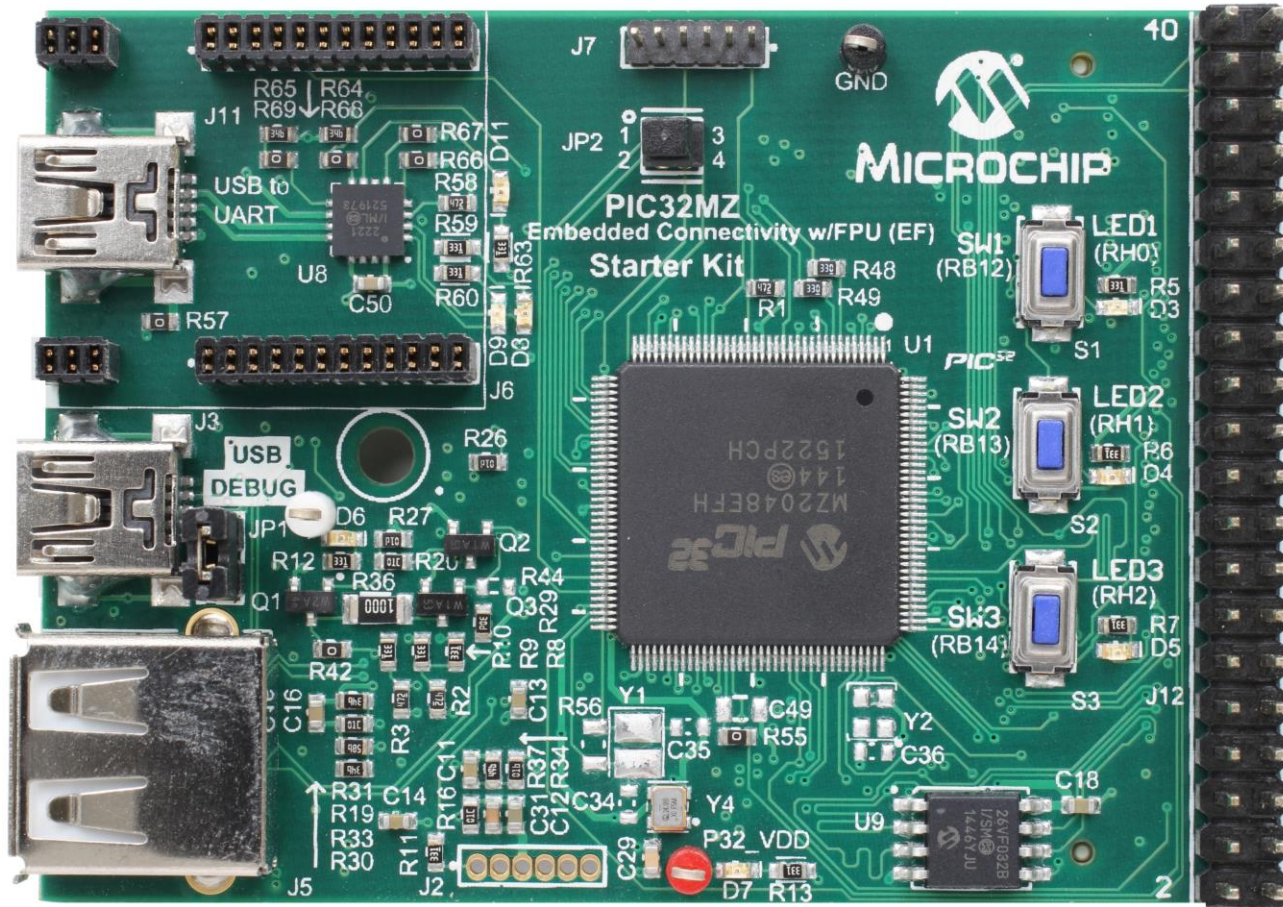


IoT Development Tools for PIC32



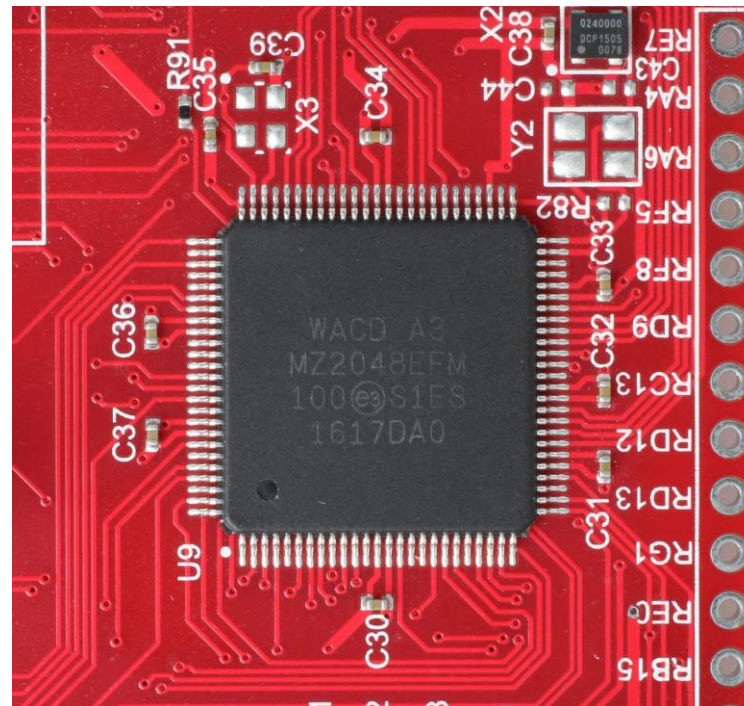
Curiosity PIC32MZ EF

January 31, 2018

FRED EADY

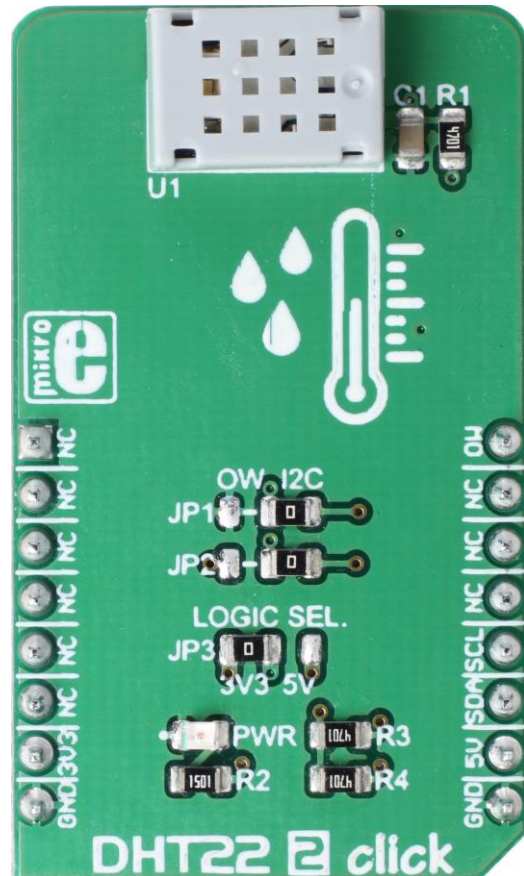
AGENDA

- **Curiosity PIC32MZ EF Hardware**
- **Blinking in Harmony**
