



**DesignNews**

DC Motor Controls with the RP2040 Pico

# **DAY 3: RP2040 Pico and MicroPython Basics Part 2: Thonny Python**

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## Webinar Logistics

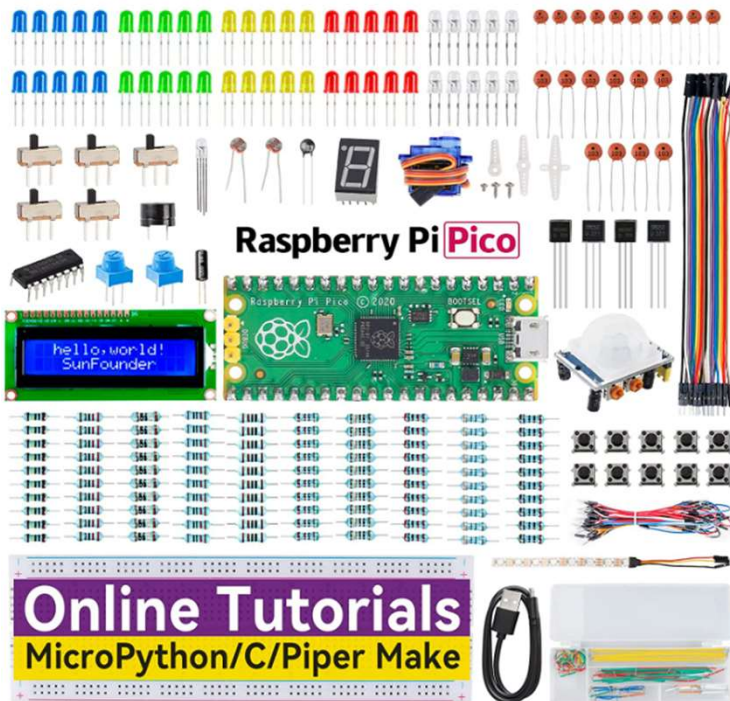
- Turn on your system sound to hear the streaming presentation.
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- Participate in ‘Attendee Chat’ by maximizing the chat widget in your dock.



## Dr. Don Wilcher

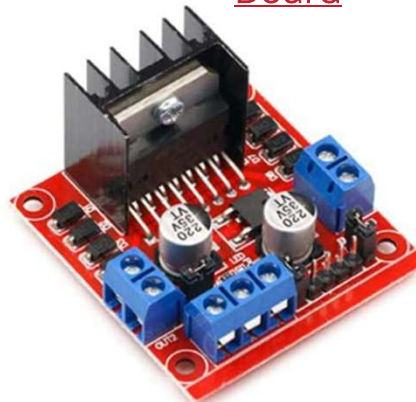
Visit 'Lecturer Profile' in your console for more details.

## SunFounder Raspberry Pi Pico Starter Kit

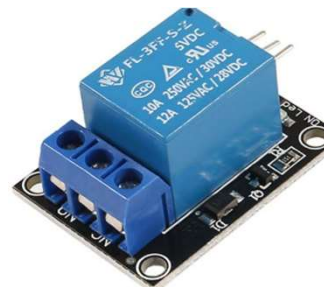


## Course Kit and Materials

### L298N Motor Drive Controller Board



### 1 Channel Relay Module



### ULN2003 4-Phase Stepper Motor with 5V Drive Board



### 1-5V – 6VDC Motor





## Agenda:

- Thonny Python
- Accessing and Installing Thonny
- MicroPython Controls Lab Activities
- Lab: Servo Motor Controller



## Raspberry Pi RP2040 :



“Raspberry Pi RP2040 SoC, a surprisingly powerful yet radically low-cost microcontroller packing dual Arm Cortex-M0+ processors, the most energy-efficient Arm processor available” (Adams, 2021).

