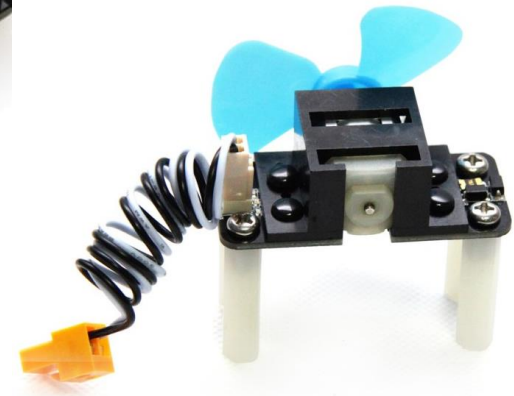
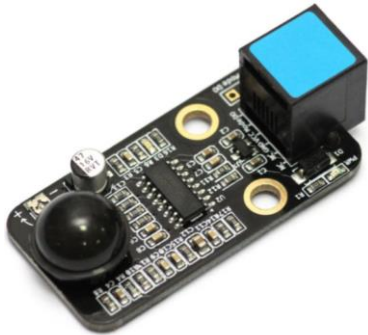


Human Inputting Devices for DC Motor Control

Class 2: Semiconductor Input Devices



July 25, 2017
Don Wilcher

Semiconductor Input Devices

Agenda

- Semiconductor Sensor Basics
- The inner workings of a PIR Sensor
- The inner workings of an Ultrasonic Sensor
- Hands-On Project: A Smart Fan

Semiconductor Sensor Basics



- Often referred to as transducers.
- Semiconductor Sensors provide a link in integrating industrial control systems.
- They convert mechanical, magnetic, thermal, electrical, optical, and chemical variations into electrical voltage, and current signals.
- They have no moving parts.

Semiconductor Sensor Basics...



- They're replacing electromechanical transducers because of
 - a) fast detection switching speeds
 - b) increase operating life.
- Semiconductor Sensors are at the center of Industry 4.0 (Industrial Internet of Things).
 - a) Data Analytics and Machine Learning
 - b) Predictive Maintenance

Semiconductor Sensor Basics...



Examples:

Semiconductor Sensors

Hall Effect Sensor



Accelerometer



Proximity Sensor (IR Optical)



Light Sensor(Photo-transistor)



Ultrasonic Sensors



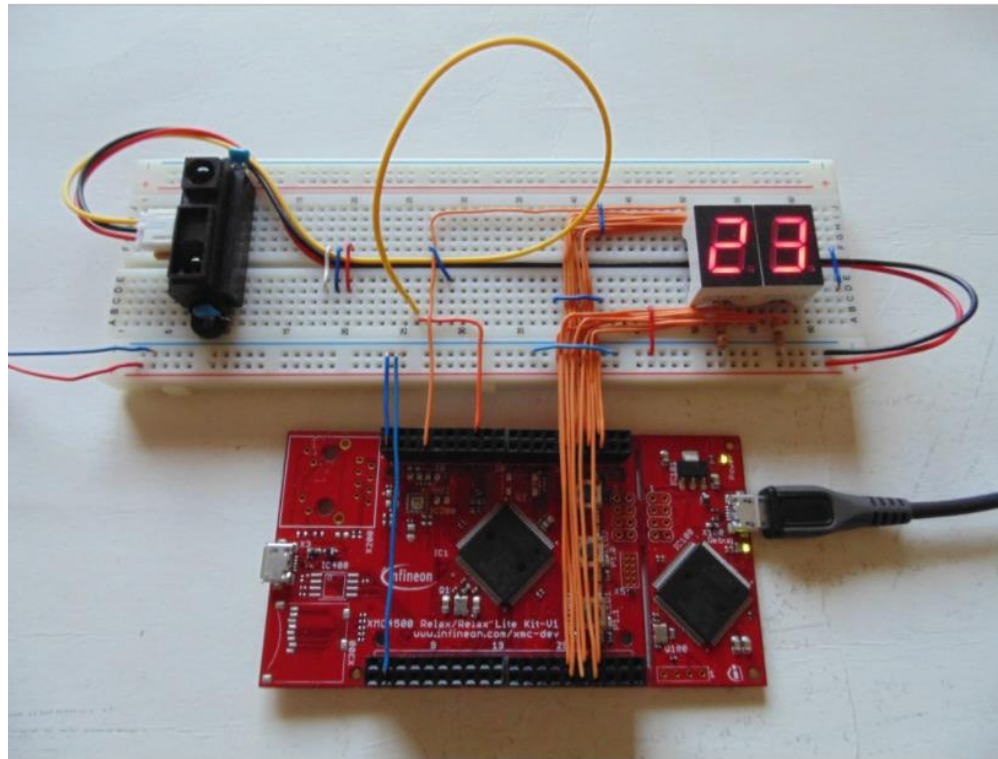
Presented by:

Semiconductor Sensor Basics...



Example Project:

Distance Sensor with 2 Digit LED Display.



Source:

<http://usgroup.eu/activities/infineon/dave3-tutorials/proximity-sensor/>

Semiconductor Sensor Basics...



Example Project:

A Simple and Cheap Dark-Detecting LED Circuit



Source:

<http://www.evilmadscientist.com/2007/a-simple-and-cheap-dark-detecting-led-circuit/>

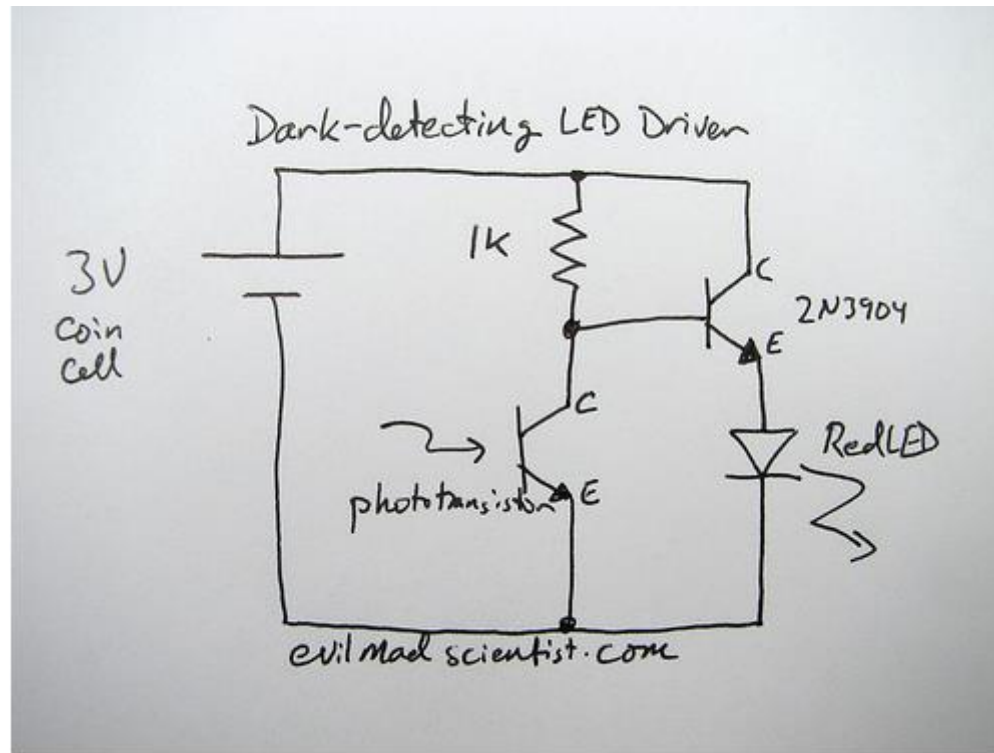
Semiconductor Sensor Basics...