- **Singing Out of Tune**
- **microSD click Project**
- **Double click – DHT22-2 click Project**
- **Buenas Tardes**

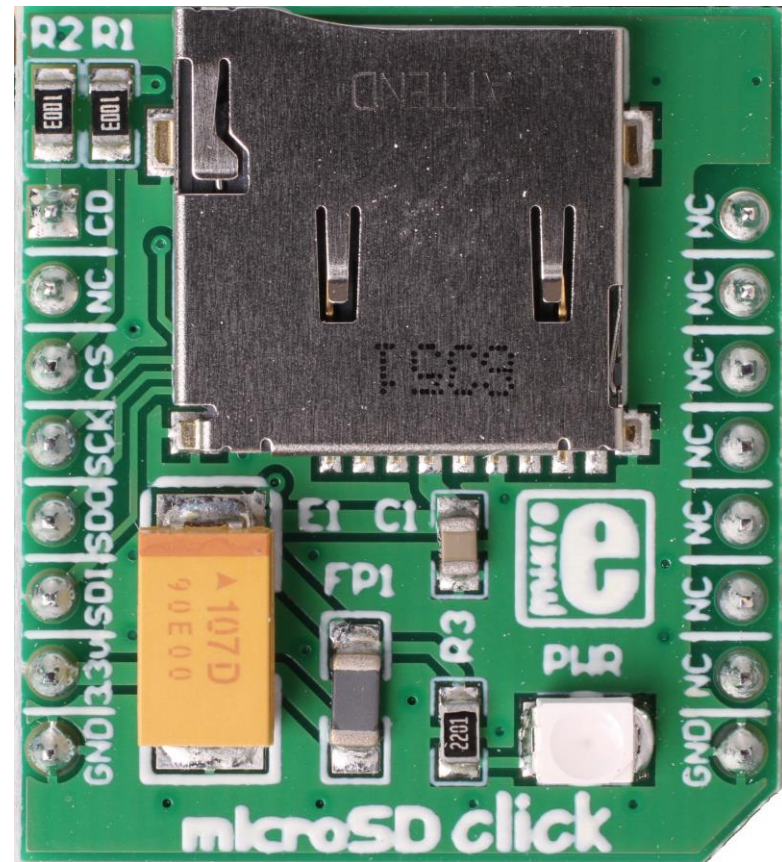


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Curiosity PIC32MZ EF Hardware – [click Part Numbers](#)