## Thonny Python



Thonny Python:

- was built from Python 3.7
  - a) developed to make complex tasks simple
  - b) influenced by Julia (Julia: is fast, dynamic, easy to use, and is an open-source programming language)
- Is one simple installation
- user interface removed all features( no distractions to use it)

## Thonny Python. . .



Thonny Python:

- Easily view variables with the *View Variable* feature
- Simple Debugger allows single-step into programs without the use of breakpoints
- Highlights syntax



## Question 1



**Thonny was influenced by \_\_\_\_\_**

- a) Guido van Rossum**
- b) Python 3.7**
- c) Julia**
- d) none of the above**

## Thonny Python...

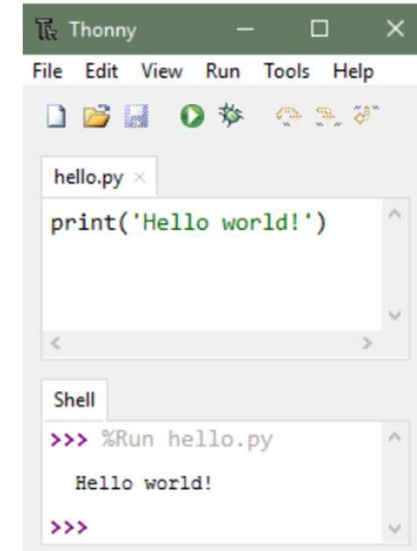
Highlights syntax errors

```
first_name = "Albus"  
last_name = "Dumbledore"  
result = math.pi * (34 + 12
```

Missing Quotation and  
parentheses



Easy To Use



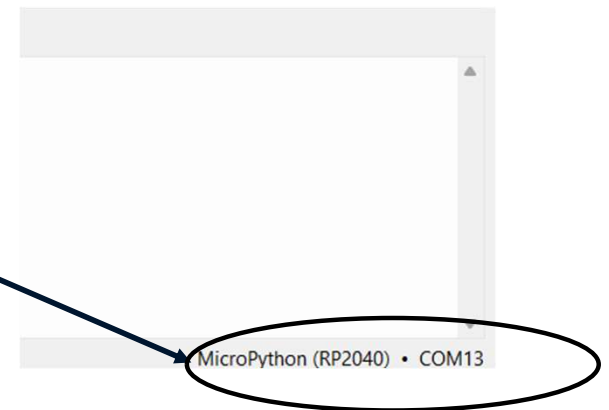
## Thonny Python. . .



How to Change Programming Language Compilers



Change Compilers Here!

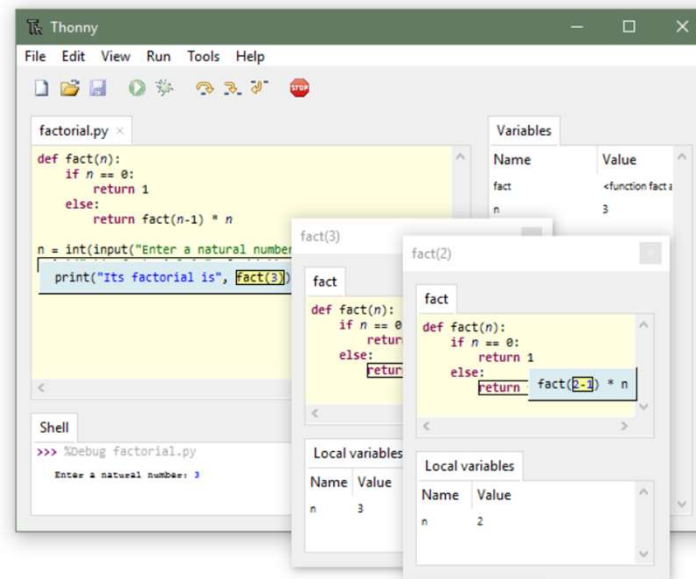


## Accessing and Installing Thonny

**Thonny**  
Python IDE for beginners



Download version [4.0.0](#) for  
Windows • Mac • Linux



<https://thonny.org/>

## Accessing and Installing Thonny . . .



### Instructions & downloads

- Installation instructions
  - [for Windows](#)
  - [for Mac](#)
  - [for Linux](#)
  - `pip install thonny`
- [FAQ](#)
- [Wiki](#)

Latest stable releases are linked in the download box at the top of this page.

