compiler Write the Application Code

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USB Control Application Code



{

```
if(usb_enumerated())
{
    if(usb_cdc_kbhit())
    {
        do{
            cmdBuf[cmdBufIndx++] = usb_cdc_getc();
        }while(usb_cdc_kbhit());
        switch(cmdBuf[4])
```

```
{
```

}

```
case 0xD4:
   output_high(led0_ORG);
   output_low(led1_BLU);
   output_low(led2_RED);
   output_low(led3_GRN);
   cmdBufIndx = 0;
break;
 case 0xD5:
  output_low(led0_ORG);
   output_high(led1_BLU);
   output_low(led2_RED);
   output_low(led3_GRN);
   cmdBufIndx = 0;
break;
case 0xD6:
   output_low(led0_ORG);
   output_low(led1_BLU);
   output_high(led2_RED);
   output_low(led3_GRN);
   cmdBufIndx = 0;
break;
case 0xD7:
   output_low(led0_ORG);
   output_low(led1_BLU);
   output_low(led2_RED);
   output_high(led3_GRN);
   cmdBufIndx = 0;
break;
```





PIC Microcontroller Embedded Development Using the CCS PIC MCU C Compiler USB Development Using the CCS C Compiler Write the Application Code

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Compile the USB Control Application Code





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Code the USB Interface Application

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USB Interface Application Code

Private Sub btnRefreshComPort_Click cmbComPorts.Items.Clear cmbComPorts.Items.AddAll(usbport.ListPorts) End Sub

Private Sub btnCloseComPort_Click

Astreams.Write2(cmdBuf,0,2) Delay(1000) Astreams.Close cmbComPorts.Items.Clear IbIConnectStatus.TextColor = fx.Colors.Red IbIConnectStatus.Text = "Disconnected" End Sub

Private Sub cmbComPorts_SelectedIndexChanged(Index As Int, Value As Object) Log(Index) If Index > -1 Then usbport.Open(cmbComPorts.Value) Astreams.InitializePrefix(usbport.GetInputStream,False,usbport.GetOutputStream,"Astreams") IbIConnectStatus.TextColor = fx.Colors.Green IbIConnectStatus.Text = "Connected " End If End Sub





PIC Microcontroller Embedded Development Using the CCS PIC MCU C Compiler USB Development Using the CCS C Compiler Code the USB Interface Application

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USB Interface Application Code

Private Sub togbtnOrg_SelectedChange(Selected As Boolean) Log("orange") cmdBuf(0) = 0xD4 Astreams.Write2(cmdBuf,0,1) End Sub

Private Sub togbtnBlu_SelectedChange(Selected As Boolean) Log("blue") cmdBuf(0) = 0xD5 Astreams.Write2(cmdBuf,0,1) End Sub

Private Sub togbtnRed_SelectedChange(Selected As Boolean) Log("red") cmdBuf(0) = 0xD6 Astreams.Write2(cmdBuf,0,1) End Sub

Private Sub togbtnGrn_SelectedChange(Selected As Boolean) Log("green") cmdBuf(0) = 0xD7 Astreams.Write2(cmdBuf,0,1) End Sub





PIC Microcontroller Embedded Development Using the CCS PIC MCU C Compiler USB Development Using the CCS C Compiler Run the USB Control Application

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USB Interface Application Code



Private Sub togbtnBlu_SelectedChange(Selected As Boolean) Log("blue") cmdBuf(0) = 0xD5 Astreams.Write2(cmdBuf,0,1) End Sub

| Expressio | on (in valid C syntax) | ~ 💠 🗸 |
|-------------|------------------------|-------|
| cmdBuf [HEX |] | ▲ X |
| ∨ cmdB | | |
| [0] | 0x01 | |
| -[1] | 0X00 | |
| [2] | 0X00 | |
| -[3] | 0X00 | |
| -[4] | 0xD5 | |
| [5] | 0x00 | |
| -[6] | 0x8E | |
| [7] | 0xDD | |



PIC Microcontroller Embedded Development Using the CCS PIC MCU C Compiler USB Development Using the CCS C Compiler Run the USB Control Application

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USB Interface Application Code



| Expressio | on (in valid C syntax) | ~ | ¢ | - |
|-------------|------------------------|---|---|------------|
| mdBuf [HEX] | | | | . x |
| ∨ cmdB | | | | |
| [0] | 0x01 | | | |
| [1] | 9X98 | | | |
| [2] | 9X98 | | | |
| -[3] | 0x00 | | | |
| [4] | 0xD5 | | | |
| [5] | 98X90 | | | |
| [6] | 0x8E | | | |
| [7] | 0xDD | | | |

```
if(usb_enumerated())
```

```
if(usb_cdc_kbhit())
  do{
     cmdBuf[cmdBufIndx++] = usb_cdc_getc();
  }while(usb_cdc_kbhit());
  switch(cmdBuf[4])
     case 0xD4:
         output_high(led0_ORG);
        output_low(led1_BLU);
        output_low(led2_RED);
        output_low(led3_GRN);
        cmdBufIndx = 0;
     break;
      case 0xD5:
        output_low(led0_ORG);
        output_high(led1_BLU);
        output_low(led2_RED);
        output_low(led3_GRN);
        cmdBufIndx = 0;
     break;
```





MORE TO COME..

Thank you for attending!!!

Please consider the resources below:

- ccsinfo.com
- CCS C Compiler Manual
- Master and Command C for PIC MCU (PDF)







Thank You





Same

