# Embedded System Design Techniques™

# **Building Your Own Internet Connected PLC**

Class 1: PLC Fundamentals

April 23<sup>rd</sup>, 2018 Jacob Beningo





## **Course Overview**

#### **Topics:**

- PLC Fundamentals
- Designing a PLC
- PLC Software Design Part 1
- PLC Software Design Part 2
- PLC Application Design





# The Lecturer – Jacob Beningo



Jacob Beningo
Principal Consultant

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**EDN**: Embedded Basics

\*ARM\*Connected Community

#### **Consulting**

- Advising
- Coaching
- Content
- Consulting
- Training



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#### **Jacobs CEC Courses**

CEC 2013 – 2015

CEC 2016 - 2017

**CEC 2018** 

Fundamentals of Embedded Software (2013)

Mastering the Software Design Cycle (2014)

Python for Embedded Systems(2014)

Software Architecture Design (2014)

Baremetal C (2015)

Mastering the ARM Cortex-M Processor (2015)

Writing Portable and Robust Firmware in C (2015)

Design Patterns and the Internet (2015)

Bootloader Design for MCUs (2016)

Rapid Prototyping w/ Micro Python (2016)

Debugging (2016)

Professional Firmware (2016)

API's and HAL's February 2017

Baremetal to RTOS
April 2017

Designing IoT Sensor Nodes
July 2017

From C to C++ October 2017 Connecting Edge Devices (March 2018)

Building an IoT Connected PLC (April 2018)

Side Topics 2018

**Bootloader Design** 

**RTOS Workshop** 

**Debugging Techniques** 





#### Session Overview

- Introduction
- PLC Ladder Logic
- PLC Ladder Execution





#### **Definition:**

A Programmable Logic Controller (PLC) is a ruggedized computer used to automate a specific process in an industrial application.

i.e. Assembly lines, amusement rides, electrical automation





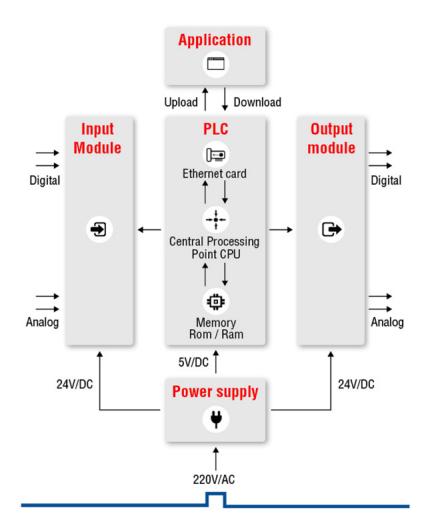
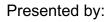


Image Source: unitronicspic.com

















Ladder logic (LD) is a visual schematic like language that incorporates the machine logic on how the controller will be behave.

- IEC 61131-3 defines the PLC Logic symbols
- Designed for technicians
- A useful reference for PLC design is plcacademy.com



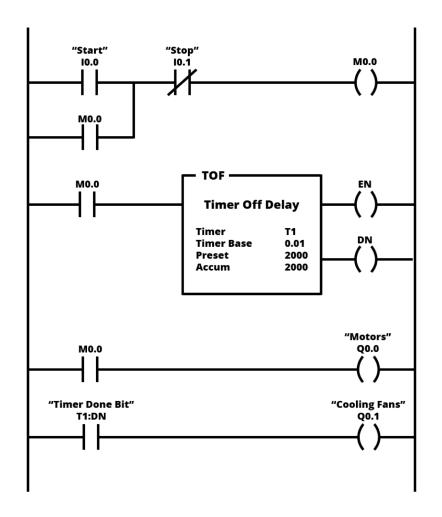
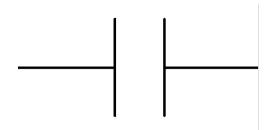


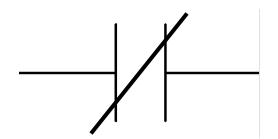
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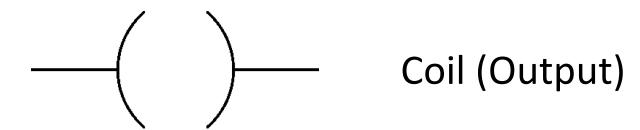


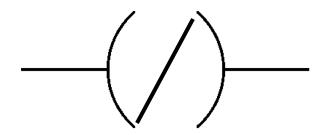
Normally Open Contact (if closed)



Normally Closed Contact (if open)







Coil Negate (Output)



How is the ladder executed?

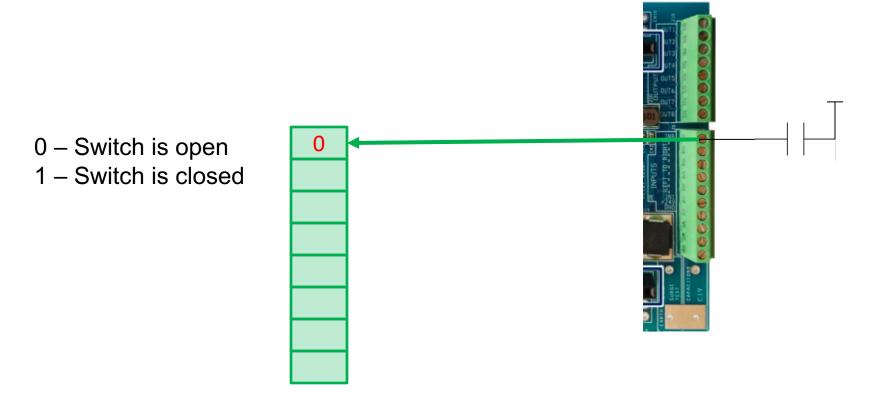
- 1) Inputs are scanned
- 2) Logic is executed
- 3) Outputs are set
- 4) Other activities are completed
- 5) Repeat

