

DesignNews

DC Motor Controls with the RP2040 Pico

DAY 5: RP2040 Pico and H-Bridge DC Motor Controls

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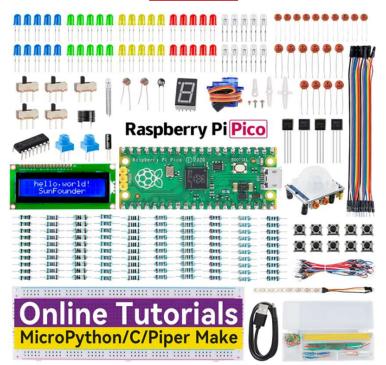
Dr. Don Wilcher

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<u>SunFounder Raspberry Pi Pico</u> Starter Kit



Course Kit and Materials

L298N Motor Drive Controller Board



1 Channel Relay Module



<u>ULN2003 4-Phase Stepper</u> <u>Motor with 5V Drive Board</u>









Agenda:

- Basic DC Motor Control Concept
- H-Bridge Motor Control Basics
- Lab: H-Bridge DC Motor Controller







Raspberry Pi RP2040:



"Raspberry Pi RP2040 SoC, a surprisingly powerful yet radically low-cost microcontroller packing dual Arm Cortex-M0+ processors, the most energy-efficient Arm processor available" (Adams, 2021).





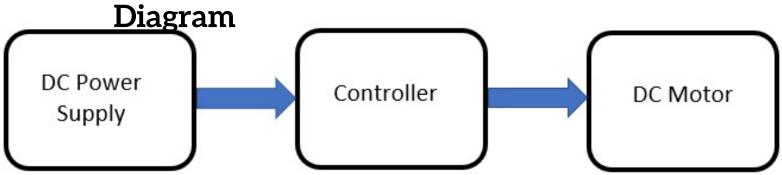
Basic DC Motor Control Concept



A Basic DC Motor Control consists of

- DC power supply.
- A controller
- A DC motor

Basic DC Motor Control Block



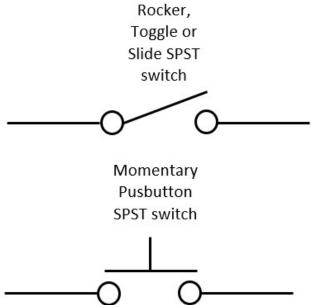




Basic DC Motor Control Concept...



A simple controller for operating a typical dc motor is a Single Pole-Single Throw switch (SPST).



Typical Switches which can be used as a simple controller





Basic DC Motor Control Concept...



Typical Switches which can be used as a simple controller



Slide SPST Switch



Rocker SPST Switch



Toggle SPST Switch





Question 1



Identify the switch based on the electrical symbol shown in Figure 1.

Figure 1.

- a) Single Pole Single Throw (SPST) switch
- b) Single Pole Double Pole (SPDT) switch
- c) Double Pole Double Throw (DPDT) switch
- d) none of the above

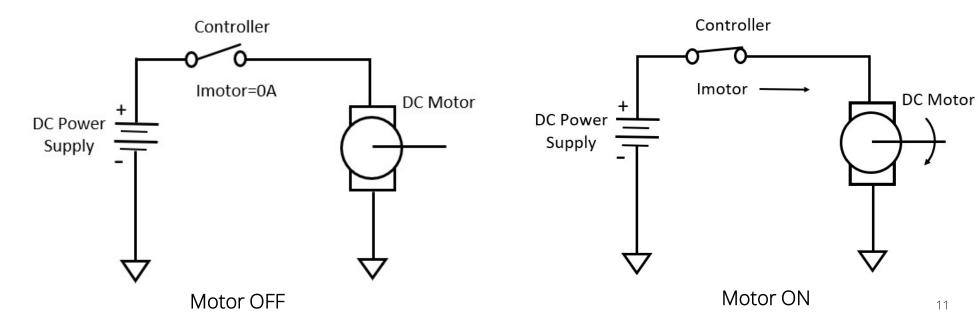




Basic DC Motor Control Concept...