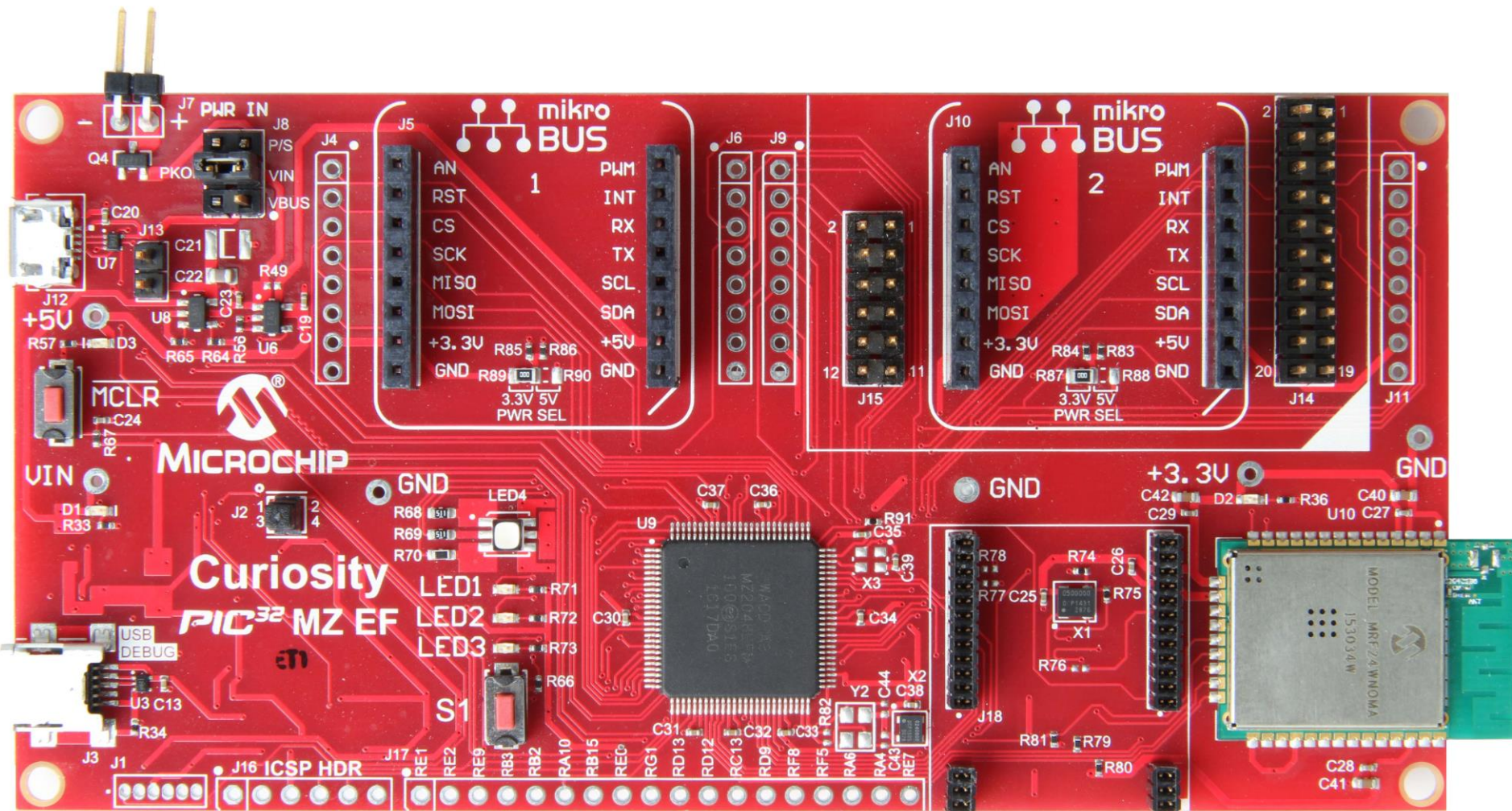
DHT22 2 CLICK
MIKROE-2818
1471-1886-ND



MICROSD CLICK STORAGE
MIKROE-924
1471-1303-ND

IoT Development Tools for PIC32

Curiosity PIC32MZ EF Hardware



IoT Development Tools for PIC32


Blinking in Harmony


New Project

Steps

1. Choose Project
2. **Name and Location**

Name and Location

Harmony Path: 


Project Location: 

Project Name:

Project Path:

Configuration Name:

Device Family: Target Device:

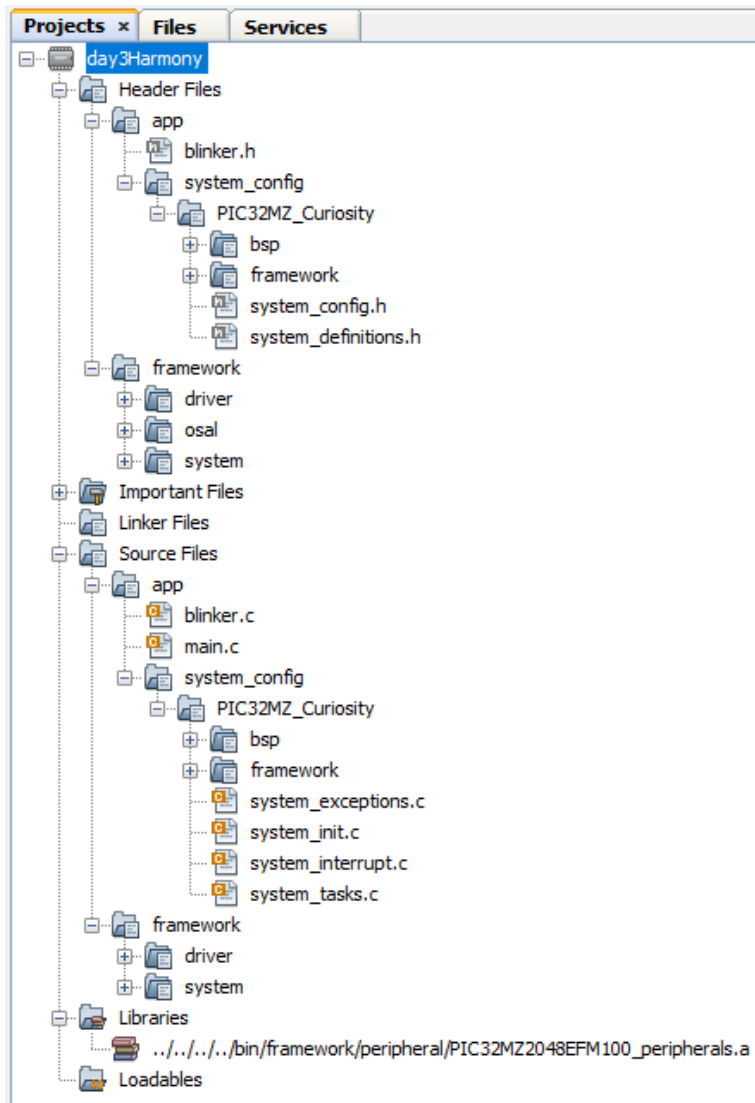
Target Board: 

Note: Press "Help" button for additional information.