Example Project:

A Simple and Cheap Dark-Detecting LED Circuit...

Circuit Schematic Diagram



Source:

<http://www.evilmadscientist.com/2007/a-simple-and-cheap-dark-detecting-led-circuit/>

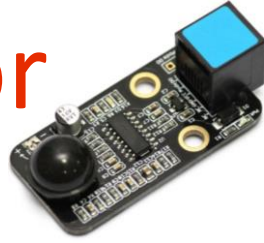
Question 1

Semiconductor sensors are often referred to as

_____.

- a) Control devices
- b) Detection devices
- c) Transducers
- d) None of the above

The inner workings of a PIR sensor

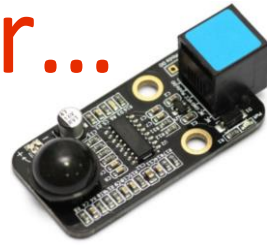


- **PIR sensors allow you**
 - a) to sense motion.
 - b) to detect whether a human has moved in or out of the sensor's range.
- **PIR sensors**
 - a) are small.
 - b) are inexpensive.
 - c) are low-power.
 - d) are easy to use.
 - e) and don't wear out.

Source:

<https://cdn-learn.adafruit.com/downloads/pdf/pir-passive-infrared-proximity-motion-sensor.pdf>

The inner workings of a PIR sensor...



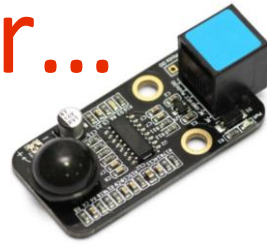
They are often referred to as PIR, "Passive Infrared", "Pyroelectric", or "IR motion" sensors.



Source:

<https://cdn-learn.adafruit.com/downloads/pdf/pir-passive-infrared-proximity-motion-sensor.pdf>

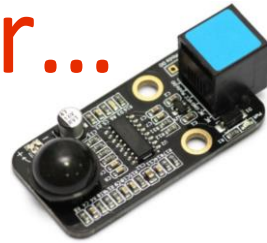
The inner workings of a PIR sensor...



What is Pyroelectricity?

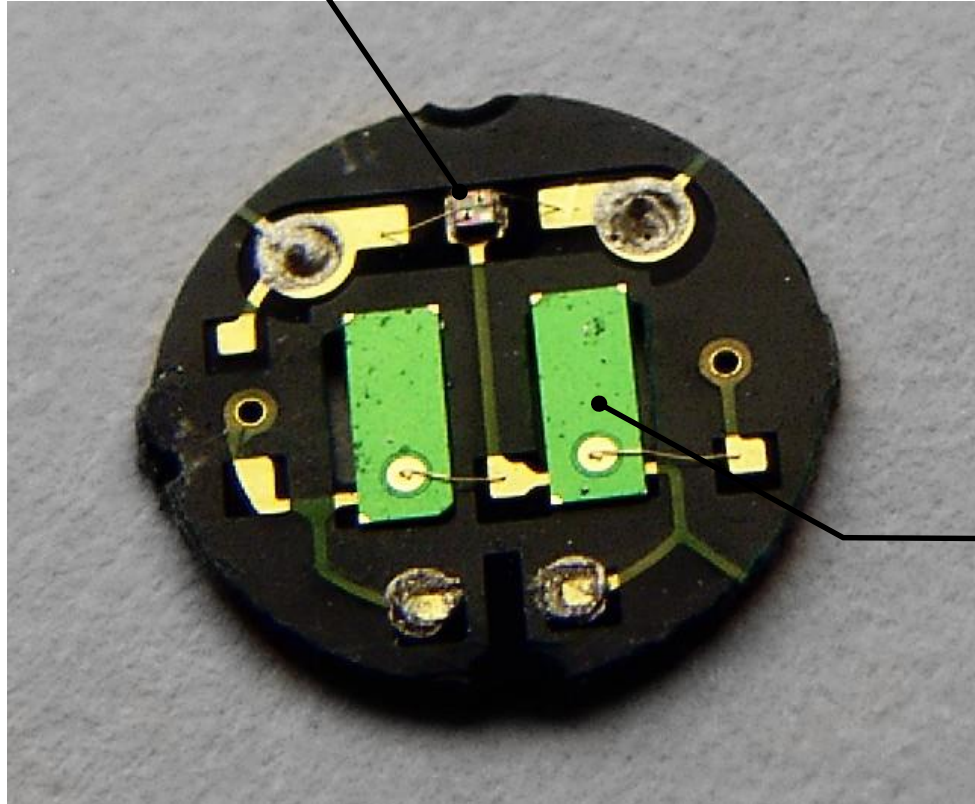
- Certain types of crystals are naturally electrically polarized.
- They contain a large electric field.
- Can be seen as one side of a triangle where each corner can be represented in three energy states:
 - a) kinetic
 - b) electrical
 - c) thermal

The inner workings of a PIR sensor...