A typical circuit schematic diagram of Basic DC Motor Controller



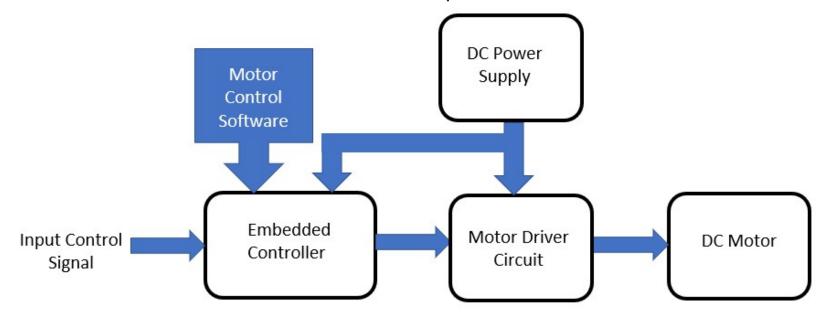




Basic DC Motor Control Concept...



To make a controller that is less manual dependent, a desirable automation-based solution can be conceptualized.



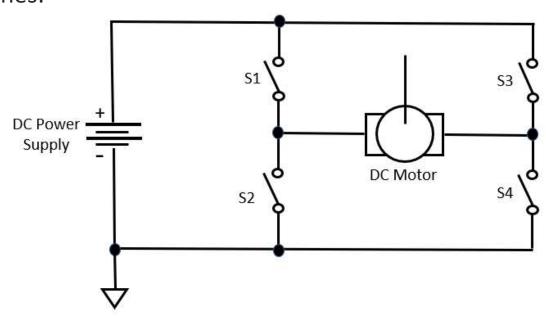




H-Bridge Driver Basics



An electronic circuit capable of switch polarity across electromechanical load. A basic method of illustrating the concept of a H-Bridge Driver circuit is using four SPST switches.





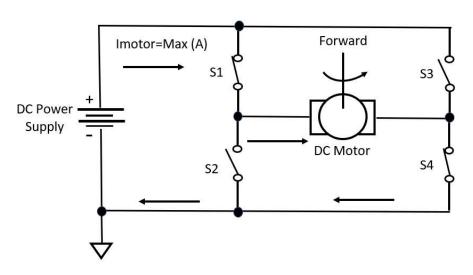


H-Bridge Driver Basics...

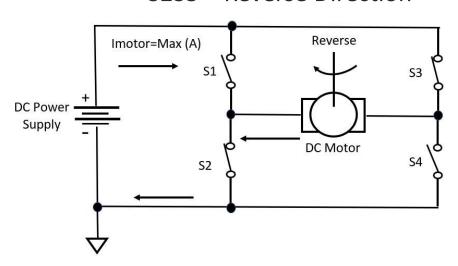


By closing the correct switch combinations, the H-Bridge Driver can control the direction of the DC motor.

S1S4 = Forward Direction



S2S3 = Reverse Direction





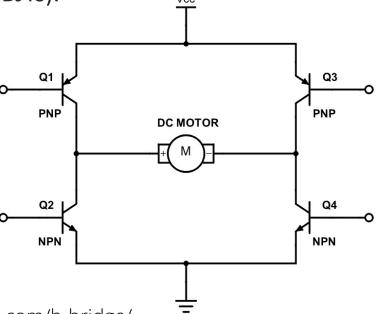


H-Bridge Driver Basics...



A solid- state (SS) version can be implemented using Complementary Pairs of PNP and NPN

bipolar junction transistors (BJTs).



Source:

https://www.build-electronic-circuits.com/h-bridge/

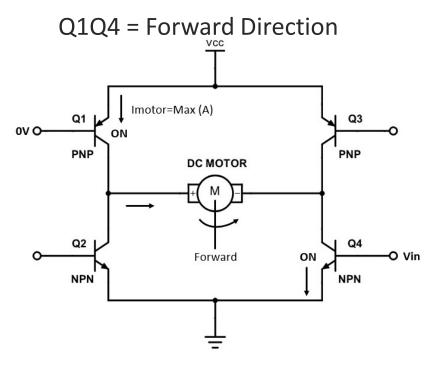


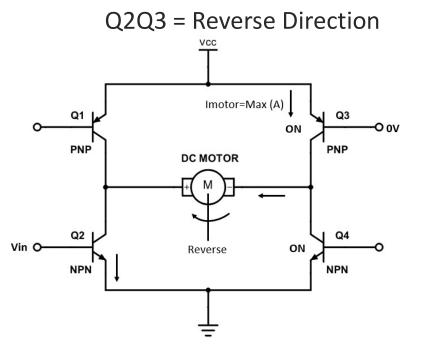


H-Bridge Driver Basics...