Older releases and prereleases can be found at

<https://github.com/thonny/thonny/releases>

<https://thonny.org/>



## Accessing and Installing Thonny . . .



} Thonny IDE

## Accessing and Installing Thonny . . .



### MicroPython Code

```
loop_code.py ×  
1 print("Loop starting!")  
2 for i in range(10):  
3     print("Loop number",i)  
4 print("Loop finished!")
```

### Output

```
Shell ×  
Loop starting!  
Loop number 0  
Loop number 1  
Loop number 2  
Loop number 3  
Loop number 4  
Loop number 5  
Loop number 6  
Loop number 7  
Loop number 8  
Loop number 9  
Loop finished!  
  
>>>
```

## Question 2



**In reviewing slide 15, the for-loop initialization is identified by**

- a) range**
- b) 10**
- c) i**
- d) none of the above**

## MicroPython Control Lab Activities



### MicroPython Code

```
1 value = input ("Enter Value")
2 if value == "20":
3     print(value)
4 else:
5     print("Incorrect Value")
6
```

### Output

```
Shell x
>>> %Run -c $EDITOR_CONTENT

Enter Value20
20
>>>
```

## MicroPython Control Lab Activities . . .

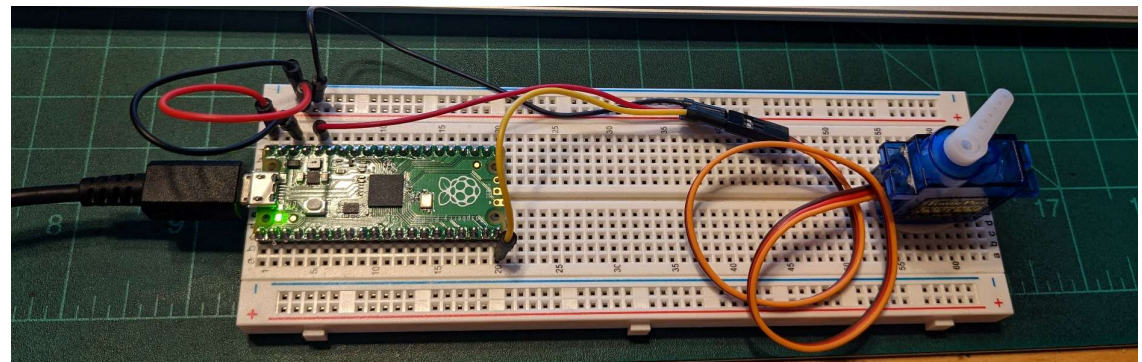


### MicroPython Code

```
1 import machine
2
3 led = machine.Pin(25,machine.Pin.OUT)
4
5 bit = input ("Enter Control Bit")
6 if bit == "1":
7     print(bit)
8     led(1)
9     print("LED is ON")
10
11 else:
12     print(bit)
13     led(0)
14     print("LED is OFF")
```

### Output

```
Shell x
>>> %Run -c $EDITOR_CONTENT
Enter Control Bit1
1
LED is ON
>>>
```





## MicroPython Control Lab Activities . . .

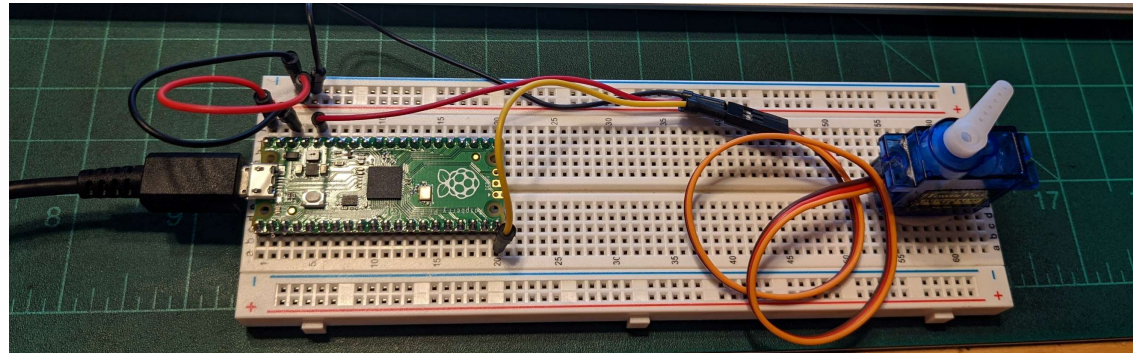


### MicroPython Code

```
1 import machine
2
3 led = machine.Pin(25,machine.Pin.OUT)
4
5 bit = input ("Enter Control Bit")
6 if bit == "1":
7     print(bit)
8     led(1)
9     print("LED is ON")
10
11 else:
12     print(bit)
13     led(0)
14     print("LED is OFF")
```