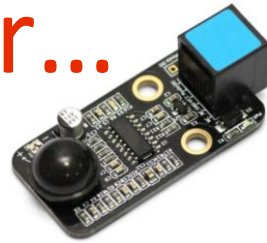
Polarized
Pyroelectric
crystal

Pyroelectric sensor: major parts



Metal film
electrode,
typical

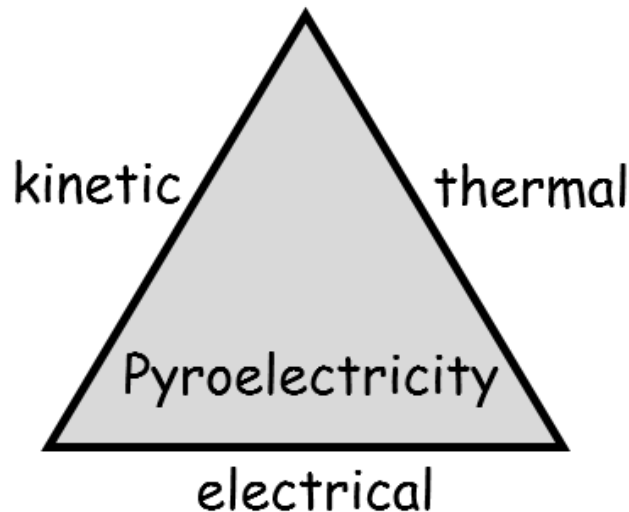
The inner workings of a PIR sensor...



Visualizing Piezoelectricity as a triangle

Piezoelectric effect = electrical + kinetic $\longrightarrow$ no heat

Pyroelectricity = electrical + thermal $\longrightarrow$ no kinetic energy

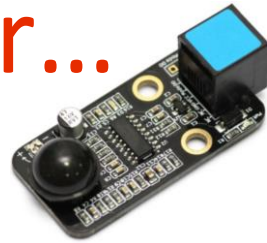


Question 2

In slide 8, what type of transistor driver is used to switch the LED on or off?

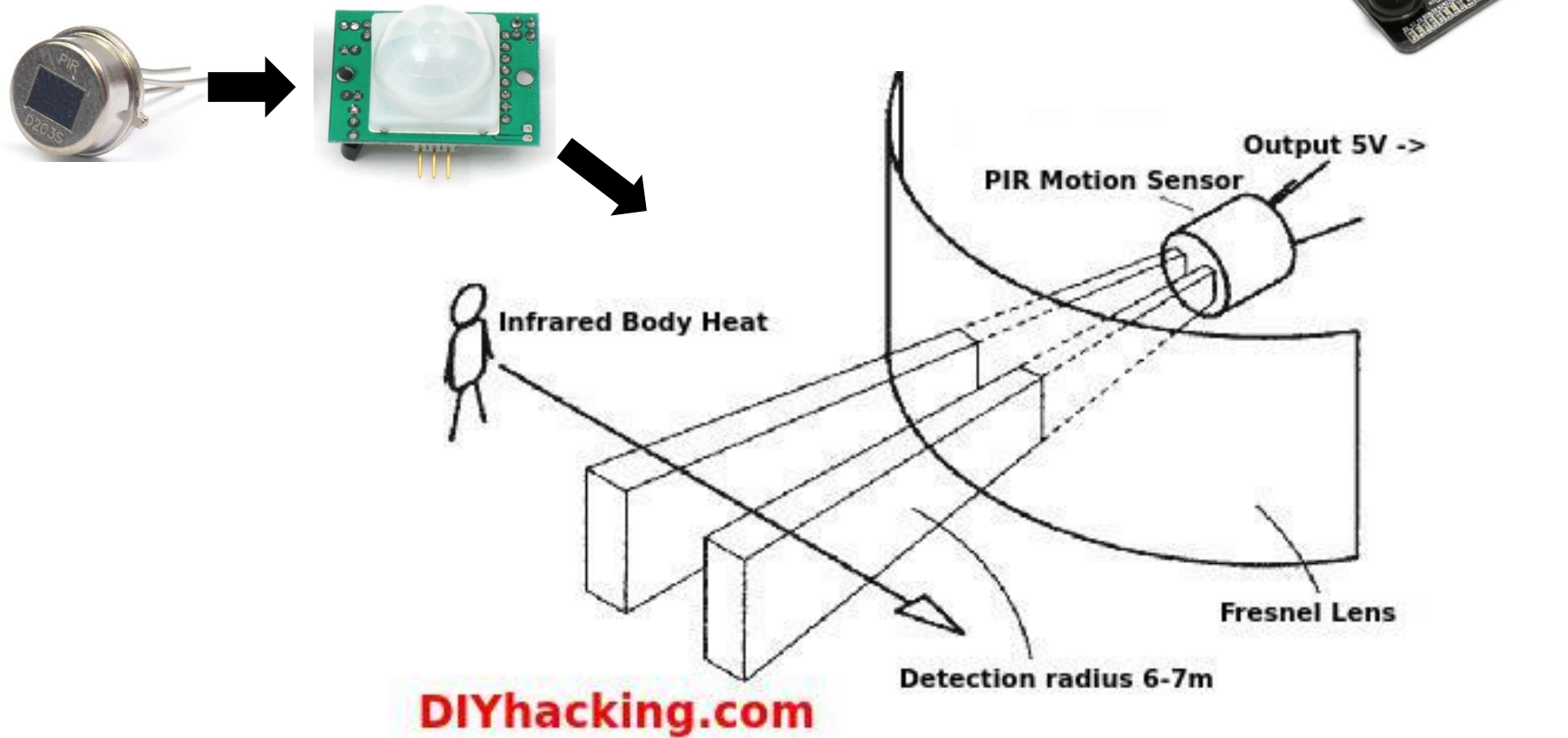
- a) Low side driver
- b) High side driver
- c) Darlington
- d) None of the above

The inner workings of a PIR sensor...



- **Sensor is split into two halves.**
 - a) Looking to detect motion change.
 - b) Not concern about average IR levels.
- **The two sensor halves are wired**
 - a) to cancel detection motion change
 - b) to swing the output signal high or low based on more or less IR radiation detected.

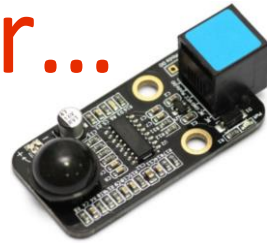
The inner workings of a PIR sensor...



Source:

<https://diyhacking.com/pir-motion-sensor-automate-home/>

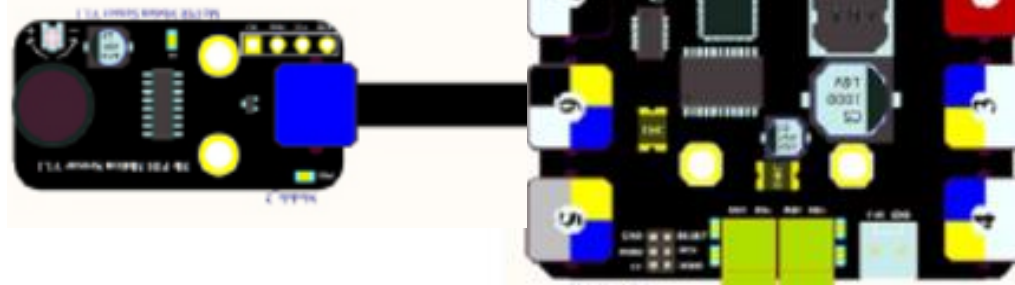
The inner workings of a PIR sensor...



