



Day 1: CCS C Project Wizardry 101

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Fred Eady

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AGENDA

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- Create a PIC18F45K50 Project
- Write the Application Code
- Compile and Run the Application Code





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PIC18F45K50 Hardware





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Choose the PIC and Specify the CPU Clock Speed

rinharala	Options Code			
enpherais	General			
log	Device			
y	Family:	PIC18	Debug Code	
munications	Device:	PIC18F45K50	Fixed Compiler Version:	None \sim
	Clock			
ers	Oscillator Type:	Crystal 🗸	Use USB Low Sp	eed
	Crystal Clock Spee	ed: 16 MHz 🗸	Use USB Full Spe	ed
der Files	CPU Clock Speed:	16 MHz V	4 MIPS Clock Out	
n/Low Voltage				
rupts	WDT	WDT Depet		
	Enabled	4 ms 4096 ms		
ins	Check any of the following to restart	0 8 ms 0 8192 ms		
ws 0.2	WDT during calls to:	◯ 16 ms ◯ 16384 ms		
15 0-2	getc() and fgetc()	○ 32 ms ○ 32768 ms		
rs 3-up	i2c_read()	0 64 ms 0 65536 ms		
(latara al)	Delay Functions	0 256 ms		
(Internal)	Reset: 4.0 ms	○ 512 ms		
(External)		O 1024 ms		
		2048 ms		
acitive Touch				
c				
-				



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Define the Analog Pins

Project Wizard - C:\Us	sers	\Public\ce	ecCCS\day	y1_code\n	nain.ccspjt				×
<u>F</u> ile <u>H</u> elp									
Peripherals	^	Options Analog	Code g Input						
Analog		An	alog Pins-				Range 0	Vdd Vd	
Communications			A0	C4			Linits: 0-1	023	1
SPI] A2] A3] A5				Internal P		1
Drivers] E0] E1	D1					1
Header Files] E2] B2	D3			Acquisitio	on time: 1.6 us 🗸	
High/Low Voltage] B1] B4	D6					
Interrupts			B0 B5						
Timers 0.2] C3						
1111615-0-2									
Timers 3-up									
LCD (Internal)									
LCD (External)									
Capacitive Touch									
RTCC									
CCP/Vret	¥				_				
		Chip:	PIC1	8F45K50	Frequency:	16,000,000		Create Project	Cancel



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Peek at the ADC Setup Code

Project Wizard - C:\U	sers	\Public\c	ecCCS\day1_code\n	nain.ccspjt			×
<u>F</u> ile <u>H</u> elp							
Peripherals	^	Options	Code				<u>^</u>
Analog		Inserted	into .c file in main():	NO VEE VDD			
Communications			setup_adc(ADC_CL	OCK_INTERNAL A	DC_TAD_MUL_8);		
SPI							
Drivers							
Header Files							
Interrupts							
I/O Pins							
Timers 0-2							
Timers 3-up							
LCD (Internal)							
LCD (External)							
Capacitive Touch							
CCP/Vref	~	<					>
		Chip:	PIC18F45K50	Frequency:	16,000,000	Create Project	Cancel



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Configure the UART

	^	Options	Code						
eripherals		C							
nalog		RS	-232 Use RS-23	32					
ommunications			Port Count	RS232#1	~	Baud:	9600	Invert	
기			02	Туре:		Parity:	None 🗸	Float_high	
rivers			3	UART1	~	Transmit Pir	1: C6 ~	External inte	rrupt
eader Files			○4	Standar	d 2	Receive Pin	: C7 ∨ Pin: None ∨	Receive Enable	Pin: None 🗸
igh/Low Voltage			Restart WI	ORS48	2	Bits:	8 ~	Buffer Size:	0
terrupts						Stream:	PORT1	ID:	10
) Pins		-120							
mers 0-2		, L	Use I2C SDA: No	ne 🗸		Master Slave	Restart WDT	on I2C are	
mers 3-up		\$	SCL: No	ne 🗸		Fast			
D (Internal)					Ó	Slow	Slave Address		
D (External)									
apacitive Touch									
гсс									



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Peek at the UART Initialization Code

Project Wizard - C:\U	sers	\Public\ce	acCCS\/	day1_code\n	nain.ccspjt				×
<u>F</u> ile <u>H</u> elp									
Peripherals	^	Options	Code						^
Analog		Inserted #use rs2	into .h fi 232(bau	ile: d=9600,parity:	=N,xmit=PIN_C6,rcv	=PIN_C7,bits=8,strea	am=PORT1)		
Communications									
SPI									
Drivers									
Header Files									
High/Low Voltage									
Interrupts									
I/O Pins									
Timers 0-2									
Timers 3-up									
LCD (Internal)									
LCD (External)									
Capacitive Touch									
RTCC									~
CCP/Vref	~	<							>
		Chip:	P	IC18F45K50	Frequency:	16,000,000		Create Project	Cancel