< Back Next > Finish Cancel Help

IoT Development Tools for PIC32

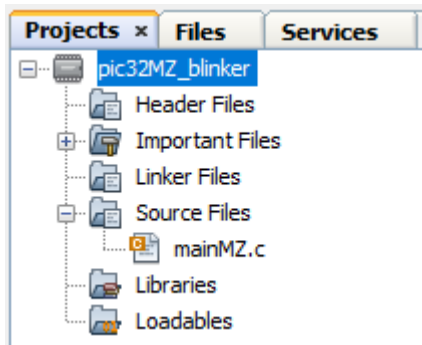
Blinking in Harmony



```
141 void BLINKER_Tasks ( void )
142 {
143
144     /* Check the application's current state. */
145     switch ( blinkerData.state )
146     {
147         /* Application's initial state. */
148         case BLINKER_STATE_INIT:
149         {
150             bool appInitialized = true;
151
152
153             if (appInitialized)
154             {
155                 blinkerData.hDelayTimer = SYS_TMR_DelayMS(BLINKER_DELAY);
156                 if (blinkerData.hDelayTimer != SYS_TMR_HANDLE_INVALID)
157                 { // Valid handle returned
158                     BSP_LEDOOn(BLINKER_LED);
159                     blinkerData.state = BLINKER_STATE_SERVICE_TASKS;
160                 }
161                 blinkerData.state = BLINKER_STATE_SERVICE_TASKS;
162             }
163             break;
164         }
165
166         case BLINKER_STATE_SERVICE_TASKS:
167         {
168             if (SYS_TMR_DelayStatusGet(blinkerData.hDelayTimer))
169             { // Single shot timer has now timed out.
170                 BSP_LEDToggle(BLINKER_LED);
171                 blinkerData.state = BLINKER_RESTART_TIMER;
172             }
173
174             break;
175         }
176
177         /* TODO: implement your application state machine.*/
178         case BLINKER_RESTART_TIMER:
179         { // Create a new timer
180             blinkerData.hDelayTimer = SYS_TMR_DelayMS(BLINKER_DELAY);
181             if (blinkerData.hDelayTimer != SYS_TMR_HANDLE_INVALID)
182             { // Valid handle returned
183                 blinkerData.state = BLINKER_STATE_SERVICE_TASKS;
184             }
185             break;
186         }
187     }
188 }
```


IoT Development Tools for PIC32

Singing Out of Tune



```

130 //Initialize TIMER2
131 T2CONCLR = 0xFFFF;           //Turn timer off - select PBCLK 1:1
132 T2CONSET = 0x0070;           //01110000 1:256 prescale
133 TMR2 = 0;                     //Clear timer register
134 PR2 = 0x0138;                //10mS @ 8MHz
135 //priority 4 sub priority 0 - bits <12:10> sub bits <9:8>
136 IPC2SET = 0x00001000; // 0000 0000 0000 0000 0001 0000 0000 0000
137 IFS0CLR = 0x00000200;
138 IEC0SET = 0x00000200;
139 T2CONSET = 0x8000;

```

```

86 //*****
87 /** SRAM VARIABLES
88 //*****
89 BYTE tmrTicks;
90 //*****
91 /** TIMER2 Interrupt Handler
92 /** it is set at priority level 4 with shadow register support
93 /** subpriority level 0
94 //*****
95 void __ISR_AT_VECTOR (_TIMER_2_VECTOR, IPL4SR) msl0Handler(void)
96 {
97     if(++tmrTicks == 100)
98     {
99         LATBINV = 0x0001;
100         tmrTicks = 0;
101     }
102     IFS0CLR = 0x00000200;
103 }

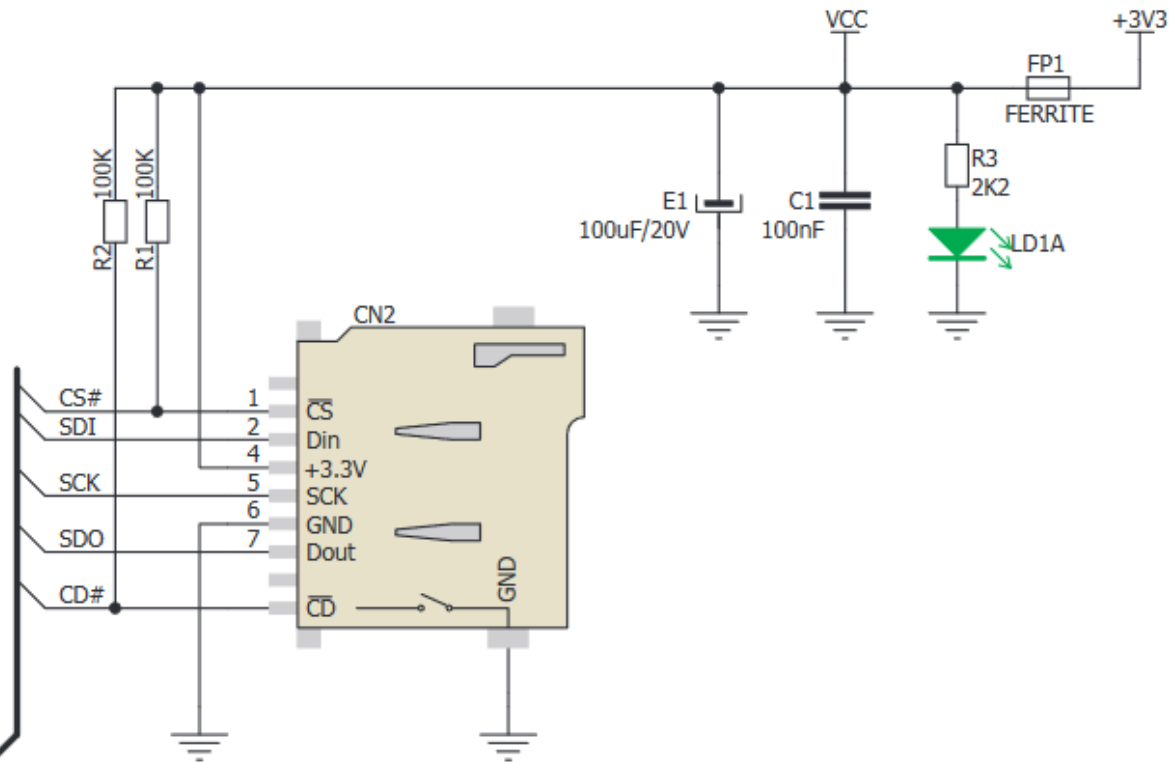
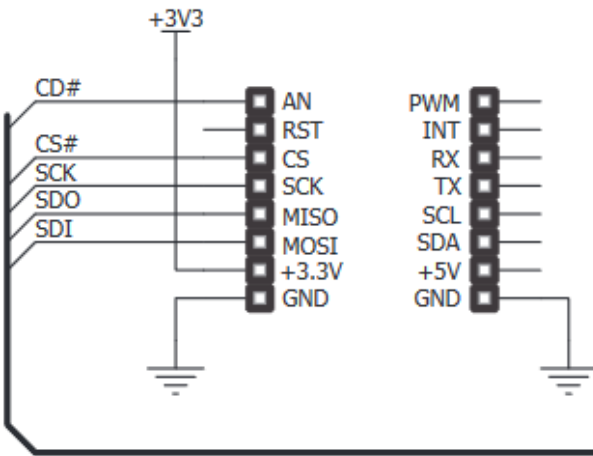
```