Testing a Me PIR Motion Sensor:

Me Orion

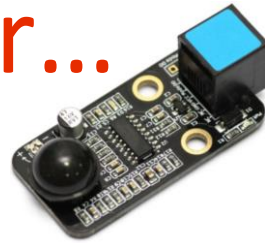
Me PIR Motion Sensor



Source:

<http://www.makeblock.com/me-pir-motion-sensor>

The inner workings of a PIR sensor...



Me Orion- Me PIR Motion Sensor Test Code

```
#include "MeOrion.h"
#include <Wire.h>
#include <SoftwareSerial.h>

MePIRMotionSensor myPIRSensor(PORT_6);

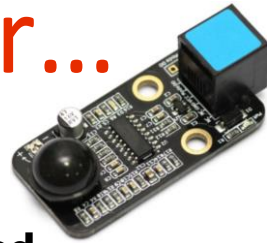
void setup( )
{
  Serial.begin(9600);
}

void loop() {
  Serial.print("PIR Motion values=");
  Serial.println(myPIRSensor.isHumanDetected());
  delay(100);
}
```

Source:

<http://www.makeblock.com/me-pir-motion-sensor>

The inner workings of a PIR sensor...



Me Orion- Me PIR Motion Sensor in operation. The value = 1, object detected.

COM4

```
PIR Motion values=1  
PIR Motion values=1  
PIR Motion values=0  
PIR Motion values=0  
PIR Motion values=0  
PIR Motion values=1  
PIR Motion values=1  
PIR Motion values=1  
PIR Motion values=1  
PIR Motion values=0  
PIR Motion values=0  
PIR Motion values=0  
PIR Motion values=0  
PIR Motion values=1  
PIR Motion values=1  
PIR Motion values=1  
PIR Motion values=1  
PIR Motion values=1  
PIR Motion values=1  
PIR Motion values=1  
PIR Motion values=1  
PIR Motion values=0  
PIR Motion values=0
```

Serial Monitor Output

The inner workings of an Ultrasonic Sensor



An ultrasonic sensor

- is a solid state sensor that can detect the presence of an object by:
 - a) emitting and receiving high frequency sound waves.
- high frequency sound waves are typically in the 200KHz range.
- can be used to monitor the level in a tank.

Source:

[Electrical Motor Controls for Integrated Systems, 5th ed, G.J. Rockis, G.A. Mazur](#)

The inner workings of an Ultrasonic Sensor...



An ultrasonic sensor

- can provide an analog voltage or digital output voltage (switched output).
- can be used to monitor the level in a tank.
- can detect metallic and non-metallic objects.
- can detect solid and liquid targets at a distance of up to approximately 1m (3.3').
- can detect other objects that easily reflect sound waves.

Source:

[Electrical Motor Controls for Integrated Systems, 5th ed, G.J. Rockis, G.A. Mazur](#)

The inner workings of an Ultrasonic Sensor...



An ultrasonic sensor has two basic operating modes:

- Direct - operates like a direct scan photoelectric sensor.
- Diffused – operates like a scan diffused photoelectric sensor.

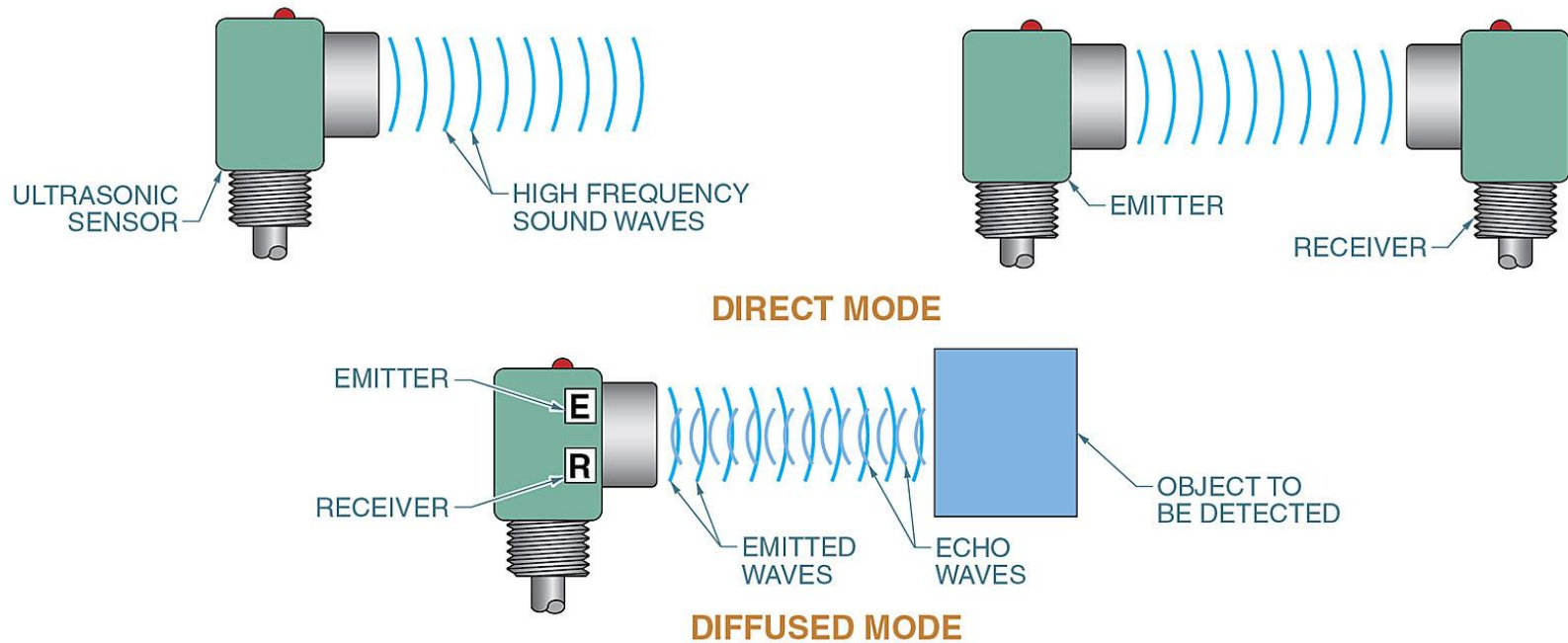
Source:

[Electrical Motor Controls for Integrated Systems, 5th ed, G.J. Rockis, G.A. Mazur](#)

The inner workings of an Ultrasonic Sensor...