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Define the GPIO Pins

Project Wizard - C:\U	Jsers	\Public\cecCC	5\day1_code\m	ain.co	spjt			>
<u>F</u> ile <u>H</u> elp								
Peripherals	^	Options Code	e					
Analog		Dect C						^
Communications		PIN_C0	None	~	Name:			
Communications		PIN_C1	None	~	Name:			
SPI		PIN_C2	None	~	Name:			
		PIN_C6	(RS232#1 XMF	r) ~	Name:			
Drivers		PIN_C7	(RS232#1 RCV	/) ~	Name:			
Header Files		Port D						
High/Low Voltage		PIN_D0	None	~	Name:			
. ng. n 2011 Voltago		PIN_D1	None	~	Name:		 	
Interrupts		PIN_D2	None	~	Name:			
I/O Pins		PIN_D3	None	~	Name:			
		PIN_D4	None	~	Name:			
Timers 0-2		PIN_D5	None	~	Name:			
T ime of S and		PIN_D6	None	~	Name:			
Timers 3-up		PIN_D7	None	~	Name:			
LCD (Internal)		Port F						
CD (External)		PIN_E0	None	~	Name:			
LOD (External)		PIN_E1	None	~	Name:		 	
Capacitive Touch		PIN_E2	None	~	Name:			
8700		PIN_E3	None	~	Name:			
RICC		🗌 Pull-up	Resistors		-			*
CCP/Vref	¥							
		Chip:	PIC18F45K50	Frequ	ency:	16,000,000	Create Project	Cancel



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Define the GPIO Pins

	^	Options Cod	de				
ligh/Low Voltage		I/O Pins					
		le la					
nterrupts		Port A			Name		 <u>^</u>
O Pins		PIN_AU	(Analog)	~	Name:		
		PIN_A1	None	~	Name:		
imers 0-2		PIN_A2	None	~	Name:		
		PIN_A3	None	~	Name:		
mers 3-up		PIN_A4	input	~	Name:	btnA4	
CD (Internal)		PIN_A5	Output	~	Name:	ledGrnA5	
		PIN_A6	None	~	Name:		
CD (External)		PIN_A/	None	~	Name:		
		Dect R					
apacitive Touch			None		Name:		
тсс		DIN B1	None		Name:		
			None		Name:		
CP/Vref		PIN B3	None		Name:		
		PIN B4	Output	ž	Name	led∀elB4	
omparator		PIN B5	Output	ž	Name:	ledRedB5	
SB		PIN B6	None		Name:		
		PIN B7	None	, v	Name		
CP/IP			In Resistore	~			
			ip Resistors				
IODBus		-Port C-					
		PIN_C0	None	~	Name:		
ANBus							



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Set and Expose the Fuses

Project Wizard - C:\l	Jsers	\Public\c	ecCCS\day1_code\n	nain.ccspjt				×
<u>F</u> ile <u>H</u> elp								
Timers 0-2	^	Options	Code					
Timers 3-up		Fuses	s ude Fuses					
LCD (Internal)								^
LCD (External)		Prim	ary clock is system clo	ock when scs=00		~		
Capacitive Touch			all-safe clock monitor e ternal External Switch	nabled Over mode enable	ed			
RTCC		No b	ower Up Timer prownout reset			~		
CCP/Vref		Brow	wnout reset at 1.9V			~		
Comparator	l		ow-Power Brownout r ORTB pins are configu	eset is enabled red as analog inpu	ut channels on RES	ET		
USB		тз с	Clock In is on CO			~		
TCP/IP		SDO) is on RB3			~		
MODBus		⊠ M ⊡ Si	aster Clear pin enable tack full/underflow wil	t cause reset				
CANBus			ow Voltage Programmi	ng on B3(PIC16) o	r B5(PIC18)			
Bootloader			ode protected from rea	and Indexed Addr ids	essing mode enabl	ed		
Advanced			ata EEPROM Code Protect	ea ected				
Options			rogram Memory Write F onfiguration registers	Protected write protected				
Fuses		B	oot block write protect	ed				~
	V	Chip:	PIC18F45K50	Frequency:	16,000,000	D	Create Project	Cancel



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Set and Expose the Fuses and Specify Function Brace Positions

Project Wizard - C:\l	Jsers	\Public\ce	ecCCS\(day1_code\m	nain.ccspjt			×
<u>F</u> ile <u>H</u> elp								
Timers 0-2	^	Options	Code					
Timers 3-up		-Option -Fu	is nction G	eneration				
LCD (Internal)		۲	Opening	g brace on the	following line			
LCD (External)		0	Opening	g brace on the	same line			
CapacitiveTouch		□ F ☑ C	Restart W One fuse	DT during cal	ls to DELAY comments			
RTCC			dd Defa	ult Fuses to H	eader File			
CCP/Vref								
Comparator								
USB								
TCP/IP								
MODBus								
CANBus								
Bootloader								
Advanced								
Options								
Fuses	¥							
		Chip:	PI	C18F45K50	Frequency:	16,000,000	Create Project	Cancel