Presented by:

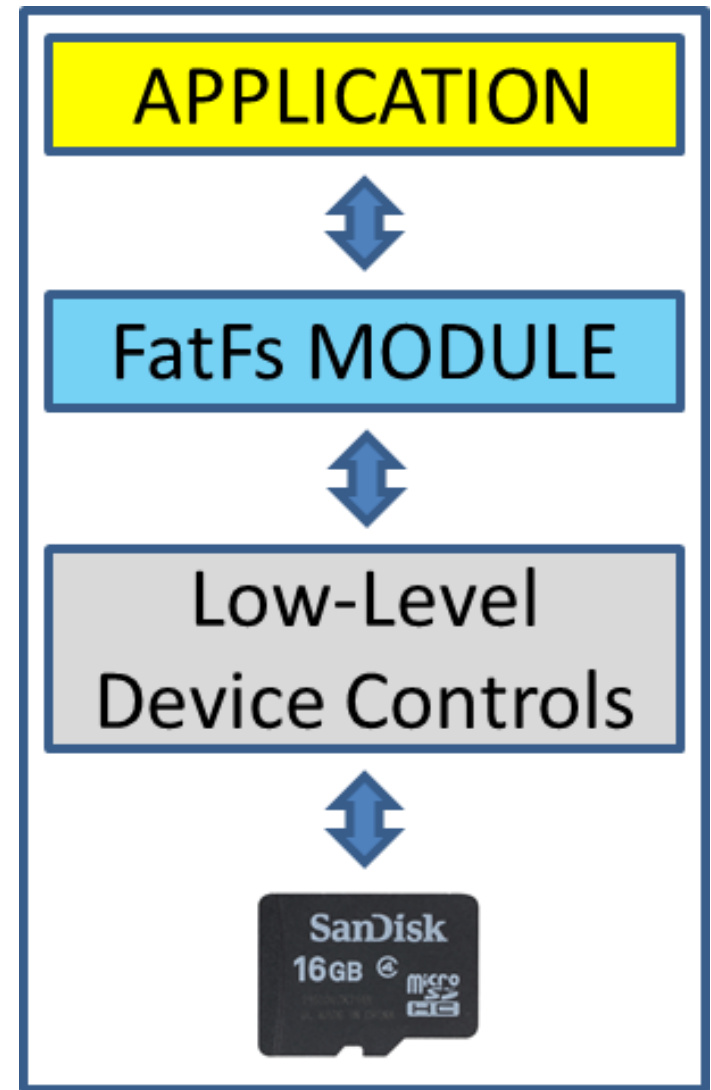
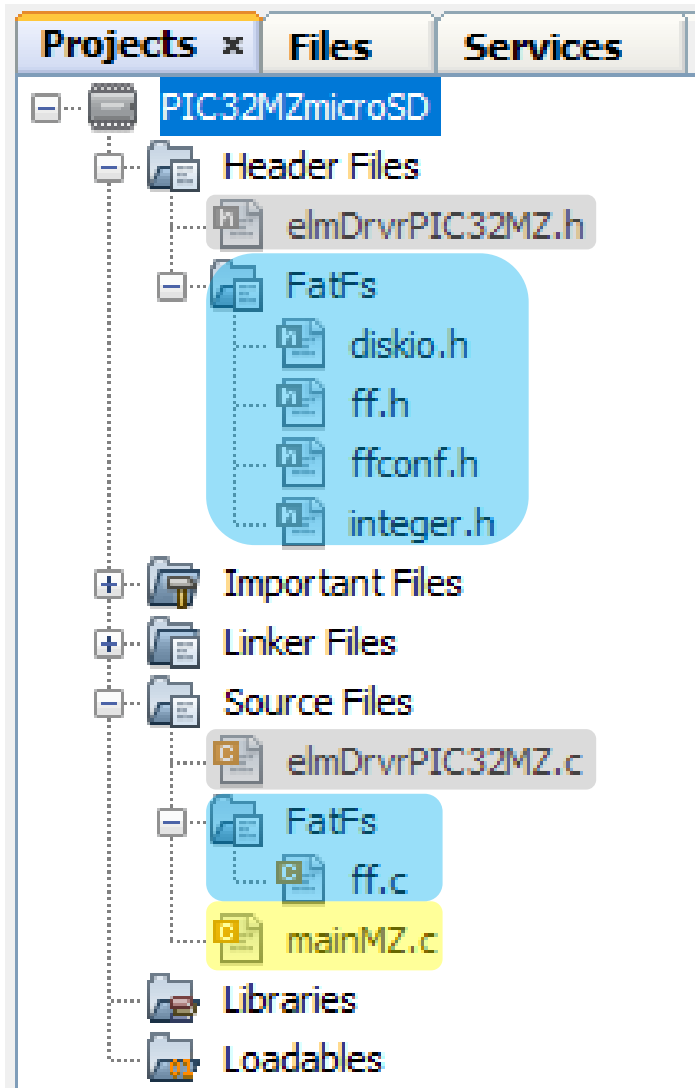
IoT Development Tools for PIC32