ULTRASONIC SENSORS



Source:

[Electrical Motor Controls for Integrated Systems, 5th ed, G.J. Rockis, G.A. Mazur](#)

Presented by:

Question 3

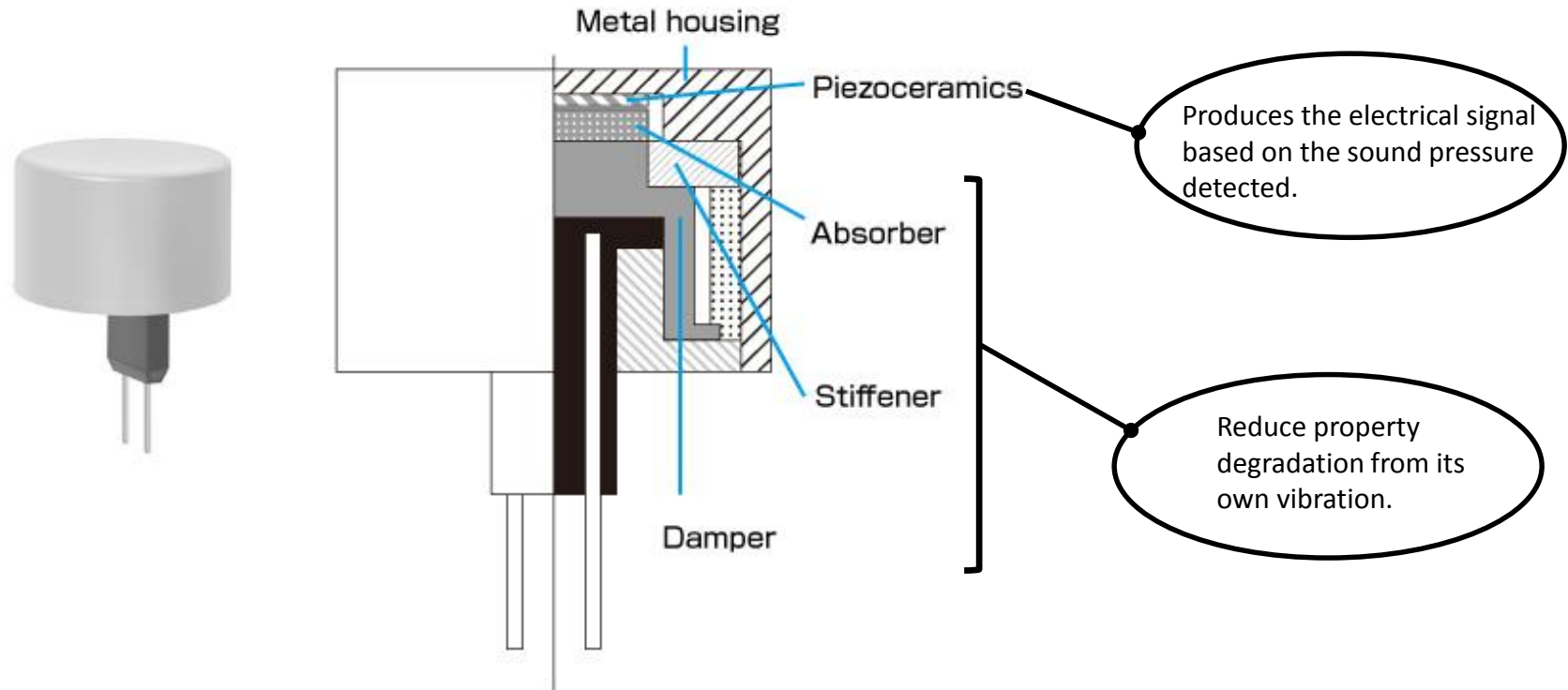
In a PIR Motion Sensor, the sensor is split in_____.

- a) 4 parts
- b) 3 parts
- c) 2 halves
- d) None of the above

The inner workings of an Ultrasonic Sensor...



Inside ultrasonic sensing element:



Source:

<http://www.murata.com/about/newsroom/techmag/metamorphosis17/productsmarket/ultrasonic>

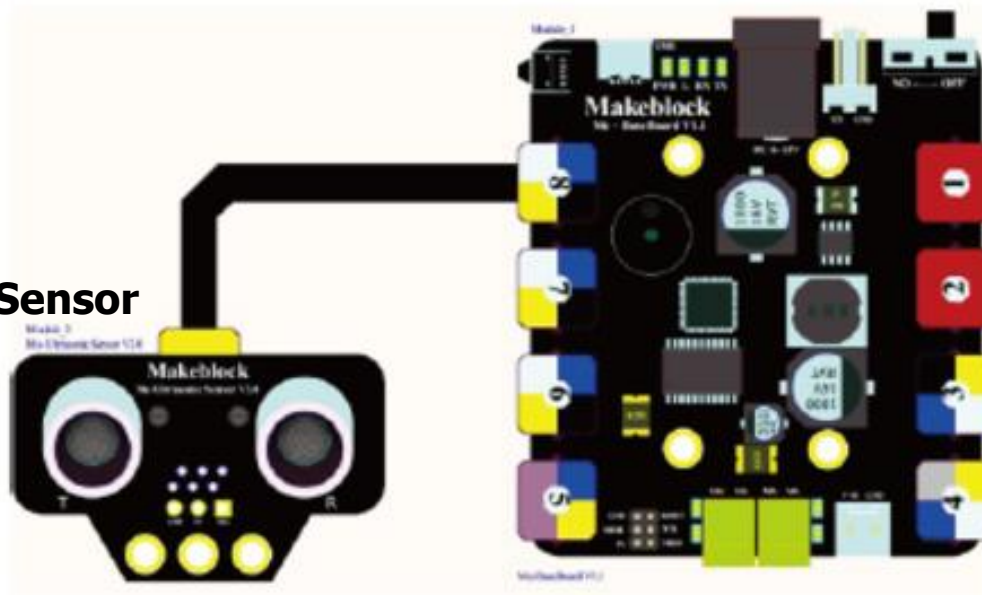
The inner workings of an Ultrasonic Sensor...



Testing a Me Ultrasonic Sensor:

Me Orion

Me Ultrasonic Sensor



Source:

<http://learn.makeblock.com/en/me-ultrasonic-sensor/>

The inner workings of an Ultrasonic Sensor...