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Expose the Fuses and Create the Project

Project Wizard - C:\U	sers	\Public\c	blic\cecCCS\day1_code\main.ccspjt X							
<u>File</u> <u>H</u> elp										
Timers 0-2	^	Options	Code							
Timers 3-up		Inserted	l into .h file:					^		
LCD (Internal)		#FUSES		//No Watch Dog Ti	ner wstem clock when s	cs=00				
LCD (External)		#FUSES #FUSES	NOBROWNOUT	//No bro //Brownout reset a	wnout reset at 1.9V					
Capacitive Touch		#FUSES #FUSES #FUSES	PBADEN T3CKC0 SDOB3	//PORTB pins are (//T3 Clock In is on //SDO is on RB3	configured as analog CO	input channels on	RESET			
RTCC		#FUSES #FUSES	MCLR	//Master Clear pin //Code not protect	enabled ed from reading					
CCP/Vref		#FUSES #FUSES	NOWRT	//Program memory //Memory not prote	not write protected ected from table read	s				
Comparator										
USB										
TCP/IP										
MODBus										
CANBus										
Bootloader										
Advanced										
Options										
Fuses	~	<						>		
		Chip:	PIC18F45K50	Frequency:	16,000,000		Create Project	Cancel		



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Create a PIC18F45K50 Project

main.h

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#include <18F45K50.h>
#device ADC=10

#FUSES	NOWDT	//No Watch Dog Timer
#FUSES	PRIMARY	//Primary clock is system clock when scs=00
#FUSES	NOBROWNOUT	//No brownout reset
#FUSES	BORV19	//Brownout reset at 1.9V
#FUSES	PBADEN	//PORTB pins are configured as analog input channels on RESET
#FUSES	T3CKC0	//T3 Clock In is on C0
#FUSES	SDOB3	//SDO is on RB3
#FUSES	MCLR	//Master Clear pin enabled
#FUSES	NOPROTECT	<pre>//Code not protected from reading</pre>
#FUSES	NOWRT	//Program memory not write protected
#FUSES	NOEBTR	<pre>//Memory not protected from table reads</pre>

#use delay(crystal=16MHz)
#use FIXED_IO(A_outputs=PIN_A5)
#use FIXED_IO(B_outputs=PIN_B5,PIN_B4)
#define btnA4 PIN_A4
#define ledGrnA5 PIN_A5
#define ledYelB4 PIN_B4
#define ledRedB5 PIN_B5

#use rs232(baud=9600, parity=N, xmit=PIN_C6, rcv=PIN_C7, bits=8, stream=PORT1)



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Initialization Code

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#include <main.h>

```
unsigned int8 biteIn;
unsigned int1 btnPressed;
long adcVal;
float conVal = 0.004887586;
void main()
   setup_adc_ports(sAN0, VSS_VDD);
   setup_adc(ADC_CLOCK_INTERNAL | ADC_TAD_MUL_8);
   set_adc_channel(0);
   btnPressed = 0;
   output_high(ledRedB5);
   output_high(ledYelB4);
   output_high(ledGrnA5);
   printf("ALL LEDS = OFF\r\n");
```





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Button Sense Code



```
while(TRUE)
     biteIn = input(btnA4);
     if(biteIn == 0)
        delay_ms(10);
        biteIn = input(btnA4);
        if(biteIn == 0)
           printf("Button is depressed...\r\n");
           btnPressed = 1;
        }
        do
           biteIn = input(btnA4);
           if(biteIn == 1)
              delay_ms(10);
              biteIn = input(btnA4);
              if(biteIn == 1)
                 btnPressed = 0;
                 printf("Button is released...\r\n");
         }while(btnPressed == 1);
```





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Analog-to-Digital Code



long adcVal;
float conVal = 0.004887586;

```
adcVal = read_adc();
printf("adcVal = 0x%LX -> %lud\r\n",adcVal,adcVal);
printf("adc voltage = %f\r\n",adcVal*conVal);
```





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Write the Application Code

LED Control Code



if(kbhit()) biteIn = getc(); switch(biteIn) case 'R': output_low(ledRedB5); output_high(ledYelB4); output_high(ledGrnA5); printf("RED LED = ON\r\n"); break; case 'Y': output_high(ledRedB5); output_low(ledYelB4); output_high(ledGrnA5); printf("YELLOW LED = ON\r\n"); break; case 'G': output_high(ledRedB5); output_high(ledYelB4); output_low(ledGrnA5); printf("GREEN LED = ON\r\n"); break; default: output_high(ledRedB5); output_high(ledYelB4); output_high(ledGrnA5); printf("Invalid Character Received -> All LEDS = OFF\r\n"); break;





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Compile and Run the Application Code

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21

Compile the Application Code





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Run the Application Code





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Run the Application Code







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Bonus USB Version





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MORE TO COME..

Thank you for attending!!!

Please consider the resources below:

- ccsinfo.com
- CCS C Compiler Manual
- Master and Command C for PIC MCU (PDF)







Thank You





Same