microSD click Project



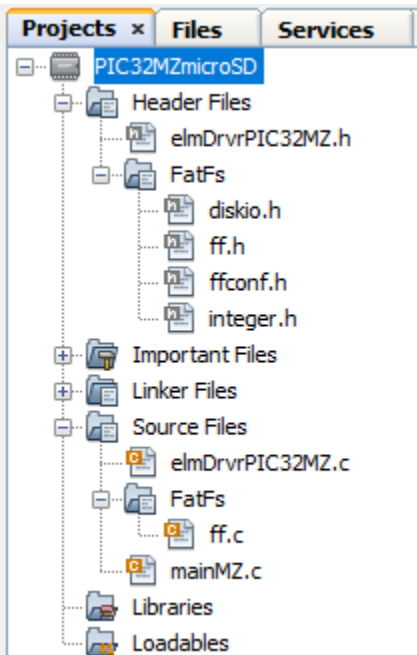
IoT Development Tools for PIC32

microSD click Project



IoT Development Tools for PIC32

microSD click Project



```

297 //*****
298 /** MAIN FUNCTION
299 //*****
300 int main (void)
301 {
302     FRESULT FOpenRes;
303     long accessmode;
304     char filename[] = "microSD.txt";
305     accessmode= (FA_CREATE_ALWAYS | FA_OPEN_ALWAYS | FA_CREATE_NEW | FA_WRITE | FA_READ);
306     char Buff[] = "IoT microSD Tools for PIC32MZ EF";
307     unsigned int bitesWritten=0;
308
309     init();
310     disk_initialize(0);
311     f_mount(&Fatfs, "", 0);
312     FOpenRes=f_open(&file1, filename, (BYTE)accessmode);
313     if (FOpenRes==FR_OK)
314     {
315         LED2ON;
316     }
317     FOpenRes=f_write(&file1, &Buff, sizeof(Buff), &bitesWritten);
318     f_close(&file1);    //close file
319     f_mount(NULL, "", 0); //unmount
320     if(bitesWritten)
321     {
322         LED3ON;
323     }
324     do{
325         ++scratch8;
326     }while(1);
327 }

```



MICROSD.TXT - Notepad

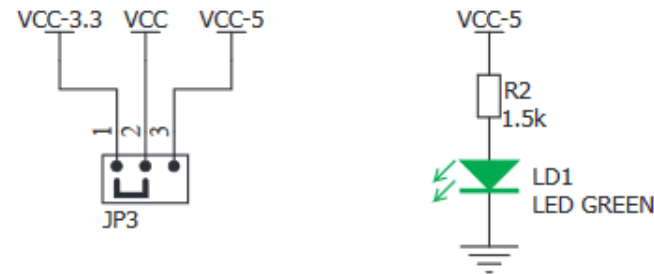
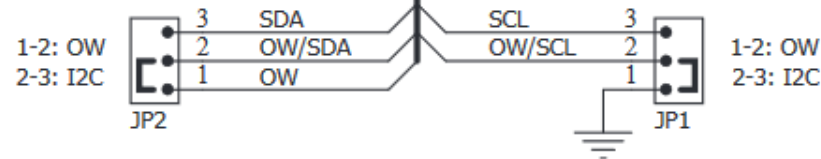
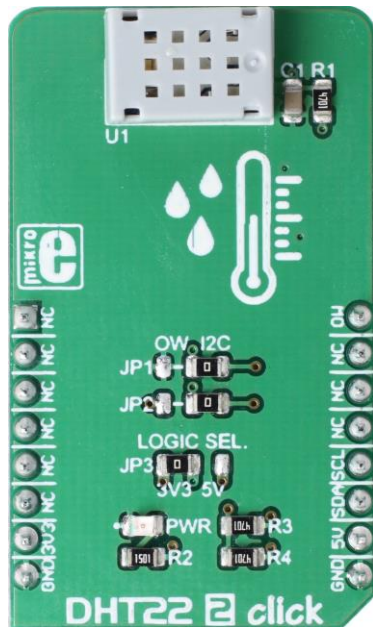
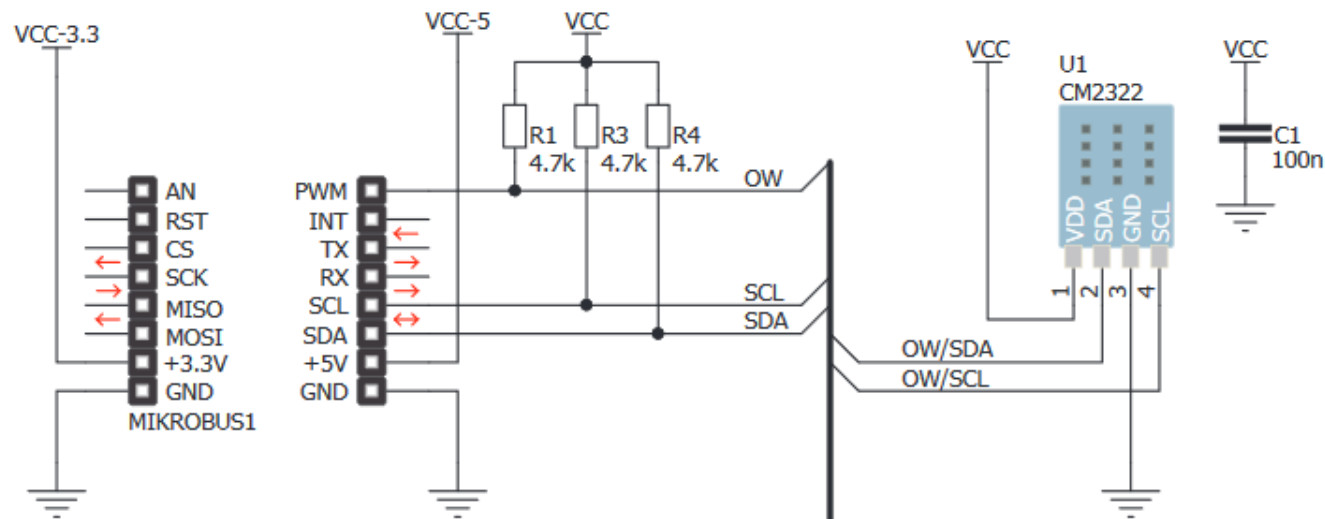
File Edit Format View Help