Me Orion- Ultrasonic Sensor Test Code

```
#include "MeOrion.h"
#include <Wire.h>
#include <SoftwareSerial.h>

MeUltrasonicSensor ultraSensor(PORT_8);

void setup() {

    Serial.begin(9600);
}

void loop() {
    Serial.print("Distance :");
    Serial.print(ultraSensor.distanceCm());
    Serial.println(" cm");
    delay(100);
}
```

Source:

<http://learn.makeblock.com/en/me-ultrasonic-sensor/>

The inner workings of an Ultrasonic Sensor...

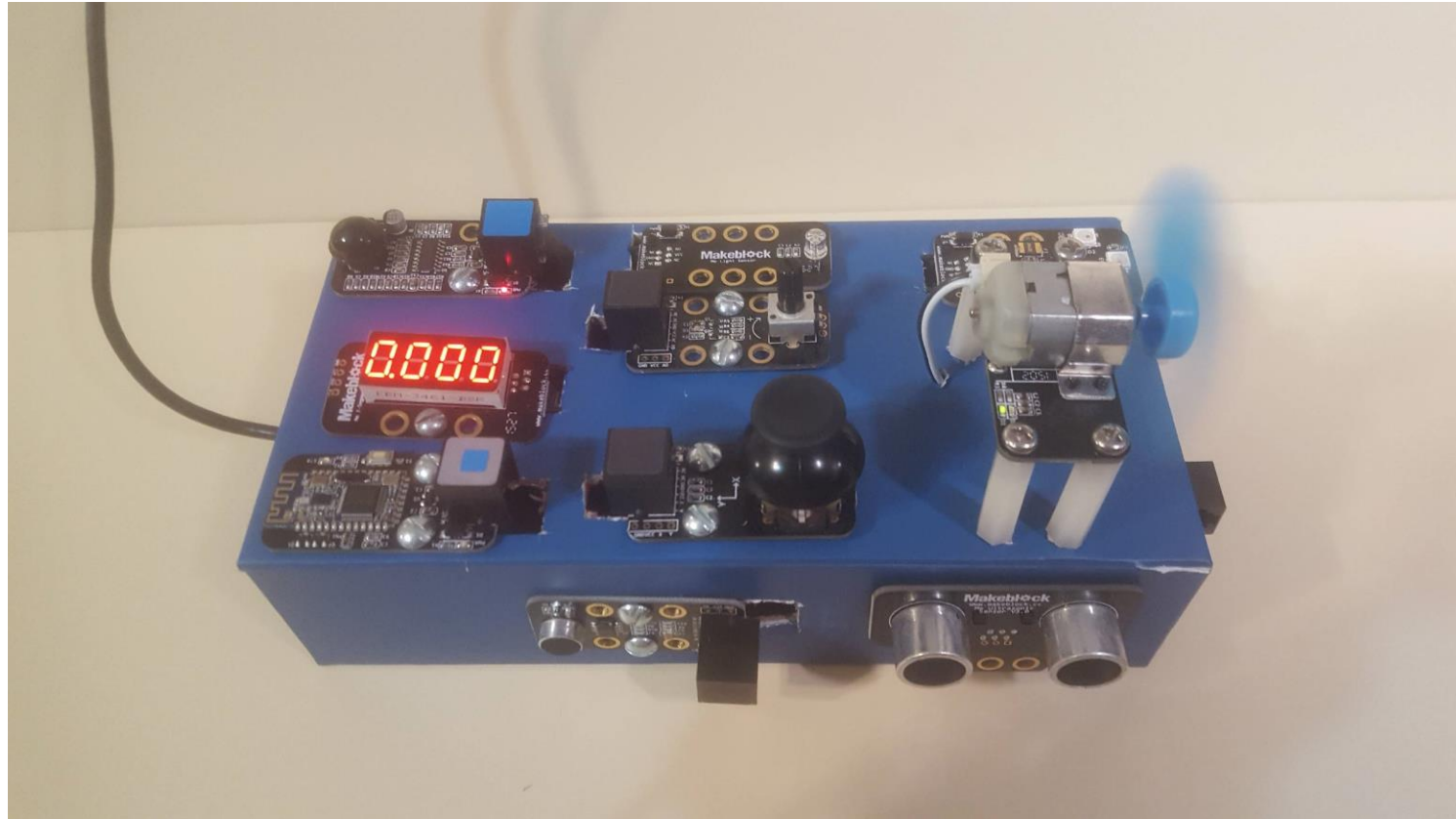


COM4

```
Distance :10.10 cm  
Distance :16.53 cm  
Distance :30.17 cm  
Distance :31.98 cm  
Distance :31.48 cm  
Distance :32.81 cm  
Distance :94.60 cm  
Distance :31.47 cm  
Distance :34.74 cm  
Distance :101.47 cm  
Distance :26.71 cm  
Distance :19.00 cm  
Distance :15.72 cm  
Distance :14.83 cm  
Distance :9.24 cm  
Distance :143.29 cm
```