### Output

```
Shell x
>>> %Run -c $EDITOR_CONTENT
Enter Control Bit0
0
LED is OFF
>>>
```



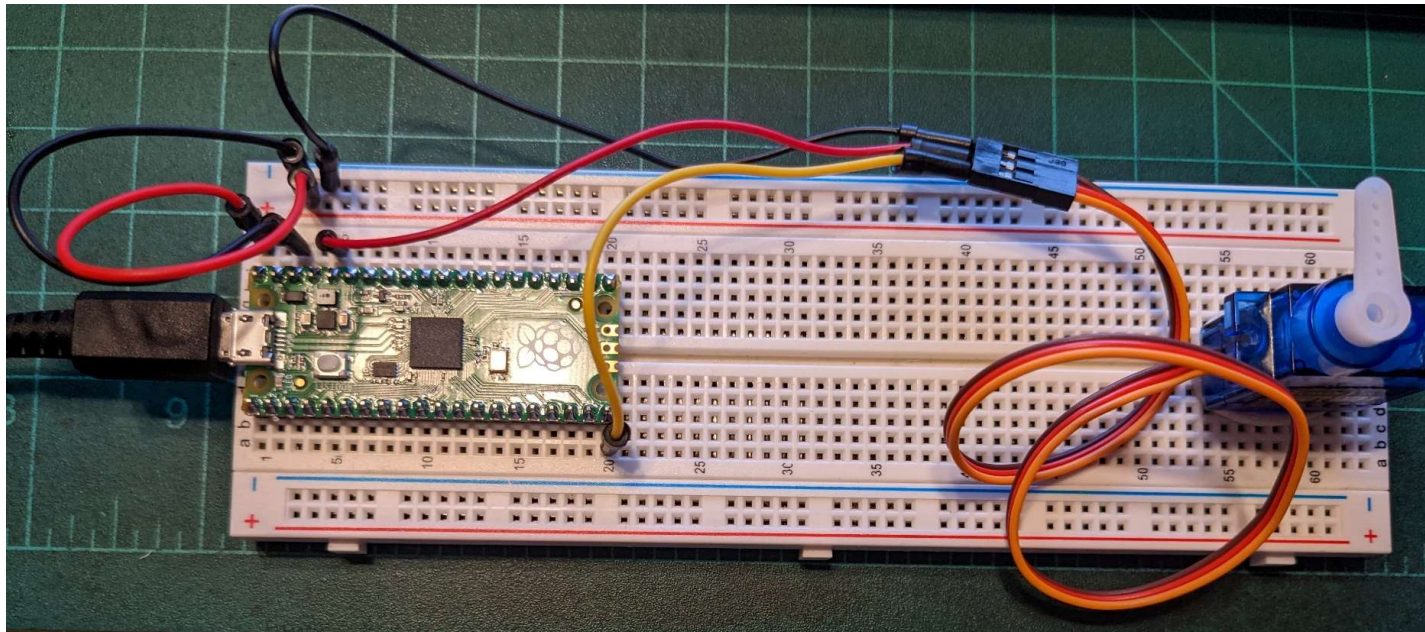
## Question 3



**In reviewing slide 19, identify the GPIO pin.**

- a) led**
- b) bit**
- c) 25**
- d) led(1)**

## Lab: Servo Motor Controller





## Lab: Servo Motor Controller. . .



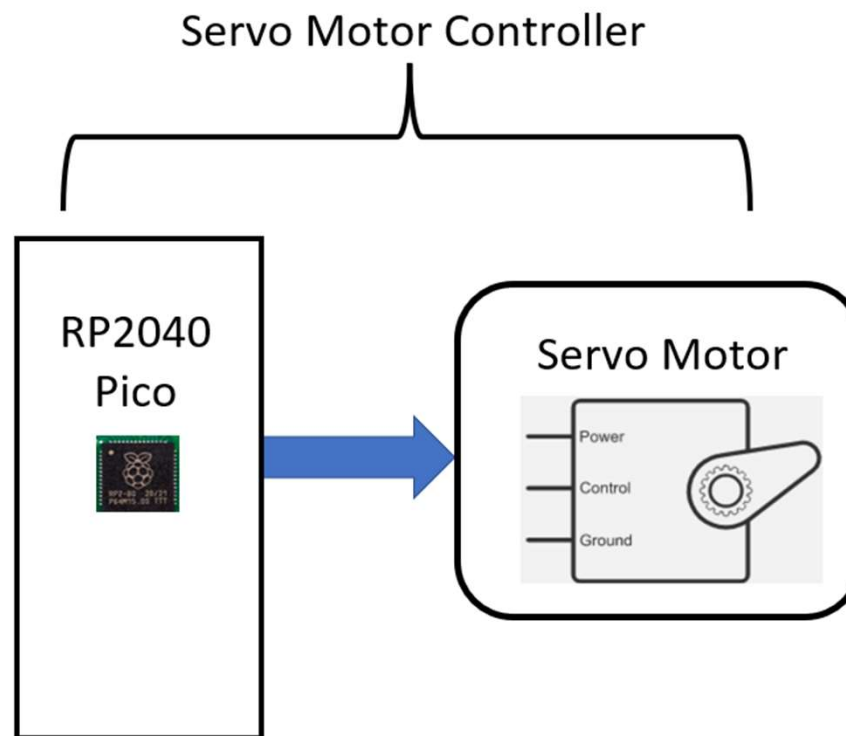
### Big IDEAS (Learning Objectives):

1. The participant will be able to wire a servo motor to an RP2040 microcontroller.
2. The participant will be able to create a servo motor controller code using MicroPython.
3. The participant will be able to test a servo motor controller using MicroPython.

## Lab: Servo Motor Controller. . .



The RP2040 microcontroller easily controls a Servo motor by providing the appropriate timed control pulse signals, power, and ground voltage rails!