Typical scan time is ~ 1 ms



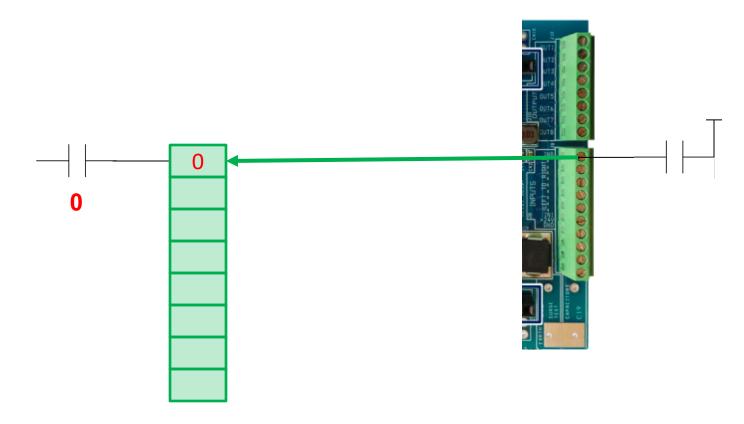


1) Scan the inputs



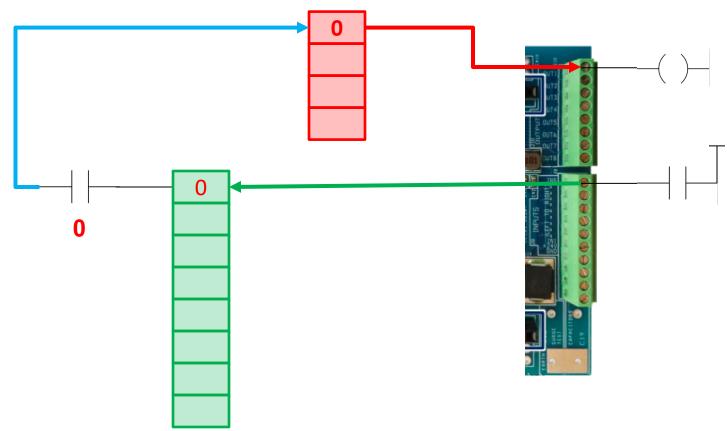


#### 2) Execute the Logic

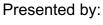


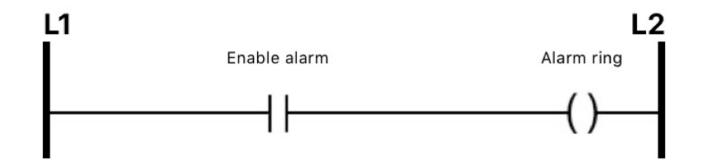


#### 3) Set the outputs





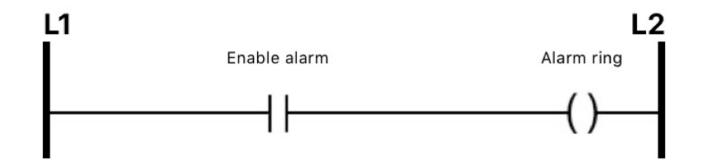




#### **Execution Sequence**

- 1) If Enable alarm is closed, input is 1
- 2) Output will be set to 1

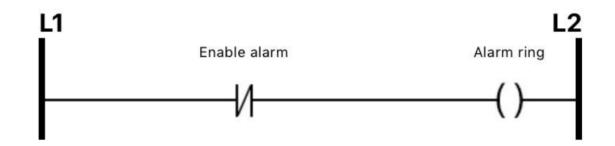




#### **Execution Sequence**

- 1) If Enable alarm is open, input is 0
- 2) Output will be set to 0

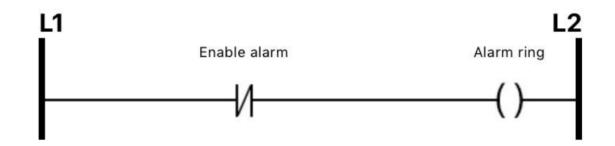




#### **Execution Sequence**

- 1) If Enable alarm is closed, input is 0
- 2) Output will be set to 0

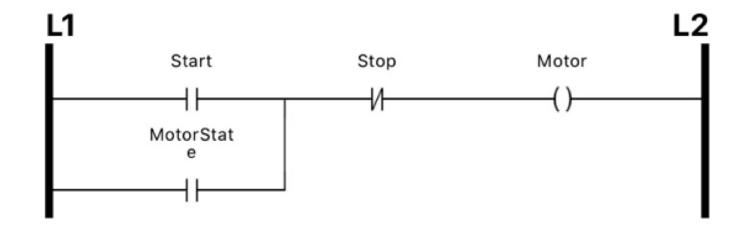




#### **Execution Sequence**

- 1) If Enable alarm is open, input is 1
- 2) Output will be set to 1







## What You will need ...

Nucleo-401RE

X-Nucelo-IDW01M01 X-Nucelo-PLC01A1



X-Nucleo-OUT01A1



Power Supply



A light snack ...











## Additional Resources

- Download Course Material for
  - C/C++ Doxygen Templates
  - Example source code
  - Blog
  - YouTube Videos
- Embedded Bytes Newsletter
  - <a href="http://bit.ly/1BAHYXm">http://bit.ly/1BAHYXm</a>



From <u>www.beningo.com</u> under

- Blog > CEC - Building Your own Internet Connected PLC