Serial Monitor Output

Hands-On Project: Smart Fan



Hands-On Project: Smart Fan



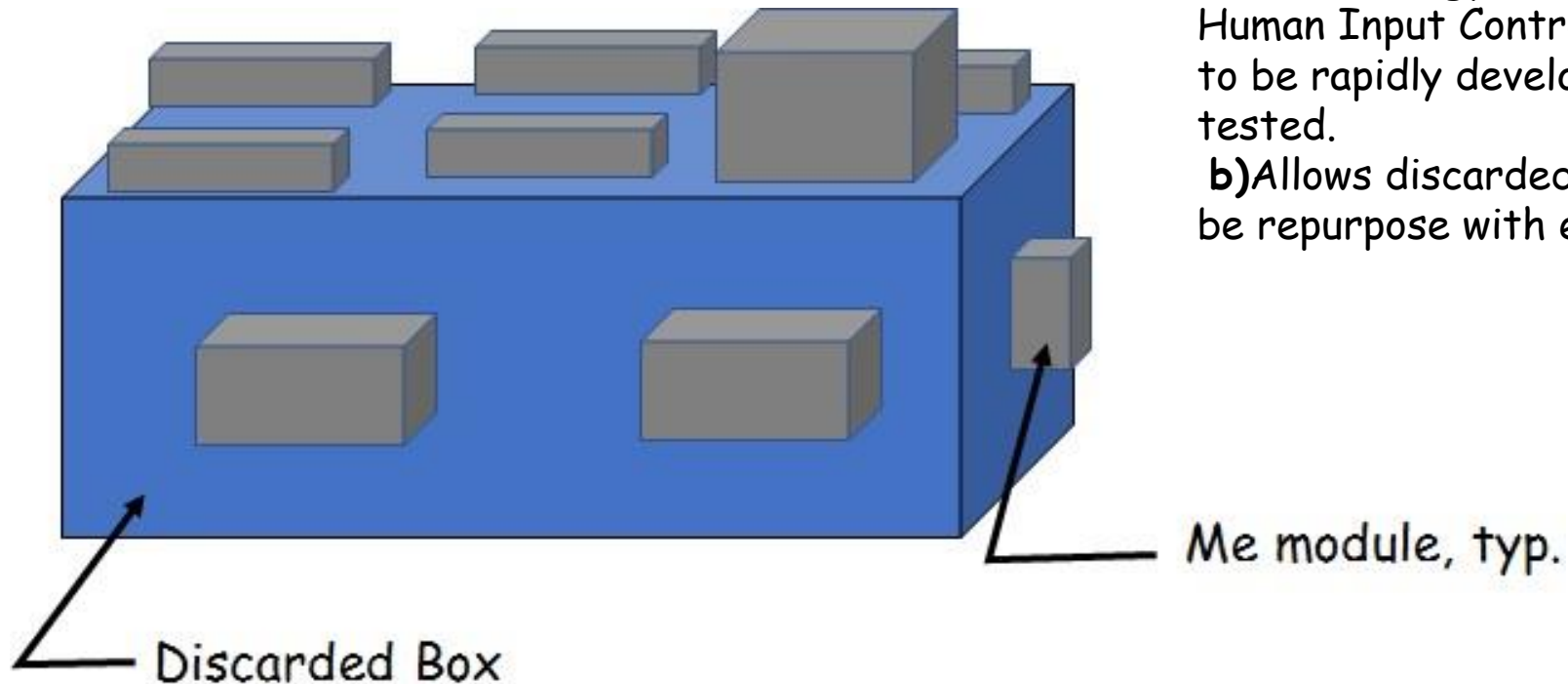
Project Objectives:

- a) Build a prototyping technology trainer for testing Human Inputting Devices concepts.
- b) Design a safety feature where placing your hand in front of a sensor will turn off a fan.
- c) Prototype semiconductor input controls that perform Design Feature b.

Hands-On Project: Smart Fan...



Human Inputting Device Technology Box: Concept Drawing



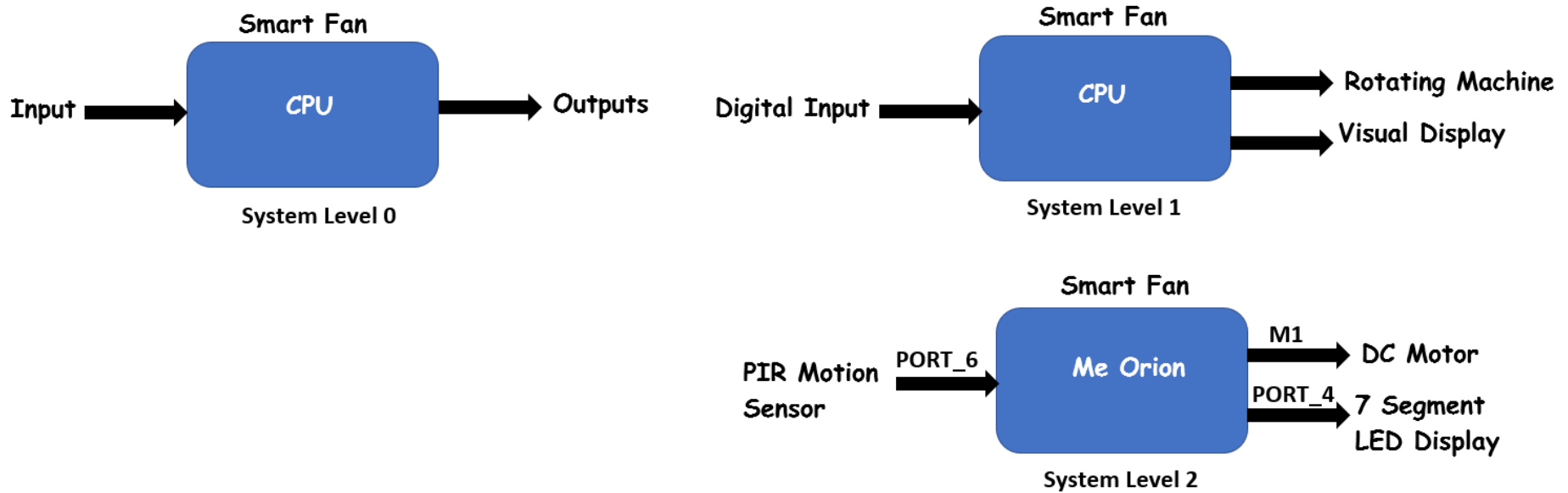
The BIG IDEAs:

- a) Technology Box allows Human Input Control Designs to be rapidly developed and tested.
- b) Allows discarded items to be repurpose with electronics.

Hands-On Project: Smart Fan



Smart Fan: System Block Diagram Designs For Safety Feature

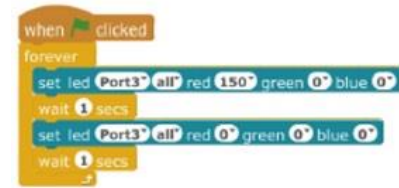


Question 4

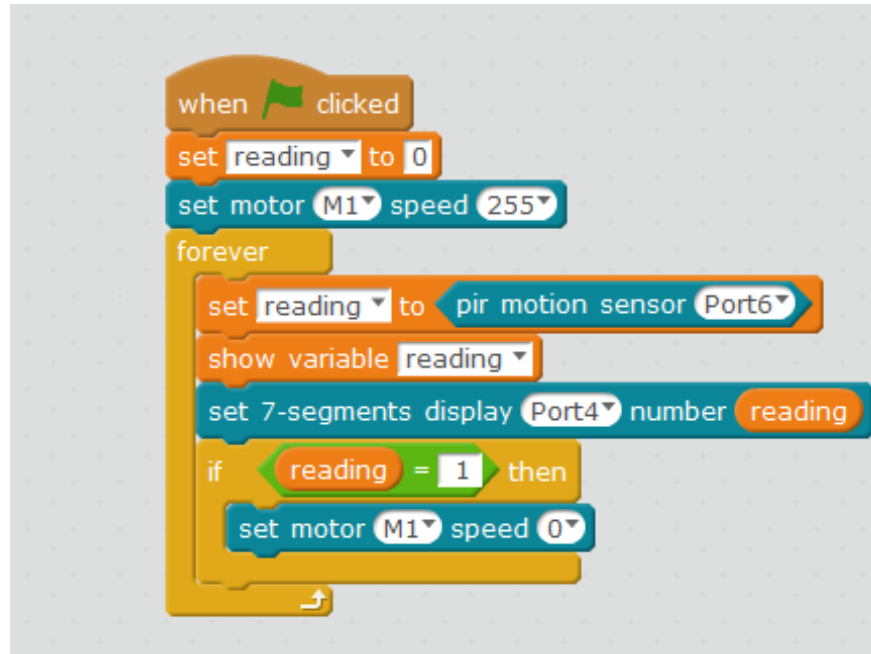
What System Level Block Diagram show the generic function of the Smart Fan?