Intelligent  
Motor  
Control

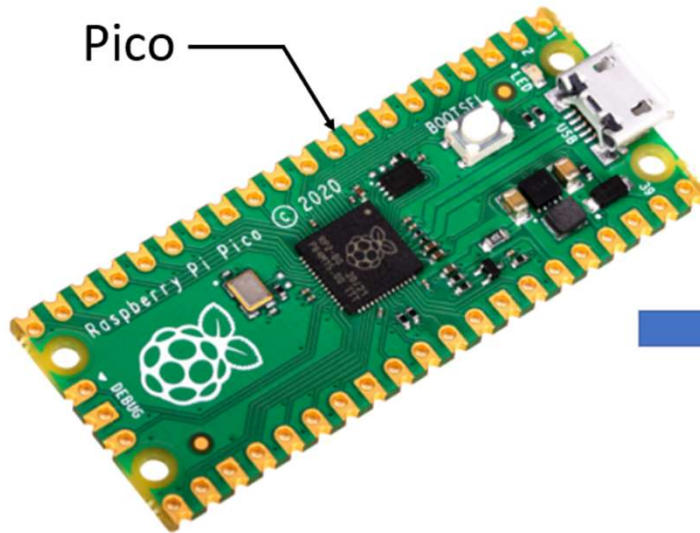


## Lab: Servo Motor Controller. . .



RP2040

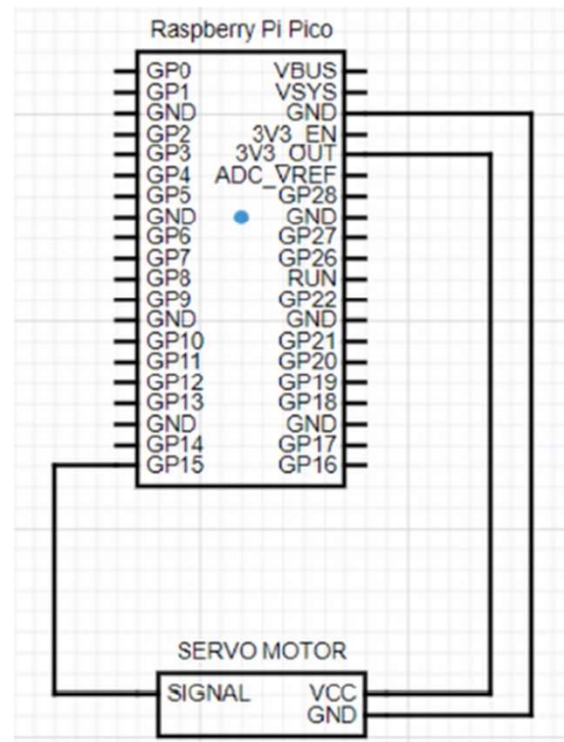
Pico



Servo Motor