IoT microSD Tools for PIC32MZ EF



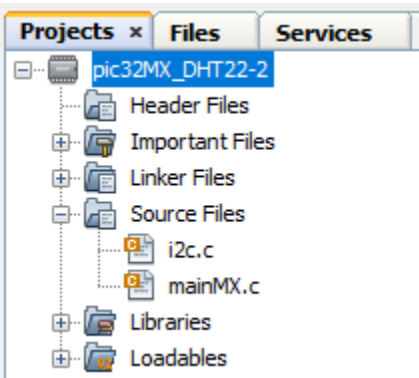
IoT Development Tools for PIC32

Double click – DHT22-2 click Project



IoT Development Tools for PIC32

Double click – DHT22-2 click Project



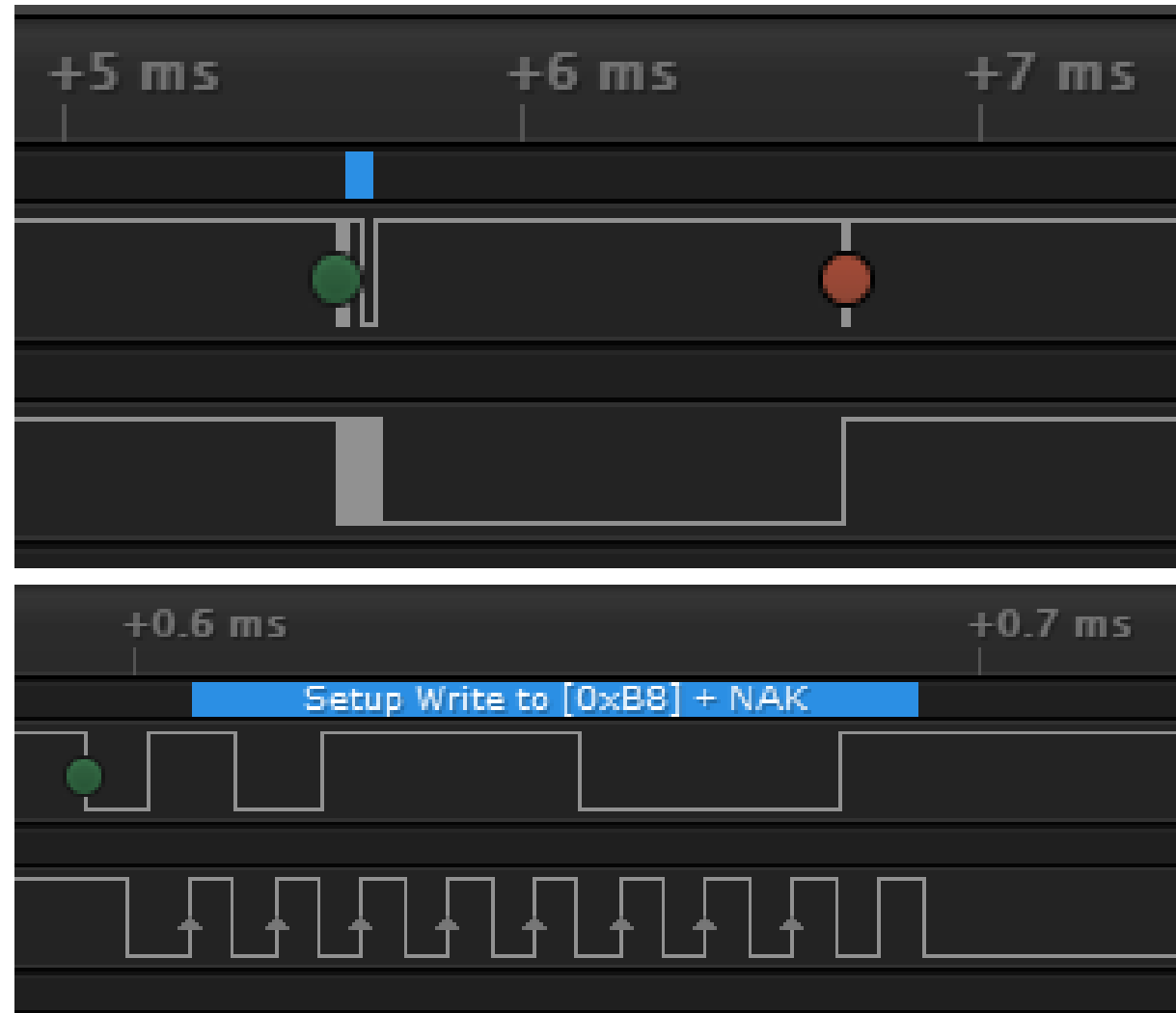
```
114 //*****  
115 /* MAIN FUNCTION  
116 //*****  
117 void main(void)  
118 {  
119     initMX();  
120     txBuf[0] = 0x03;  
121     txBuf[1] = 0x00;  
122     txBuf[2] = 0x04;  
123     clickOFF;  
124     i2cInit();  
125     ctDelaysms(500);  
126     clickON;  
127     do{  
128         ctDelaysms(1000);  
129         i2cStart();  
130         i2cSendByte(i2cAddrW);  
131         ctDelaysms(1);  
132         i2cStop();  
133         ctDelaysms(100);  
134         i2cWriteDHTRegs(i2cAddrW, txBuf, 3);  
135         ctDelaysms(100);  
136         i2cReadDHTRegs(i2cAddrR, rxBuf, 8);  
137         ctDelaysms(1000);  
138     }while(1);  
139 }
```