- a) Level 0
- b) Level 1
- c) Level 2

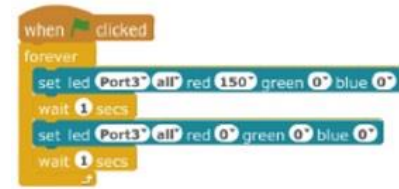
mBlock (VPL) Visual Programming Language...



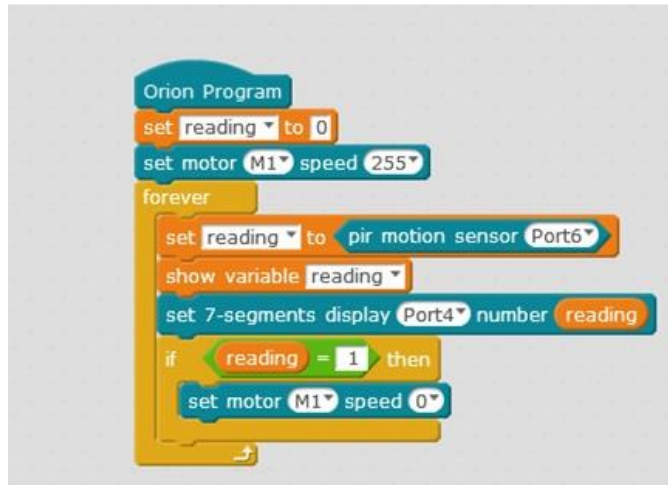
Project Code: PIR Motion Controlled Smart Fan



mBlock (VPL) Visual Programming Language with Arduino Code...



Project Code: PIR Motion Controlled Smart Fan



```
#include <Arduino.h>
#include <Wire.h>
#include <SoftwareSerial.h>

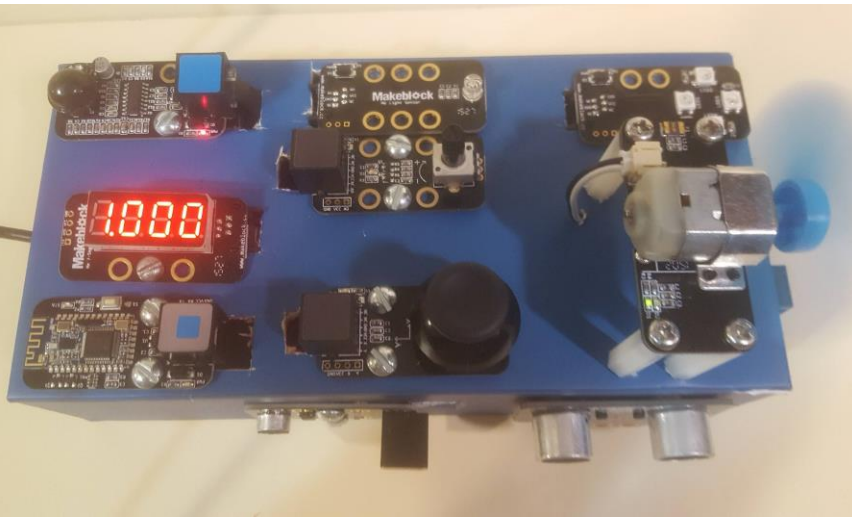
#include <MeOrion.h>

double angle_rad = PI/180.0;
double angle_deg = 180.0/PI;
double __var__98_111_111_108_32_114_101_97_100_105_110_103;
double reading;
MeDCMotor motor_9(9);
MePIRMotionSensor pir_6(6);
Me7SegmentDisplay seg7_4(4);

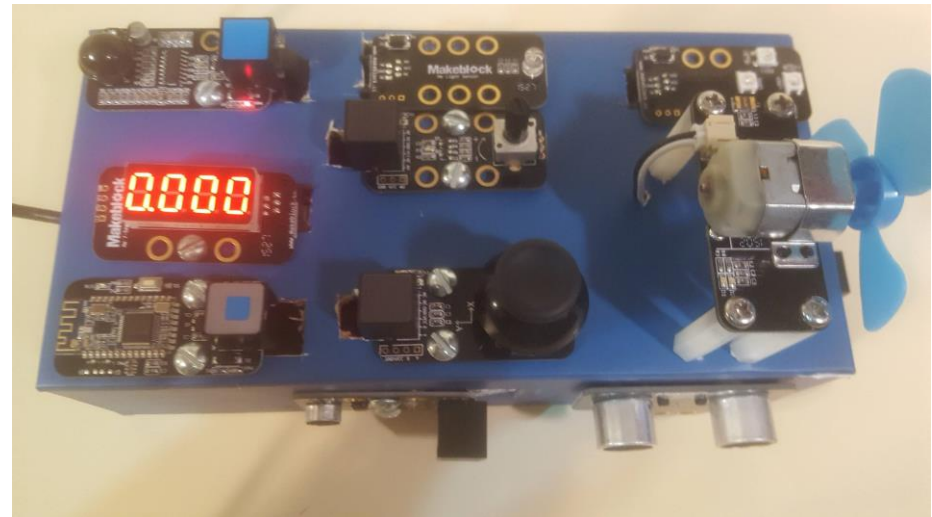
void setup(){
  __var__98_111_111_108_32_114_101_97_100_105_110_103 = 0;
  motor_9.run(255);
}

void loop(){
  reading = pir_6.isHumanDetected();
  seg7_4.display((float)reading);
  if(((reading)==( 1 ))){
    motor_9.run(0);
  }
  _loop();
}
```

Hands-On Project: Smart Fan



**Fan Running, object detected.
PIR Motion Sensor value = Binary 1**



**Fan Stop Running.
PIR Motion Sensor value = Binary 0**

Question 5

What logic function is being performed by the Smart Fan's safety feature?

- a) The AND Gate
- b) The OR Gate
- c) The NOT Gate
- d) None of the above