## Lab: Servo Motor Controller. . .



Servo Motor Controller Circuit  
Schematic Diagram

## Question 4



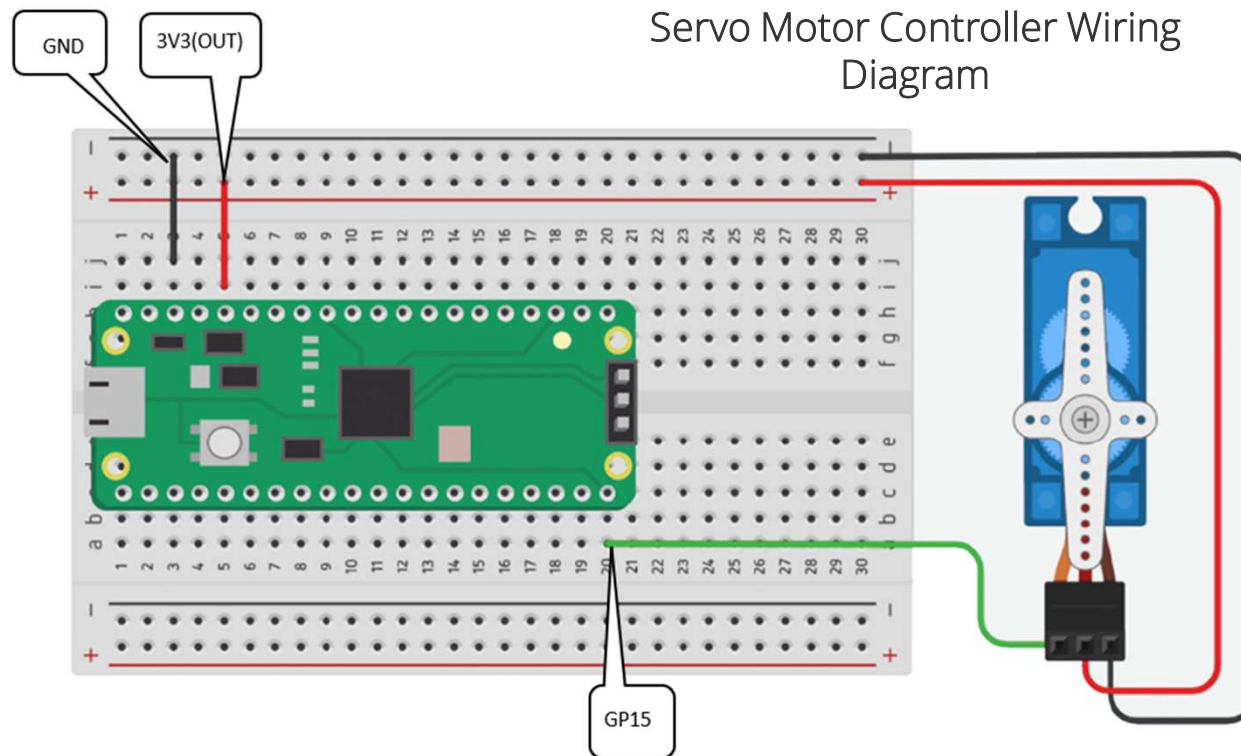
**Which GPIO pin on slide 25 provides the control signal for the servo motor?**