IoT Development Tools for PIC32

Double click – DHT22-2 click Project

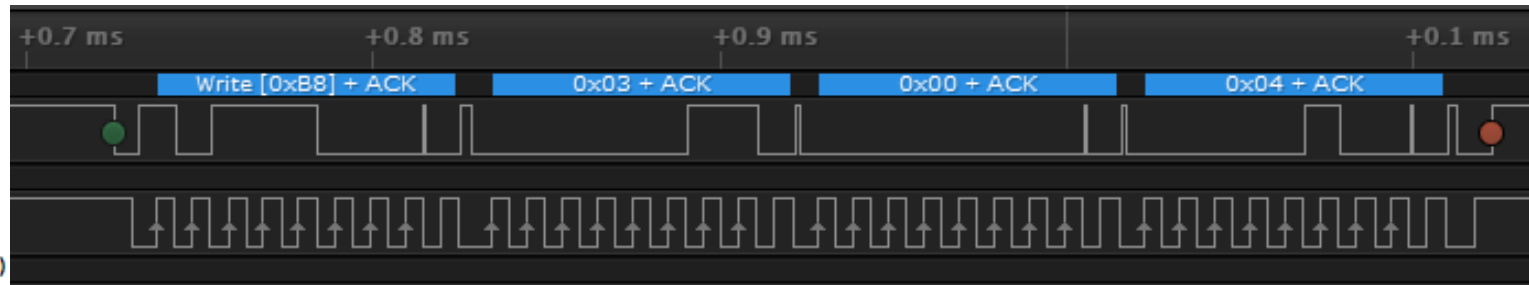
```
114 //*****
115 /* MAIN FUNCTION
116 //*****
117 void main(void)
118 {
119     initMX();
120     txBuf[0] = 0x03;
121     txBuf[1] = 0x00;
122     txBuf[2] = 0x04;
123     clickOFF;
124     i2cInit();
125     ctDelaysms(500);
126     clickON;
127     do{
128         ctDelaysms(1000);
129         i2cStart();
130         i2cSendByte(i2cAddrW);
131         ctDelaysms(1);
132         i2cStop();
133         ctDelaysms(100);
134         i2cWriteDHTRegs(i2cAddrW,txBuf,3);
135         ctDelaysms(100);
136         i2cReadDHTRegs(i2cAddrR,rxBuf,8);
137         ctDelaysms(1000);
138     }while(1);
139 }
```



IoT Development Tools for PIC32

Double click – DHT22-2 click Project

```
114 //*****
115 /** MAIN FUNCTION
116 //*****
117 void main(void)
118 {
119     initMX();
120     txBuf[0] = 0x03;
121     txBuf[1] = 0x00;
122     txBuf[2] = 0x04;
123     clickOFF;
124     i2cInit();
125     ctDelaysms(500);
126     clickON;
127     do{
128         ctDelaysms(1000);
129         i2cStart();
130         i2cSendByte(i2cAddrW);
131         ctDelaysms(1);
132         i2cStop();
133         ctDelaysms(100);
134         i2cWriteDHTRegs(i2cAddrW,txBuf,3);
135         ctDelaysms(100);
136         i2cReadDHTRegs(i2cAddrR,rxBuf,8);
137         ctDelaysms(1000);
138     }while(1);
139 }
```



IoT Development Tools for PIC32

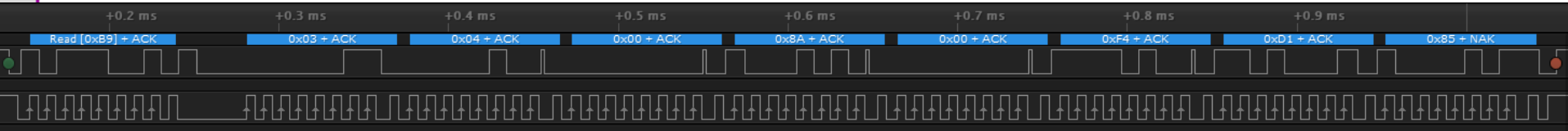
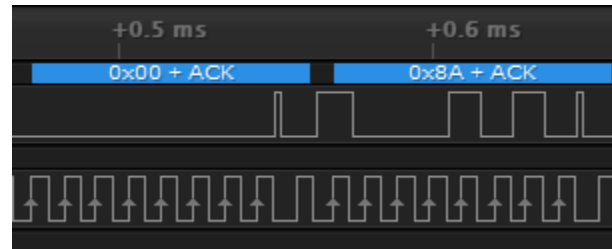
Double click – DHT22-2 click Project

```

114 //*****
115 /** MAIN FUNCTION
116 //*****
117 void main(void)
118 {
119     initMX();
120     txBuf[0] = 0x03;
121     txBuf[1] = 0x00;
122     txBuf[2] = 0x04;
123     clickOFF;
124     i2cInit();

```

Humidity = 13.8%

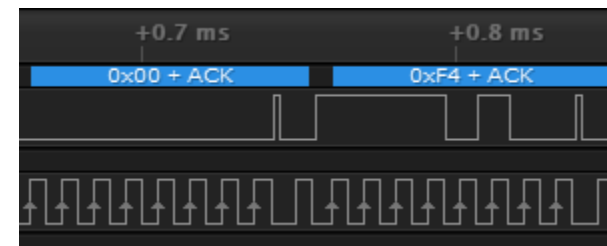


```

130 i2cSendByte(i2cAddrW);
131 ctDelaysms(1);
132 i2cStop();
133 ctDelaysms(100);
134 i2cWriteDHTRegs(i2cAddrW, txBuf, 3);
135 ctDelaysms(100);
136 i2cReadDHTRegs(i2cAddrR, rxBuf, 8);
137 ctDelaysms(1000);
138 }while(1);
139 }

```

Temperature = 24.4° C



IoT Development Tools for PIC32

Buenas Tardes