The direction of the DC Motor is controlled by turning on the correct complementary pair of BJTs.











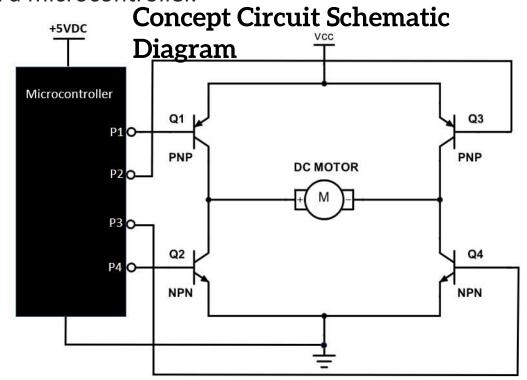
H-Bridge Driver Basics

The advantage to using a SS H-Bridge Driver is the ability to control speed and direction of the DC Motor with a microcontroller.

Pulse Width Modulating (PWM) the microcontroller's digital port pins (P1-P4) will provide speed control for the DC Motor.

P1P3 = Forward Direction P2P4 = Reverse Direction

Note: Each BJT transistor will have a base resistor (Rb) to limit current flowing through the semiconductor component.







The L293 H-Bridge IC

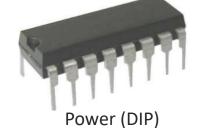




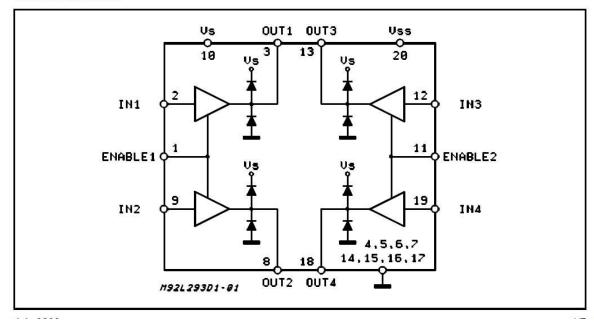
18



Small Outline (SO)



BLOCK DIAGRAM



Source:

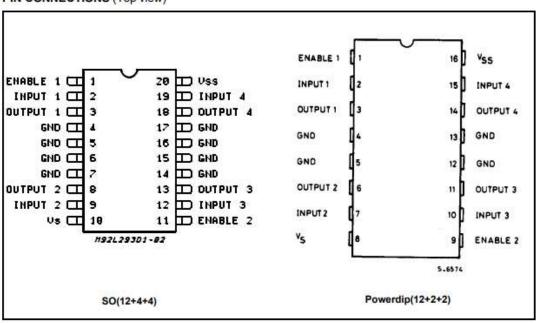




The L293 H-Bridge IC...

The L293 H-Bridge IC pinout for small outline (SO) and plastic Dual-Inline-Package (DIP) components

PIN CONNECTIONS (Top view)



Source:





The L293 H-Bridge IC...



The L293 H-Bridge IC electrical specifications.

ABSOLUTE MAXIMUM RATINGS

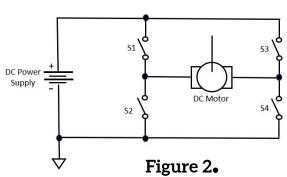
Symbol	Parameter	Value	Unit
Vs	Supply Voltage	36	V
Vss	Logic Supply Voltage	36	V
Vi	Input Voltage	7	V
Ven	Enable Voltage	7	V
l _o	Peak Output Current (100 µs non repetitive)	1.2	Α
P _{tot}	Total Power Dissipation at Tpins = 90 °C	4	W
T _{stg} , T _j	Storage and Junction Temperature	- 40 to 150	°C

Source:





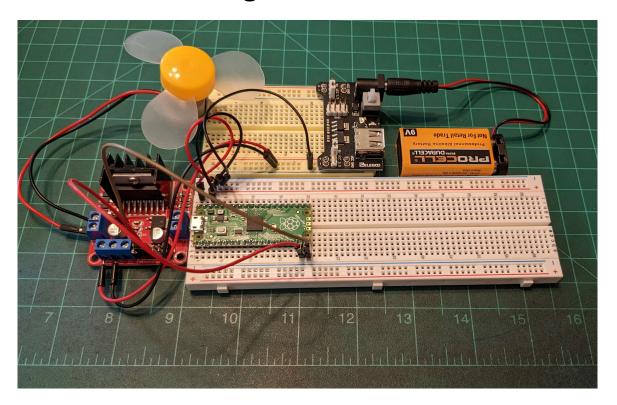
Question 2 Identify the electrical circuit shown in Figure 2.



- a) Half bridge DC motor driver circuit
- b) DC motor driver circuit
- c) H-Bridge DC motor driver circuit
- d) none of the above















Big IDEAS (Learning Objectives):

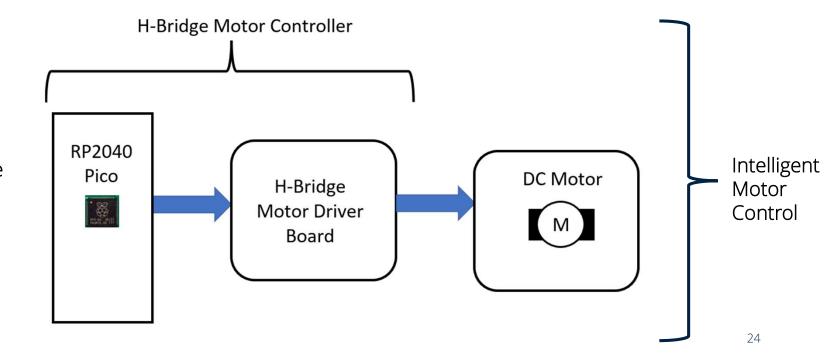
- The participant will be able to wire a DC motor to an H-Bridge DC motor driver board.
- The participant will be able to wire an H-Bridge DC motor driver board to an RP2040 microcontroller
- 3. The participant will be able to create an H-Bridge DC motor controller code using MicroPython.
- 4. The participant will be able to test a H-Bridge DC motor driver controller using MicroPython and the RP2040.







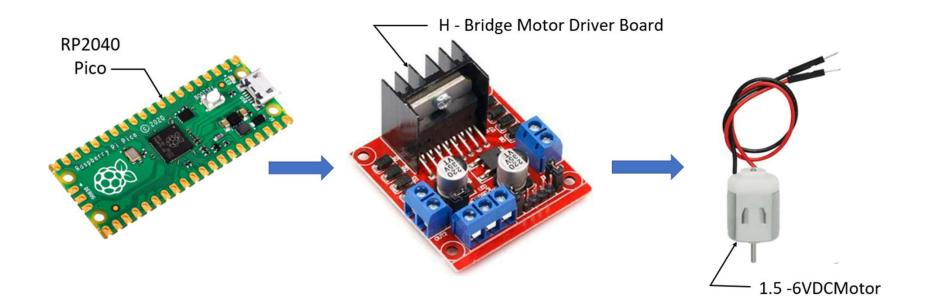
The RP2040 microcontroller easily controls a DC motor by providing the appropriate control signals to an H – Bridge motor driver board. Th









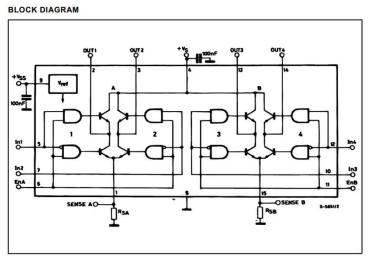








L298 Full Bridge IC on Board



H-Bridge Motor Driver Board Milliwatt15 or PowerSO20 packages





Question 3



What IC is on board an H-Bridge Motor driver board?