- a) GND**
- b) GP0**
- c) GP14**
- d) GP15**

## Lab: Servo Motor Controller. . .



Servo Motor Controller Wiring  
Diagram



## Lab: Servo Motor Controller. . .

To run the MicroPython Code, click the Run button

```
File Edit View Run Tools Help
servo_motor.py x
1 from machine import Pin, PWM
2 import utime
3
4 MID = 1500000
5 MIN = 1000000
6 MAX = 2000000
7
8 led = Pin(25, Pin.OUT)
9 pwm = PWM(Pin(15))
10
11 pwm.freq(50)
12 pwm.duty_ns(MID)
13
14 while True:
15     led.value(1)
16     pwm.duty_ns(MIN)
17     utime.sleep(1)
18     pwm.duty_ns(MID)
19     utime.sleep(1)
20     pwm.duty_ns(MAX)
21     led.value(0)
22     utime.sleep(1)
Shell x
MicroPython v1.19.1 on 2022-06-18; Raspberry Pi Pico with RP2040
Type "help()" for more information.
>>>
```

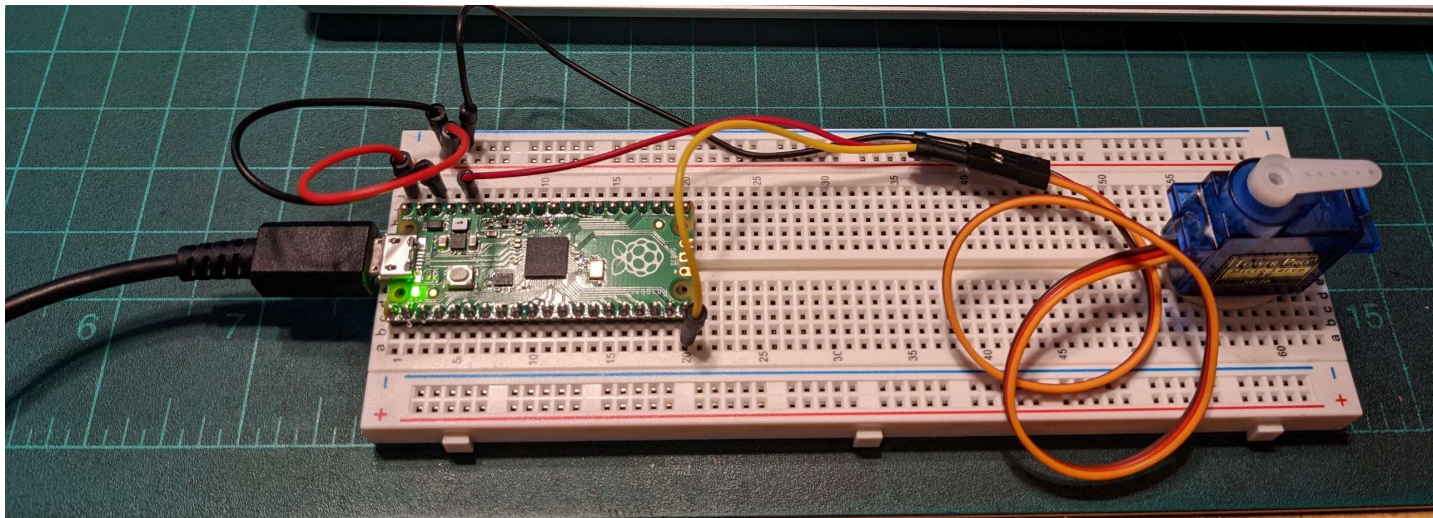


Thonny IDE



## Lab: Servo Motor Controller. . .

RP2040 Servo Motor Controller in  
Operation



Watch Video Clip  <https://youtu.be/lvQzayXIIfw>

## Question 5



**Which GPIO pin number is assigned to perform the pwm function on slide 28?**

- a) 25**
- b) 15**
- c) 50**
- d) none of the above**

# Thank you for attending

Please consider the resources below:

Adams, J. (2021, February 1). *Raspberry pi rp2040: Our microcontroller for the masses.*

<https://www.arm.com/blogs/blueprint/raspberry-pi-rp2040>

RP2040 Datasheet. (2022). RP2040 datasheet: A microcontroller by raspberry pi.

<https://datasheets.raspberrypi.com/rp2040/rp2040-datasheet.pdf>

Raspberry Pi Pico Resources: [Raspberry Pi Documentation - Raspberry Pi Pico and Pico W](#)



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Thank You

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