- a) L293
- b) L294
- c) L298
- d) none of the above



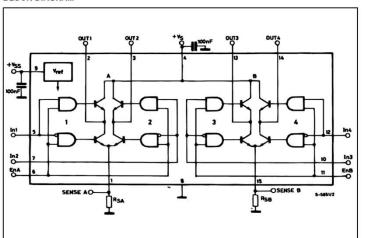




L298 Full Bridge IC on Board

2 Full Bridge Drivers

BLOCK DIAGRAM



Basic Specifications

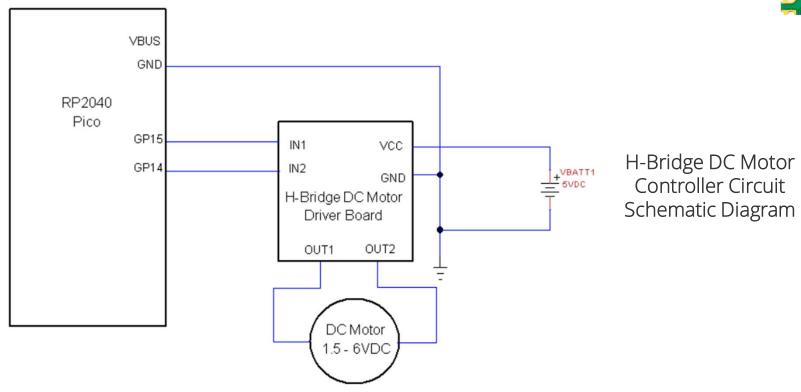
ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
Vs	Power Supply	50	٧
Vss	Logic Supply Voltage	7	٧
V_{I},V_{en}	Input and Enable Voltage	-0.3 to 7	٧
lo	Peak Output Current (each Channel) - Non Repetitive (t = 100µs) -Repetitive (80% on -20% off; ton = 10ms) -DC Operation	3 2.5 2	A A A
V _{sens}	Sensing Voltage	-1 to 2.3	٧
Ptot	Total Power Dissipation (T _{case} = 75°C)	25	W
Top	Junction Operating Temperature	-25 to 130	°C
T _{stg} , T _j	Storage and Junction Temperature	-40 to 150	°C













Question 4



What is the maximum output current (Io) the 298 IC can source to each channel?

a) 500mA

Continuing

- b) 2.5A
- c) 3A
- d) none of the above







To run the MicroPython Code, click the Run button

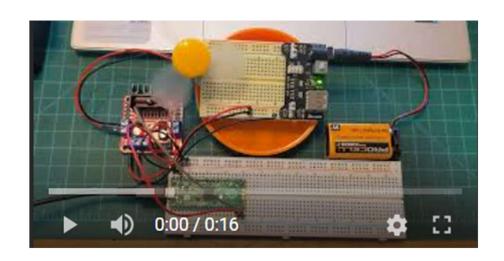
```
from machine import Pin
   import utime
   In1 = Pin(15, Pin.OUT)
   In2 = Pin(14, Pin.OUT)
   while True:
 8
       In1.value(0)
       In2.value(0)
9
10
       utime.sleep(1)
12
       In1.value(0)
13
       In2.value(1)
14
       utime.sleep(1)
15
       In1.value(1)
16
17
       In2.value(0)
18
       utime.sleep(1)
19
20
       In1.value(1)
21
       In2.value(1)
22
        utime.sleep(1)
```







H- Bridge DC Motor Controller Output



Watch Video Clip



https://youtu.be/s2sDUrZtCME





Question 5



The utime.sleep (1) instruction shown on slide 31 provides what time delay value?

- a) 1us
- **b) 1ms**
- c) 1s
- d) none of the above





Thank you for attending

Please consider the resources below:

Adams, J. (2021, February 1). *Raspberry pi rp2040: Our microcontroller for the masses*. https://www.arm.com/blogs/blueprint/raspberry-pi-rp2040

RP2040 Datasheet. (2022). RP2040 datasheet: A microcontroller by raspberry pi. https://datasheets.raspberrypi.com/rp2040/rp2040-datasheet.pdf

Raspberry Pi Pico Resources: Raspberry Pi Documentation - Raspberry Pi Pico and Pico W

How To Use Your Raspberry Pi Pico with DC Motors:

https://www.tomshardware.com/how-to/dc-motors-raspberry-pi-pico

How To Use A DC Motor With The Raspberry Pi Pico:

https://www.youngwonks.com/blog/How-to-use-a-DC-motor-with-the-Raspberry-Pi-Pico



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